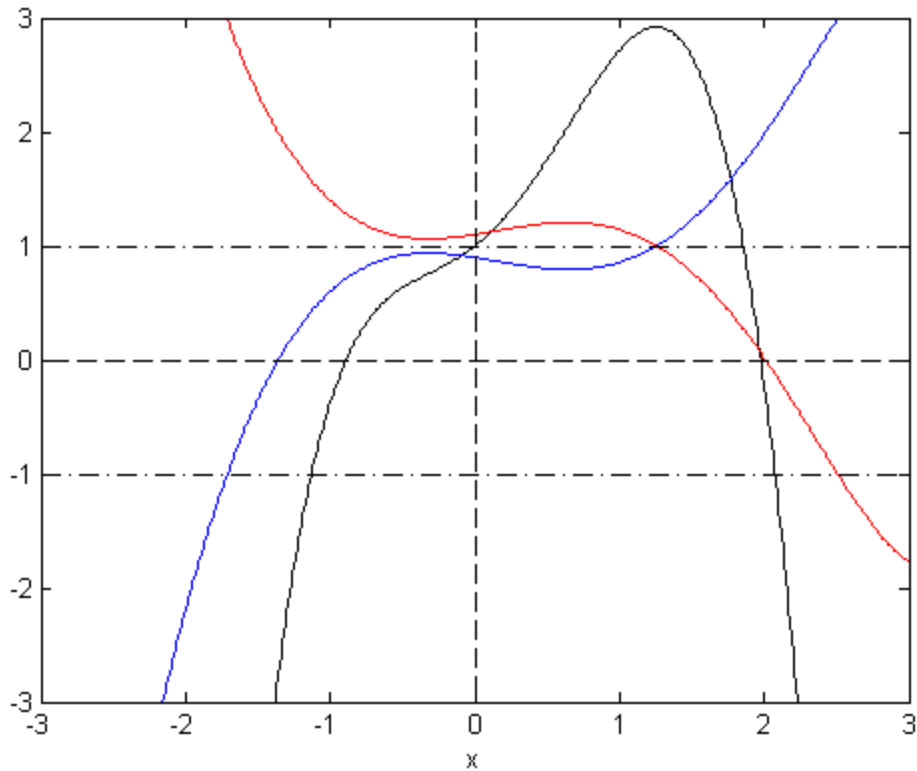


**Prob 1** Solution, Example 1 (prepared by HPH)

This example uses  $g_1(x) = x + 0.1(xe^x - x^4 + 0.1)$  and  $g_2(x) = x - 0.1(xe^x - x^4 + 0.1)$  for the positive and negative solutions, respectively. The factor of 0.1 helps us adjust the magnitude of  $g'(x)$  so as to bring it to within  $|g'(x)| < 1$  in the neighborhood of the desirable solution. The original function  $f(x)$  and the first derivative of  $g_1(x)$  and  $g_2(x)$  are shown in the following figure in black, red, and blue. The good interval for the initial guess for each solution can be readily inferred from the plot. We use  $x = 2$  and  $x = 0$  for the positive and negative solutions. from the plot. The matlab code is in next page. (The actual segment of the code for finding the solution is just a few lines.)



