

Lecture 7

9/14

Reminder: HW1 due (at Canvas) 11:59 PM, Friday.

Office hrs: Mon/Tue 3-5 PM, ERC 359

Figures should be clearly labeled.

~~A~~

Background (governing eqs.)

p-based vs. g-based solver

Relevant points

concerning Fluent

Turbulence vs. Laminar model

"Scaled residual"

Steady vs. transient

~~trans~~ solution

* Continuity eq. (Cons. of mass) ✓

* Energy eq. (" of thermal energy) 1/2 (static)

discussed special case w/ $\rho = \text{const}$

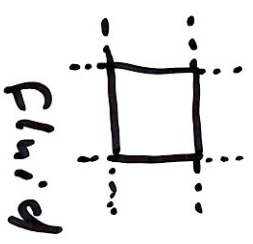
* Momentum eq. (" of momentum)

$m \vec{v}$ mech. 101

Newton's 2nd law

$$\frac{d\vec{v}}{dt} = \frac{\vec{F}}{m}$$

change of momentum

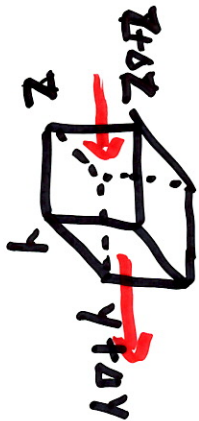


$$P = \frac{F}{A}$$

* internal interaction

between neighboring parcels, in the "normal" direction

* external force (e.g. gravity)



$$\vec{v} = (u, v, w)$$



momentum balance Net force

force at x : $p(x, y, z, t) \cdot \Delta y \cdot \Delta z$ (left)

→ " $x + \Delta x$: $p(x + \Delta x, y, z, t) \cdot \Delta y \cdot \Delta z$ (right)

$$[p(x, y, z, t) - p(x + \Delta x, y, z, t)] \cdot \Delta y \cdot \Delta z \quad \text{net force in } x\text{-dir}$$

$$= \underbrace{\rho \cdot \Delta x \cdot \Delta y \cdot \Delta z}_{\text{mass}} \cdot \underbrace{\left(\frac{du}{dt}\right)}_{\text{acc. in } x\text{-dir}} = \rho \cdot \Delta x \cdot \Delta y \cdot \Delta z \cdot \frac{du}{dt}$$

$$\frac{dv}{dt} = -\frac{1}{\rho} \left(\frac{p(x+\Delta x, y, z, t) - p(x, y, z, t)}{\Delta x} \right)$$

$$\lim_{\Delta x \rightarrow 0} \frac{dv}{dt} = -\frac{1}{\rho} \frac{\partial p}{\partial x} \quad \text{pressure gradient}$$

pressure gradient force PGF

Repeat for y- z-direction:

$$\frac{dv}{dt} = -\frac{1}{\rho} \frac{\partial p}{\partial y} \quad \text{--- ②}$$

$$\frac{dv}{dt} = -\frac{1}{\rho} \frac{\partial p}{\partial z} \quad \text{--- ③}$$

Next

(D) \rightsquigarrow (E)

$$\frac{d(\cdot)}{dt} \equiv \frac{\partial(\cdot)}{\partial t} + u \frac{\partial(\cdot)}{\partial x} + v \frac{\partial(\cdot)}{\partial y} + w \frac{\partial(\cdot)}{\partial z}$$

① $\rightarrow \frac{\partial u}{\partial t} = -u \frac{\partial u}{\partial x} - v \frac{\partial u}{\partial y} - w \frac{\partial u}{\partial z} - \frac{1}{\rho} \frac{\partial p}{\partial x}$

$\frac{\partial v}{\partial t} = -u \frac{\partial v}{\partial x} - v \frac{\partial v}{\partial y} - w \frac{\partial v}{\partial z} - \frac{1}{\rho} \frac{\partial p}{\partial y}$

$\frac{\partial w}{\partial t} = -u \frac{\partial w}{\partial x} - v \frac{\partial w}{\partial y} - w \frac{\partial w}{\partial z} - \frac{1}{\rho} \frac{\partial p}{\partial z} - g$

