

$$g = 9.8 \text{ m/s}^2$$

$$G = 6.67 \times 10^{-11} \text{ N}\cdot\text{m}^2/\text{kg}^2$$

KINEMATICS: $\vec{v}(t) \equiv \frac{d}{dt}\vec{r}(t)$ $\vec{a}(t) \equiv \frac{d}{dt}\vec{v}(t)$ $|a_r| = \frac{v^2}{r}$ $\vec{v}_{P/S} = \vec{v}_{P/S'} + \vec{v}_{S'/S}$

PARTICLES: $F_G = G\frac{m_1m_2}{r^2}$ $\vec{F}_{2on1} = -\vec{F}_{1on2}$ $\Sigma\vec{F} = m\vec{a}$ $\int_{t_i}^{t_f} \Sigma\vec{F} dt = \Delta\vec{p}$

$$\Sigma W = \Delta K \qquad \Sigma\vec{\tau}_O = \frac{d}{dt}\vec{L}_O$$

SYSTEMS: $\vec{r}_{cm} \equiv (\Sigma_i m_i \vec{r}_i) / M_{sys}$ $\Sigma\vec{F}_{ext} = M_{sys}\vec{a}_{cm}$ $\int_{t_i}^{t_f} \Sigma\vec{F}_{ext} dt = \Delta\vec{p}_{sys}$

$$\Delta U_{sys} \equiv -W_C \qquad W_{NC} = \Delta E_{sys} \qquad \Sigma\vec{\tau}_{ext,O} = \frac{d}{dt}\vec{L}_{sys,O}$$

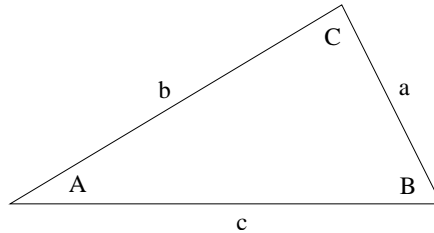
RIGID: $I_z \equiv \Sigma_i m_i r_{i \rightarrow z}^2$ $I_z = I_{cm} + M_{sys} R_{cm \rightarrow z}^2$ $K_{sys} = \frac{1}{2} I_{cm} \omega^2 + \frac{1}{2} M_{sys} v_{cm}^2$

$$\Sigma\tau_{ext,z} = I_z \alpha_z \qquad \vec{L}_{sys,O} = I_{cm} \vec{\omega} + \vec{r}_{O \rightarrow cm} \times \vec{p}_{sys}$$

QUADRATIC FORMULA: The solutions of $ax^2 + bx + c = 0$ are

$$\frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

TRIGONOMETRY:



$$\frac{\sin(A)}{a} = \frac{\sin(B)}{b} = \frac{\sin(C)}{c} \qquad c^2 = a^2 + b^2 - 2ab \cdot \cos(C)$$

DIFFERENTIAL EQUATIONS

$$x(t) = x_{max} \cos(\omega t + \phi) \quad \text{solves} \quad \frac{d^2}{dt^2}x(t) = -Cx(t) \quad \text{with} \quad \omega = \sqrt{C}$$

EXPANSIONS: $(1+x)^n = 1 + nx + \frac{n(n-1)x^2}{2!} + \dots$

$$\sin(\theta) = \theta - \frac{\theta^3}{3!} + \dots$$

$$\cos(\theta) = 1 - \frac{\theta^2}{2!} + \dots$$