Positive solution is 1.976937

Negative solution is -0.892466

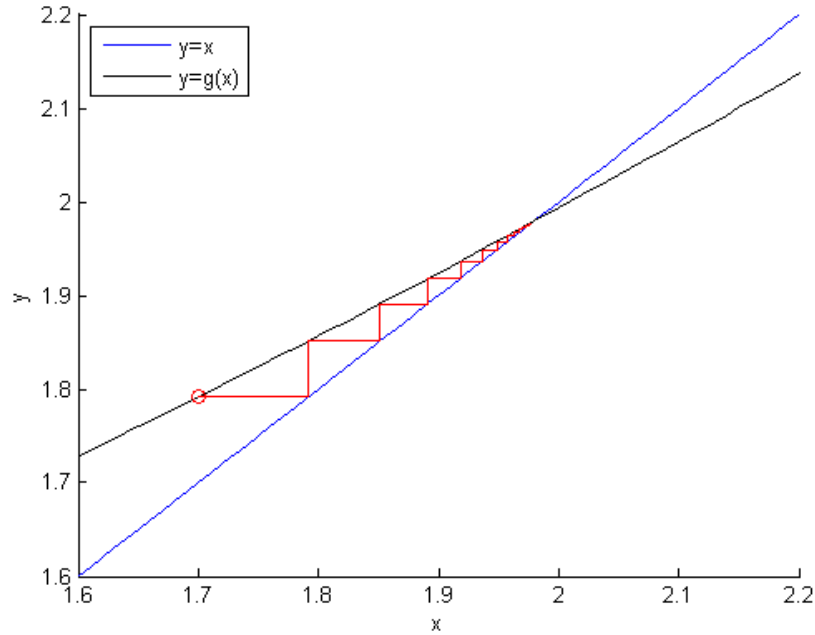
(Matlab code for Prob 1 Example 1)

```
x = [-3:0.01:3];
f = inline('x*exp(x)-x^4+1','x');
g1 = inline('x+0.1*x*exp(x)-0.1*(x^4)+0.1','x');
g2 = inline('x-0.1*x*exp(x)+0.1*(x^4)-0.1','x');
g1p = inline('1+0.1*exp(x)+0.1*x*exp(x)-0.4*(x^3)','x');
g2p = inline('1-0.1*exp(x)-0.1*x*exp(x)+0.4*(x^3)','x');
for k = 1:601
    p1(k) = f(x(k));
    p2(k) = g1p(x(k));
    p3(k) = g2p(x(k));
    z(k) = 0;
    zp1(k) = 1;
    zn1(k) = -1;
end
plot(x,p1,'-k',x,p2,'-r',x,p3,'-b',...
     x,z,'--k',x,zp1,'-.k',x,zn1,'-.k')
xlabel('x')
hold on; plot([0 0],[-3 3],'--k')
axis([-3 3 -3 3])
%
% positive sol (using g1)
%
xs = 2;
for iter = 1:50
    xs = g1(xs);
end
fprintf('Positive solution is %10.6f \r',xs)
%
% Negative sol (using g2)
%
xs = 0;
for iter = 1:50
    xs = g2(xs);
end
fprintf('Negative solution is %10.6f \r',xs)
```

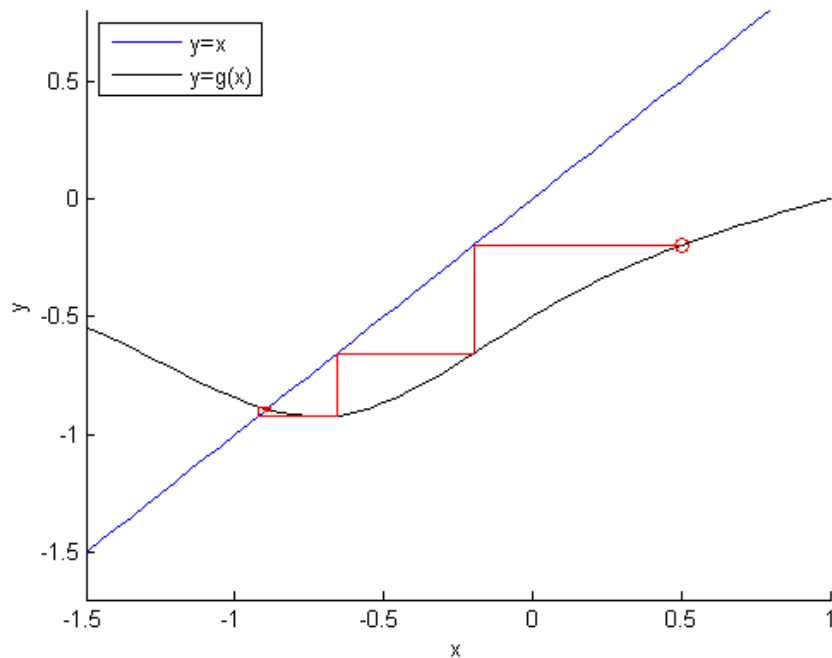
**Prob 1** Solution, Example 2

(This version is inspired by the work of Eduardo Perez and Lindsay Fleming. Thanks to both.)

