

Using MOC to solve higher-order PDE

Old ideas for ODE higher-order

$$u(x)$$

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ODE

$$u'''' + 7u''' + xu'' + \sin(x) = 0$$

$$\begin{aligned} u(0) &= A \\ u'(0) &= B \\ u''(0) &= C \\ u'''(0) &= D \end{aligned}$$

$$\begin{cases} P' = -7P - xW - \sin(x) \\ W' = P \\ V' = W \\ U' = V \end{cases}$$

$$\begin{aligned} u(0) &= A \\ v(0) &= B \\ w(0) &= C \\ p(0) &= D \end{aligned}$$

split into multiple first-order PDEs

Let $V \equiv u'$
 $W \equiv u''$ ($= V'$)
 $P \equiv u'''$ ($= W'$)
 ~~$Q \equiv u''''$ ($= P'$)~~

PDE :

EX: 1-D Wave eq. $u(x, t)$

$$\frac{\partial^2 u}{\partial t^2} = \frac{\partial^2 u}{\partial x^2}$$

2-nd order PDE

(Not of MOC form)

$$\mathcal{L} \left(\frac{\partial^2}{\partial t^2} - \frac{\partial^2}{\partial x^2} \right) u = 0$$

$$\mathcal{L} u = 0$$

2 ways

(i) $\left(\frac{\partial}{\partial t} - \frac{\partial}{\partial x} \right) \left(\frac{\partial}{\partial t} + \frac{\partial}{\partial x} \right) u = 0$

$\mathcal{L}_1, \mathcal{L}_2$
 $\underline{\text{1st}}$ 1st
 order order

$$\left\{ \begin{array}{l} \frac{\partial w}{\partial t} - \frac{\partial w}{\partial x} = 0 \\ \frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} = w \end{array} \right.$$

-MOC ✓
 -MOC ✓

alternative

(ii) $(\frac{\partial}{\partial t} + \frac{\partial}{\partial x}) (\underbrace{\frac{\partial}{\partial t} - \frac{\partial}{\partial x}}_w) u = 0$ will also work (in principle)

$$\left\{ \begin{aligned} \frac{\partial w}{\partial t} + \frac{\partial w}{\partial x} &= 0 \\ \frac{\partial u}{\partial t} - \frac{\partial u}{\partial x} &= w \end{aligned} \right.$$

Sometimes, one way of decomposition works better than the other(s)

Ex:

$$u(x, t) \quad \frac{\partial^2 u}{\partial t^2} - \frac{\partial^2 u}{\partial x^2} = \frac{\partial u}{\partial t} - \frac{\partial u}{\partial x} + x$$

(ii) better $\Rightarrow (\frac{\partial}{\partial t} + \frac{\partial}{\partial x}) (\underbrace{\frac{\partial}{\partial t} - \frac{\partial}{\partial x}}_w) u = (\underbrace{\frac{\partial u}{\partial t} - \frac{\partial u}{\partial x}}_w) + x$

$$\left[\begin{aligned} \frac{\partial w}{\partial t} + \frac{\partial w}{\partial x} &= w + x \\ \frac{\partial u}{\partial t} - \frac{\partial u}{\partial x} &= w \end{aligned} \right. \quad \checkmark$$

Ex: (relevant to HW5 Q4)

$$-\infty < x < \infty \quad t \geq 0$$

$$\begin{cases} \frac{\partial^2 u}{\partial t^2} = \frac{\partial^2 u}{\partial x^2} + t \\ u(x, 0) = x \\ u_t(x, 0) = 2 \end{cases}$$

PDE:

$$\left(\frac{\partial^2}{\partial t^2} - \frac{\partial^2}{\partial x^2} \right) u = t$$

$$\left(\frac{\partial}{\partial t} - \frac{\partial}{\partial x} \right) \underbrace{\left(\frac{\partial}{\partial t} + \frac{\partial}{\partial x} \right) u}_{w} = t$$

$$\begin{cases} \frac{\partial w}{\partial t} - \frac{\partial w}{\partial x} = t & \text{--- ①} \\ \frac{\partial w}{\partial t} + \frac{\partial w}{\partial x} = w & \text{--- ②} \end{cases}$$

Need to solve ① first
 → b.c. = ?

$$w(x, t) \equiv u_t(x, t) + u_x(x, t)$$

at $t=0$

$$w(x, 0) \equiv u_t(x, 0) + u_x(x, 0) = 2 + \frac{\partial}{\partial x}(x) = 3$$

Solve ①

$$\begin{cases} \frac{\partial w}{\partial t} - \frac{\partial w}{\partial x} = t \\ w(x, 0) = 3 \end{cases}$$



