

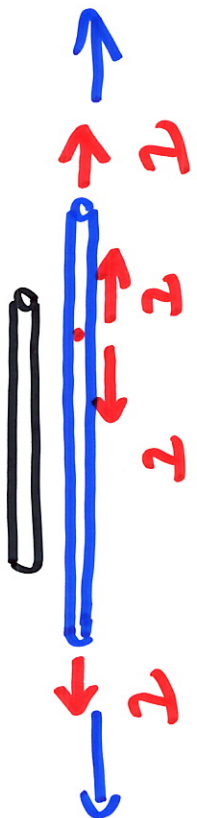
1-D Wave Eq. "Hyperbolic"

vibration of a "1-D string" (thin)

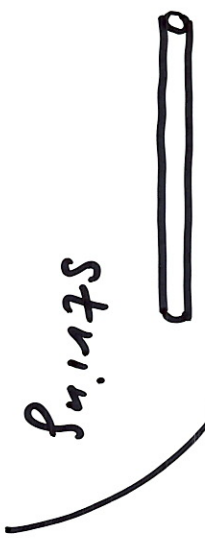


Lecture 1-14
Scope of midterm

"tension" μ



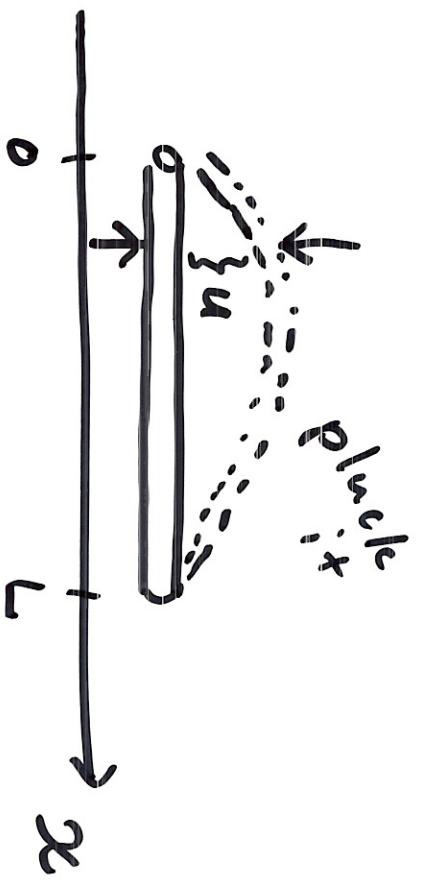
neutral configuration



force unit per area

A : x-sectional area

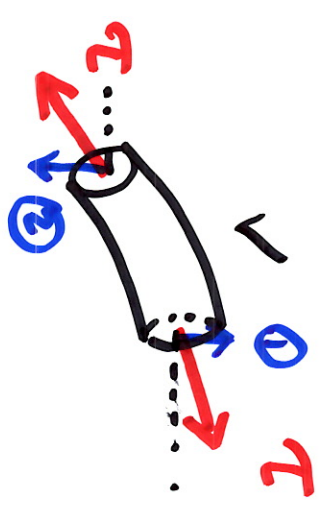
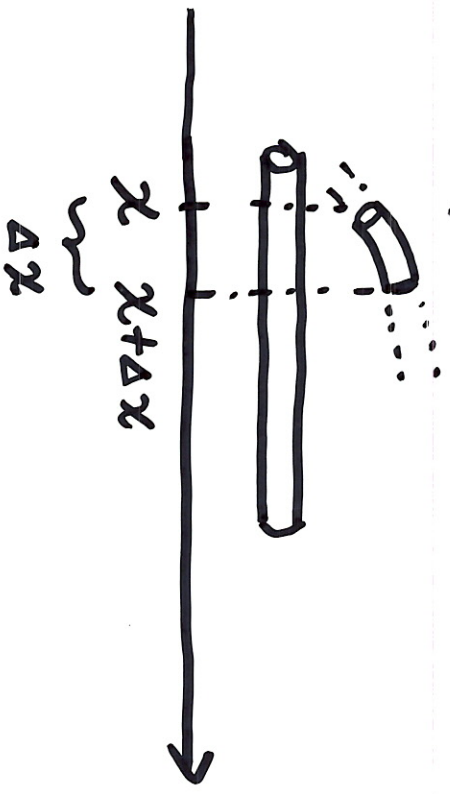
$T \cdot A = \text{force}$