This example demonstrates another way to visualize the process of convergence. Here,  $g_1(x)=(x e^x + 1)^{1/4}$  (initial guess = 1.7) and  $g_2(x)=(x - 1)/(e^x - x^3 + 1)$  (initial guess = 0.5) are chosen for the positive and negative solutions. The following figures (top for the positive solution, bottom for the negative solution) show the two curves of  $y = x$  and  $y = g(x)$  whose intersection is the solution. The red segments indicate the progress of the iterative process (starting from the initial guess as the red circle), in the same fashion as Fig. 3-18 in the textbook. The matlab code for the negative solution (bottom) is in next page.



Solution is 1.9768 after 19 iterations



Solution is -0.8924 after 9 iterations

(Matlab code for Prob 1 Example 2)

```
x = [-1.5:0.05:1];
g = inline('(x-1)/(exp(x)-x^3+1)', 'x');
for k = 1:51
    gplot(k) = g(x(k));
end
hold on
plot(x,x,'b-',x,gplot,'k-','LineWidth',1.3)
xlabel('x');ylabel('y');
legend('y=x','y=g(x)','Location','NorthWest')
axis([-1.5 1 -1.7 0.8]);
x0 = 0.5;
x1 = g(x0);
plot([x0 x1],[x1 x1],'r-','LineWidth',1.3)
plot(x0,x1,'o','MarkerEdgeColor','r')
ktot = 0
while (abs(x1-x0) > 0.0001)
    ktot = ktot+1
    x0 = x1;
    x1 = g(x0);
    plot([x0 x0],[x0 x1],'r-','LineWidth',1.3)
    plot([x0 x1],[x1 x1],'r-','LineWidth',1.3)
end
hold off
fprintf('Solution is %9.4f after %4u iterations \r',x1,ktot)
```

**Prob 1** Further notes

Most people got the positive solution right. What's causing trouble is the negative solution. The following table summarizes the different forms of  $g(x)$ 's you have chosen that work for the *negative* solution. The number in the second column indicates the number of students who chose the particular form of  $g(x)$ . There would be some deduction if a correct pick of  $g(x)$  is accompanied by a wrong initial guess, or if an initial guess is not specified. An incorrect (improbable) pick of  $g(x)$  that "leads to the right solution" would receive no credit.

$g(x)$	# of students	Remarks
$-(x e^x + 1)^{1/4}$	27	Note that $(x e^x + 1)^{1/4}$ and $-(x e^x + 1)^{1/4}$ are two distinctive choices of $g(x)$ . The former works for the positive solution while the latter works for the negative solution. Some students claimed that the former works for both (by arbitrarily inserting a negative sign in the iterative process). This would lead to a deduction.
$x + A(e^x - x^3 + 1/x)$ or $x + A(x e^x - x^4 + 1)$ , where $A$ is a small negative number	16	See instructor's solution which uses $A = -0.1$ .
$\frac{x-1}{e^x - x^3 + 1}$	7	An interesting choice. See if you can figure out how to obtain this form of $g(x)$ .
$x \cos(x e^x - x^4 + 1)$	4	It works, but convergence is painfully slow in this case. For example, using $x = -1$ as the initial guess, it takes over 2000 iterations to reach within 0.0001 of the true solution.
$x \left( \frac{x e^x + 1}{x^4} \right)^{1/100}$	2	Convergence is somewhat slow in this case; Needs about 200 iterations to reach a reasonably accurate result starting from the initial guess of $x = -1$ .
$(e^x + 1/x)^{1/3}$	2	While this is a valid pick, it could be somewhat tricky to implement the calculation in matlab (or using a regular calculator) due to the $1/3$ power and the fact that the number in the parentheses is negative. You might need to use a special function ("nthroot" in matlab) to take the root or matlab would return a complex number (which is a valid root but not what we want).
$(x^2 e^x + x)^{1/5}$	2	See above remark.
$\left( \frac{-1}{x^{-2} e^x - x} \right)^{1/3}$	1	See above remark.
$x^5(x e^x - x^4 + 1 + 1/x^4)$	1	
Other choices that did not lead to convergence to the negative solution	31	