Full sol. for $w(x, t)$

$$w(x, t) = 3 + t^2/2$$

move to ②

$$\textcircled{2} \quad \frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} = 3 + t^2/2$$

$$u(x, 0) = x$$

↪ MOC

$$\frac{dx}{dt} = 1 \Rightarrow \underline{x(t) = x(0) + t} \Rightarrow x(0) = x(t) - t$$

$$\frac{du}{dt} = 3 + \frac{t^2}{2} \Rightarrow u(t) = u(0) + 3t + \frac{t^3}{6}$$

b.c. for ② is just " $u(x, 0) = x$ "

$$\underline{u(x(t), t)} = \underline{u(x(0), 0)} + 3t + \frac{t^3}{6}$$

$$= \underline{x(0)} + 3t + t^3/6$$

$$= \underline{(x(t) - t)} + 3t + t^3/6$$

Full sol.

$$u(x, t) = x + 2t + t^3/6$$

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Further examples on MOC

EX: $-\infty < x < \infty$ $t \geq 0$ ✓ "decouple" ✓
OR

$$\begin{cases} \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = x \\ u(x, 0) = 0 \end{cases}$$

MOC: $\frac{dx}{dt} = x$ ①

coupled $\left\{ \begin{aligned} \frac{dx}{dt} &= x && \text{--- ①} \\ \frac{du}{dt} &= x && \text{--- ②} \end{aligned} \right.$

$\frac{d}{dt} \begin{pmatrix} x \\ u \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ u \end{pmatrix}$

✓ combine ①, ②
into 1 eq. ✓
1 var

General remark Don't worry about (Not needed for our HW, it! Exsm questions)

\vec{x} $\frac{d\vec{x}}{dt} = A\vec{x}$ diagonalization to "decouple"

λ_j : eig. val. of A $A = E^{-1}AE$
 \vec{e}_j : " basis of A

$E = (\vec{e}_1 \dots)$ $\frac{d\vec{x}}{dt} = E^{-1}AE \vec{y} \equiv E \vec{x}$

$A = \begin{pmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \ddots \end{pmatrix}$ $\frac{d\vec{y}}{dt} = A\vec{y}$ ✓

Strategies:

(i)

$$\frac{dx}{dt} = u \quad \text{--- ①}$$

$$\frac{dy}{dx} = x \quad \text{--- ②}$$

$$\frac{d(x+y)}{dt} = (x+y)$$

define $v \equiv x+y$

$$\frac{dv}{dt} = v \quad v(t) = v(0)e^t$$

$$x(t) + y(t) = [x(0) + y(0)]e^t = \underline{x(0)e^t}$$

$$u(t) = x(t) - x(0)e^t$$

Use ①

$$\frac{dx}{dt} = x - x(0)e^t$$

$$x(t) = x(0)e^t + \int_0^t x(0)e^{\tau} e^{-(t-\tau)} d\tau \quad (\text{Sec 8.3})$$

keep going

try to work out detail!

$$(ii) \quad \frac{dx}{dt} = u \quad \text{--- ①}$$

$$\text{---} \quad \frac{du}{dt} = x \quad \text{--- ②}$$

$$\frac{d(x-u)}{dt} = (u-x)$$

$$v \equiv x - u$$

$$\frac{dv}{dt} = -v$$

$$v(t) = v(0)e^{-t}$$

⋮

work out detail!

(iii)

$$\frac{dx}{dt} = u \quad \text{--- ①}$$

$$\frac{du}{dt} = x \quad \text{--- ②}$$

$$\Rightarrow x(t) = \frac{du}{dt} = A \sinh(t) + B \cosh(t)$$

$$\frac{d}{dt} \text{②} \Rightarrow \frac{d^2 u}{dt^2} = u \Rightarrow u(t) = A \cosh(t) + B \sinh(t)$$

From b.c.: "u(x,0)=0" \Rightarrow u(0)=0

$$\underline{A=0} \Leftrightarrow 0 = u(0) = \underbrace{A \cosh(0)}_1 + \cancel{B \sinh(0)}$$

$$\Rightarrow \left. \begin{array}{l} x(t) = B \cosh(t) \\ u(t) = B \sinh(t) \end{array} \right\} \frac{u(t)}{x(t)} = \tanh(t)$$

Full sol:

$$u(t) = \cancel{x} x(t) \tanh(t)$$

$$u(x,t) = x \tanh(t)$$

$$\Leftrightarrow u(\underline{x}, t) = \underline{x(t)} \cdot \tanh(t)$$