u : displacement

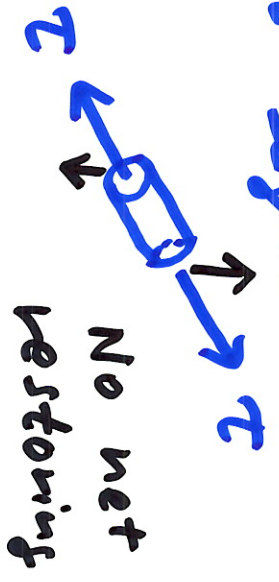
$u(x, t)$

balance of force on the small segment

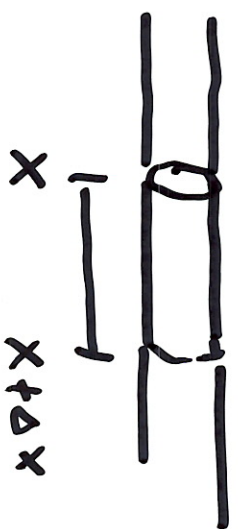


$|\textcircled{2}| > |\textcircled{1}|$

"straight" segment



No net restoring force !!



$$\tau \sin \theta(x+\Delta x, t)$$

u is displacement
in y dir



(in y dir)
Newton's Law \rightarrow

$$F = m \cdot a$$

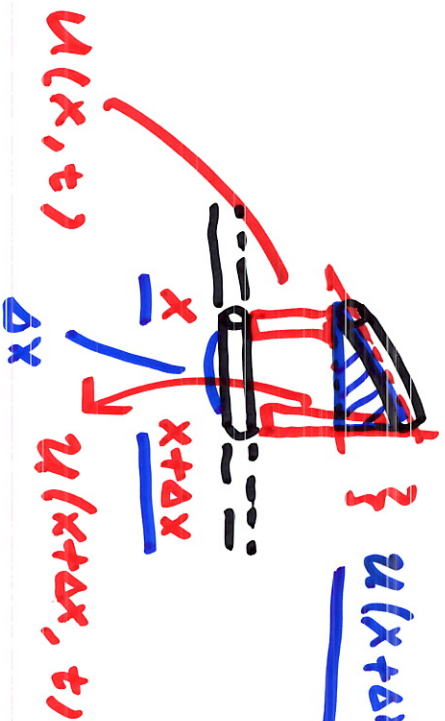
density ρ
 $\tau \sin \theta(x, t)$

$$\cancel{A} \cdot \tau [\sin \theta(x+\Delta x, t) - \sin \theta(x, t)]$$

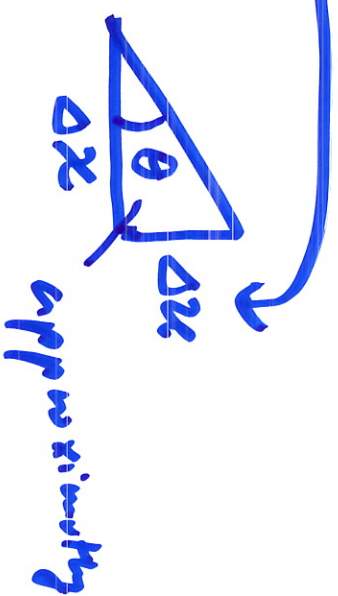
$$A: \text{X-sec area} = \rho \cdot \cancel{A} \cdot \Delta x \frac{\partial^2 u}{\partial t^2}$$

$$\Rightarrow \frac{\partial^2 u}{\partial t^2} = \frac{\tau}{\rho} \frac{\sin \theta(x+\Delta x, t) - \sin \theta(x, t)}{\Delta x} \quad (*)$$

Small perturbation ($\theta \ll 1$)



$$u(x+\Delta x, t) - u(x, t)$$



$$\frac{\Delta u}{\Delta x} \approx \tan \theta$$

$$\Delta x \rightarrow 0 \quad \frac{\partial u}{\partial x} \approx \tan \theta$$

If θ is small

$$\Rightarrow \tan \theta \sim \theta \sim \sin \theta$$

$$\tan \theta = \frac{\sin \theta}{\cos \theta} \approx \theta$$

small θ

$$\Rightarrow \frac{\partial u}{\partial x} \sim \sin \theta$$

$$\sin \theta = \theta - \frac{\theta^3}{3!} + \frac{\theta^5}{5!} - \frac{\theta^7}{7!} + \dots$$