**Prob 2 Solution** (Thanks to Nicholas Ramseyer)

(a) The result of Gauss elimination is  $(x_1, x_2, x_3) = (1, 2, 0.5)$

Matlab code for (b)-(d):

```
% JACOBI ITERATION METHOD
K = 0;
X1 = 0;
X2 = 0;
X3 = 0;

fprintf('Below are the solutions for Jacobi Iteration Mehtod')
disp(' ')
disp(' ')
for K = 1:15
    N = K;
    Y1 = X1;
    Y2 = X2;
    Y3 = X3;
    X1 = (9 - 1*Y2 - 2*Y3)/6;
    X2 = (13 - 2*Y1 - 2*Y3)/5;
    X3 = (6 - 1*Y1 - 1*Y2)/6;

    R1 = (6*(X1)+ 1*(X2)+ 2*(X3)) - 9;
    R2 = (2*(X1)+ 5*(X2)+ 2*(X3)) - 13;
    R3 = (1*(X1)+ 1*(X2)+ 6*(X3)) - 6;

    E = ((R1^2 + R2^2 + R3^2)^(1/2));
    E1(K) = E;
    fprintf('%g E = %f X1 = %5f , X2 = %5f , X3 = %5f \r',N+1,E,X1,X2,X3)
end

disp(' ')
disp(' ')
fprintf('Below are the solutions for Gauss Seidel Method')
disp(' ')
disp(' ')
% GAUSS SEIDEL ITERATION
k = 0;
x1 = 0;
x2 = 0;
x3 = 0;

for k = 1:15
    I = k;
    x1 = (9 - 1*x2 - 2*x3)/6;
    x2 = (13 - 2*x1 - 2*x3)/5;
    x3 = (6 - 1*x1 - 1*x2)/6;
```

Jacobi

Gauss Seidel

(Matlab code continues to next page)

(Prob 2, Matlab code continued)

```
R1 = (6*(x1)+ 1*(x2)+ 2*(x3)) - 9;
R2 = (2*(X1)+ 5*(X2)+ 2*(x3)) - 13;
R3 = (1*(X1)+ 1*(x2)+ 6*(x3)) - 6;

e = ((R1^2 + R2^2 + R3^2)^(1/2));
E2(k) = e;
fprintf('%g E = %f  x1 = %5f , x2 = %5f , x3 = %5f \r',I+1,e,x1,x2,x3)
end

n = 1:15;

plot(n,E1,'Color',[1 0 0])
hold on
plot(n,E2)
xlabel('Iterations','FontSize',12)
ylabel('Values of percent error','FontSize',12)
title('Jacobi vs. Gauss Seidel Plot','FontSize',14)
legend('Jacobi','Gauss Seidel')
```

(Prob 2 continued)

Below are the solutions for Jacobi Iteration Method

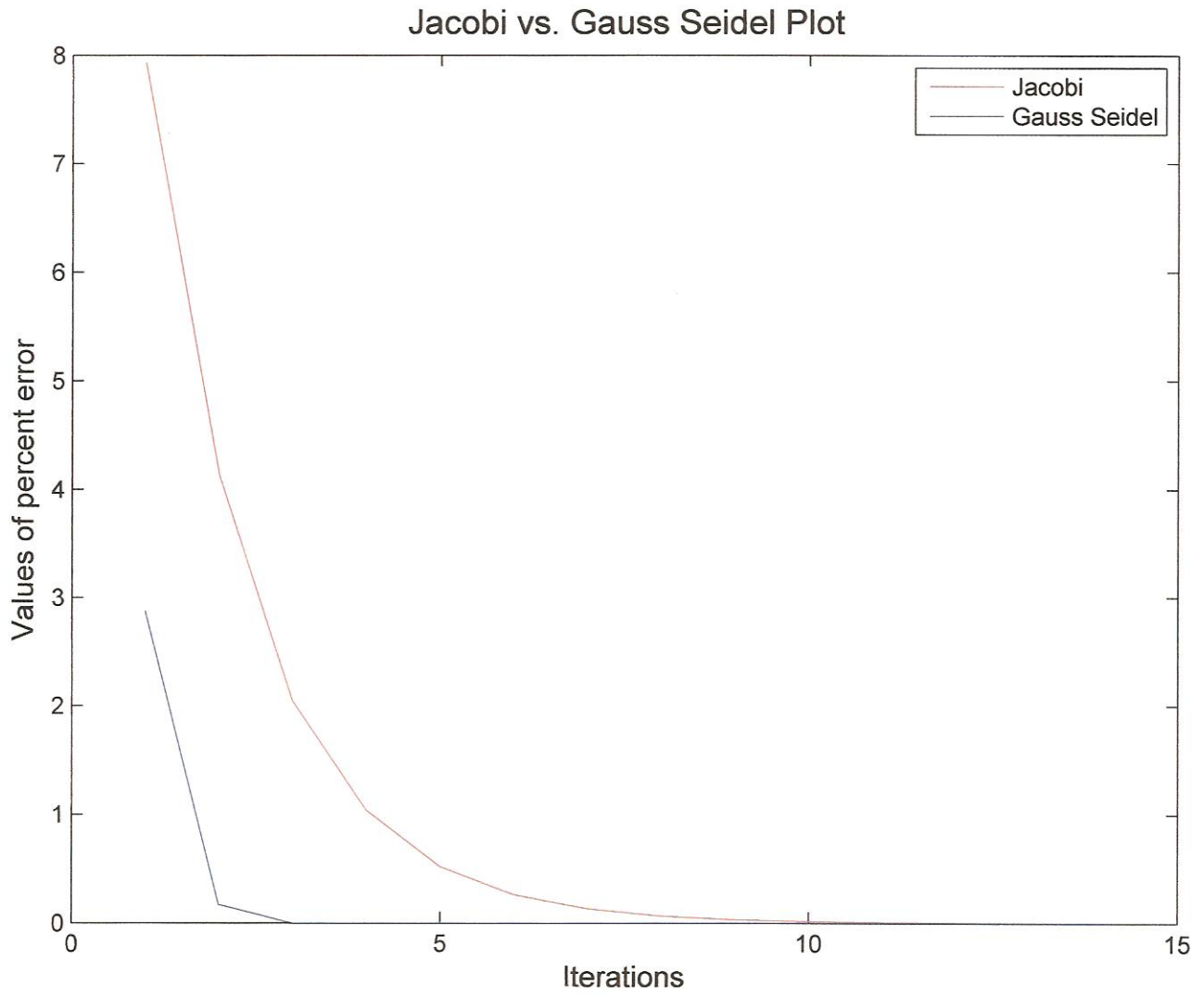
2 E = 7.935364 X1 = 1.500000 , X2 = 2.600000 , X3 = 1.000000  
3 E = 4.139109 X1 = 0.733333 , X2 = 1.600000 , X3 = 0.316667  
4 E = 2.052831 X1 = 1.127778 , X2 = 2.180000 , X3 = 0.611111  
5 E = 1.045047 X1 = 0.932963 , X2 = 1.904444 , X3 = 0.448704  
6 E = 0.525566 X1 = 1.033025 , X2 = 2.047333 , X3 = 0.527099  
7 E = 0.265806 X1 = 0.983078 , X2 = 1.975951 , X3 = 0.486607  
8 E = 0.134106 X1 = 1.008473 , X2 = 2.012126 , X3 = 0.506829  
9 E = 0.067726 X1 = 0.995703 , X2 = 1.993880 , X3 = 0.496567  
10 E = 0.034191 X1 = 1.002164 , X2 = 2.003092 , X3 = 0.501736  
11 E = 0.017263 X1 = 0.998906 , X2 = 1.998440 , X3 = 0.499124  
12 E = 0.008716 X1 = 1.000552 , X2 = 2.000788 , X3 = 0.500442  
13 E = 0.004400 X1 = 0.999721 , X2 = 1.999602 , X3 = 0.499777  
14 E = 0.002222 X1 = 1.000141 , X2 = 2.000201 , X3 = 0.500113  
15 E = 0.001122 X1 = 0.999929 , X2 = 1.999899 , X3 = 0.499943  
16 E = 0.000566 X1 = 1.000036 , X2 = 2.000051 , X3 = 0.500029  
17 E = 0.000286 X1 = 0.999982 , X2 = 1.999974 , X3 = 0.499985  
18 E = 0.000144 X1 = 1.000009 , X2 = 2.000013 , X3 = 0.500007  
19 E = 0.000073 X1 = 0.999995 , X2 = 1.999993 , X3 = 0.499996  
20 E = 0.000037 X1 = 1.000002 , X2 = 2.000003 , X3 = 0.500002  
21 E = 0.000019 X1 = 0.999999 , X2 = 1.999998 , X3 = 0.499999  
22 E = 0.000009 X1 = 1.000001 , X2 = 2.000001 , X3 = 0.500000  
23 E = 0.000005 X1 = 1.000000 , X2 = 2.000000 , X3 = 0.500000  
24 E = 0.000002 X1 = 1.000000 , X2 = 2.000000 , X3 = 0.500000  
25 E = 0.000001 X1 = 1.000000 , X2 = 2.000000 , X3 = 0.500000  
26 E = 0.000001 X1 = 1.000000 , X2 = 2.000000 , X3 = 0.500000  
27 E = 0.000000 X1 = 1.000000 , X2 = 2.000000 , X3 = 0.500000  
28 E = 0.000000 X1 = 1.000000 , X2 = 2.000000 , X3 = 0.500000