$\sin \theta \approx \theta$ for small θ

$$\cos \theta = 1 - \frac{\theta^2}{2!} + \frac{\theta^4}{4!} - \frac{\theta^6}{6!} + \dots$$

$$\cos \theta \approx 1$$

~~(*)~~ (**)

plug (***) back to (*)

$$\Rightarrow \frac{\partial^2 u}{\partial t^2} = \frac{T}{\rho} \left[\frac{\partial u}{\partial x} \Big|_{x+\Delta x, t} - \frac{\partial u}{\partial x} \Big|_{x, t} \right] \Delta x$$

$$\lim_{\Delta x \rightarrow 0}$$

$$\frac{\partial^2 u}{\partial t^2} = \frac{T}{\rho} \frac{\partial^2 u}{\partial x^2}$$

1-D wave eq.

$$\frac{\partial^2 u}{\partial t^2} = C^2 \frac{\partial^2 u}{\partial x^2}$$

Given
Positive
const

$$\frac{T}{\rho} > 0$$

Let's call it

$$C^2 \equiv \frac{T}{\rho}$$

$$C \equiv \sqrt{\frac{T}{\rho}}$$

Rescale ...

$$\frac{\partial^2 u}{\partial t^2} = \frac{\partial^2 u}{\partial x^2}$$

$u(x, t)$

1-D wave

Compare

w/ Laplace's eq.

sep of var $u \sim G(x)H(t)$

$$G'' = cG \quad \begin{matrix} \sin \\ \cos \end{matrix}$$

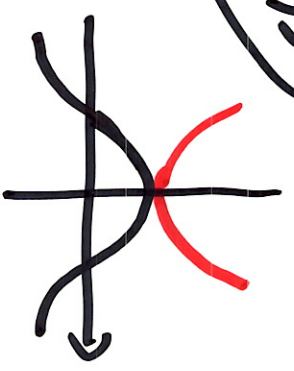
$$\dot{H} = cH \quad \begin{matrix} \sin \\ \cos \end{matrix}$$

$u(x, y)$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0 \implies$$

$$-\frac{\partial^2 u}{\partial y^2} = \frac{\partial^2 u}{\partial x^2}$$

sep of var
 $u \sim G(x)H(y)$



$$G(x) \sim \begin{matrix} \sin \\ \cos \end{matrix}$$

$$G'' = cG$$

$$\implies H(y) \sim \begin{matrix} \sinh \\ \cosh \end{matrix}$$

$$\dot{H} = -cH$$

Boundary condition Hypersbolic type

$$\checkmark \quad \frac{\partial^2 u}{\partial t^2} = \frac{\partial^2 u}{\partial x^2} \quad \text{--- (*)}$$

(I) $u(0, t) = 0$

(II) $u(1, t) = 0$

(III) $u(x, 0) = P(x)$ initial displacement

(IV) $u_t(x, 0) = Q(x)$ "velocity"



Newton's 2nd Law



$$\frac{d^2 \vec{r}}{dt^2} = \frac{\vec{F}}{m}$$

$$\frac{\vec{r}(0)}{\#} = \square \quad \frac{\dot{\vec{r}}(0)}{\#} = \square$$

sketch of sol. (Nothing new)

sep of var on (I), (II), (III) in the technique
 $u \sim G(x)H(t)$ for solution)

$$\Rightarrow \begin{cases} G'' = cG & G(0) = 0 & G(L) = 0 \end{cases}$$

$$\begin{cases} \dot{H} = cH \\ \downarrow \text{(Lec 4, 5,)} \end{cases}$$

$c_n = -(n\pi)^2 \quad n=1, 2, \dots$

$$\ddot{H}_n = -(n\pi)^2 H_n \quad G_n(x) = \sin(n\pi x)$$

$$H_n(t) = A_n \cos(n\pi t) + B_n \sin(n\pi t)$$

$$u_n(x, t) = G_n(x)H_n(t) \quad \begin{matrix} \rightarrow A_n \\ \rightarrow B_n \end{matrix}$$

Full sol:

$$u(x, t) = \sum_{n=1}^{\infty} a_n u_n(x, t) \quad \begin{matrix} a_n A_n \rightarrow A_n \\ a_n B_n \rightarrow B_n \end{matrix}$$

$$= \sum_{n=1}^{\infty} [A_n \cos(n\pi t) + B_n \sin(n\pi t)] \sin(n\pi x)$$

Use b.c. (III), (IV) to fix $\{A_n\}, \{B_n\}$