Below are the solutions for Gauss Seidel Method

2 E = 2.881936 x1 = 1.500000 , x2 = 2.000000 , x3 = 0.416667  
3 E = 0.175242 x1 = 1.027778 , x2 = 2.022222 , x3 = 0.491667  
4 E = 0.003071 x1 = 0.999074 , x2 = 2.003704 , x3 = 0.499537  
5 E = 0.002421 x1 = 0.999537 , x2 = 2.000370 , x3 = 0.500015  
6 E = 0.000372 x1 = 0.999933 , x2 = 2.000021 , x3 = 0.500008  
7 E = 0.000035 x1 = 0.999994 , x2 = 1.999999 , x3 = 0.500001  
8 E = 0.000002 x1 = 1.000000 , x2 = 2.000000 , x3 = 0.500000  
9 E = 0.000000 x1 = 1.000000 , x2 = 2.000000 , x3 = 0.500000  
10 E = 0.000000 x1 = 1.000000 , x2 = 2.000000 , x3 = 0.500000  
11 E = 0.000000 x1 = 1.000000 , x2 = 2.000000 , x3 = 0.500000  
12 E = 0.000000 x1 = 1.000000 , x2 = 2.000000 , x3 = 0.500000  
13 E = 0.000000 x1 = 1.000000 , x2 = 2.000000 , x3 = 0.500000  
14 E = 0.000000 x1 = 1.000000 , x2 = 2.000000 , x3 = 0.500000  
15 E = 0.000000 x1 = 1.000000 , x2 = 2.000000 , x3 = 0.500000  
16 E = 0.000000 x1 = 1.000000 , x2 = 2.000000 , x3 = 0.500000  
17 E = 0.000000 x1 = 1.000000 , x2 = 2.000000 , x3 = 0.500000  
18 E = 0.000000 x1 = 1.000000 , x2 = 2.000000 , x3 = 0.500000  
19 E = 0.000000 x1 = 1.000000 , x2 = 2.000000 , x3 = 0.500000  
20 E = 0.000000 x1 = 1.000000 , x2 = 2.000000 , x3 = 0.500000  
21 E = 0.000000 x1 = 1.000000 , x2 = 2.000000 , x3 = 0.500000



(Prob 2 continued)



(Prob 2 continued - Part (e))

```
clear all
close all
clc

A = [6,1,2;2,5,2;1,1,6];

% A(Row,Column)

B = ((A(1,1)^2) + (A(1,2)^2) + (A(1,3)^2)...
     + (A(2,1)^2) + (A(2,2)^2) + (A(2,3)^2)...
     + (A(3,1)^2) + (A(3,2)^2) + (A(3,3)^2))^(1/2);

fprintf('Value of Norm for A is %g',B)
disp(' ')
disp(' ')
C = inv(A);

D = ((C(1,1)^2) + (C(1,2)^2) + (C(1,3)^2)...
     + (C(2,1)^2) + (C(2,2)^2) + (C(2,3)^2)...
     + (C(3,1)^2) + (C(3,2)^2) + (C(3,3)^2))^(1/2);

fprintf('norm of inverse = %g',D)
disp(' ')
disp(' ')
E = B*D;

fprintf('Condition number is equal to %g',E)
disp(' ')
```

The condition number is 3.8147. The system is not ill-conditioned.