gravity \swarrow

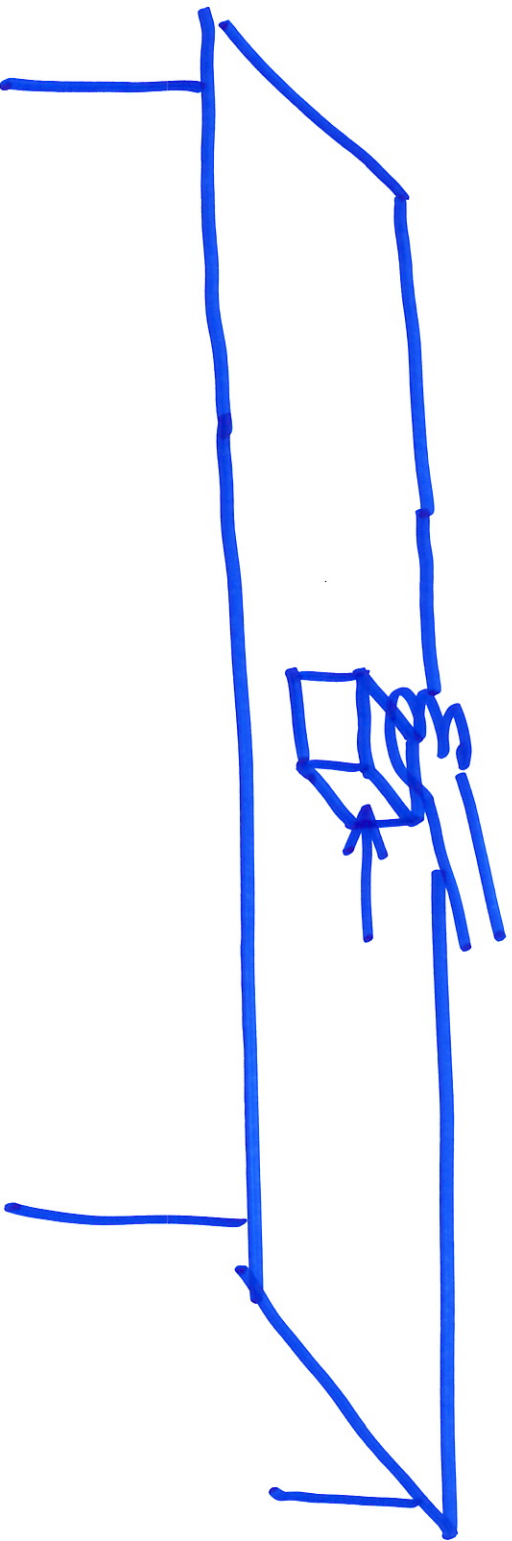
inertial terms P.G.F.

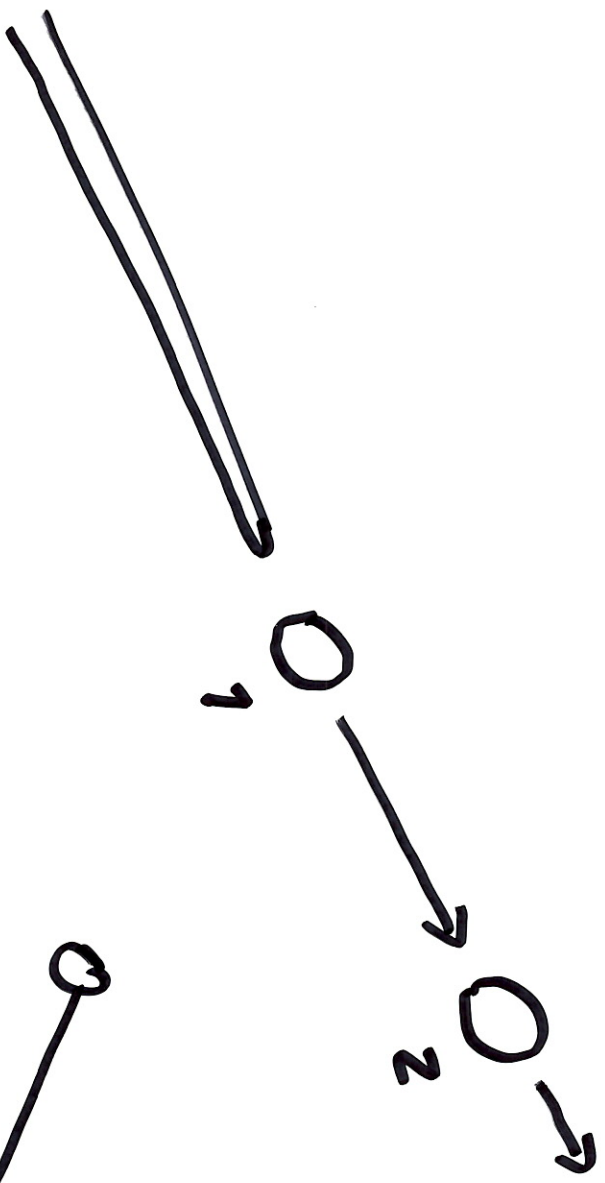
Euler eq.

Momentum eq. for an inviscid flow

Viscous term: "Diffusion" of momentum

intercal interaction between neighboring parcels, in the tangential direction

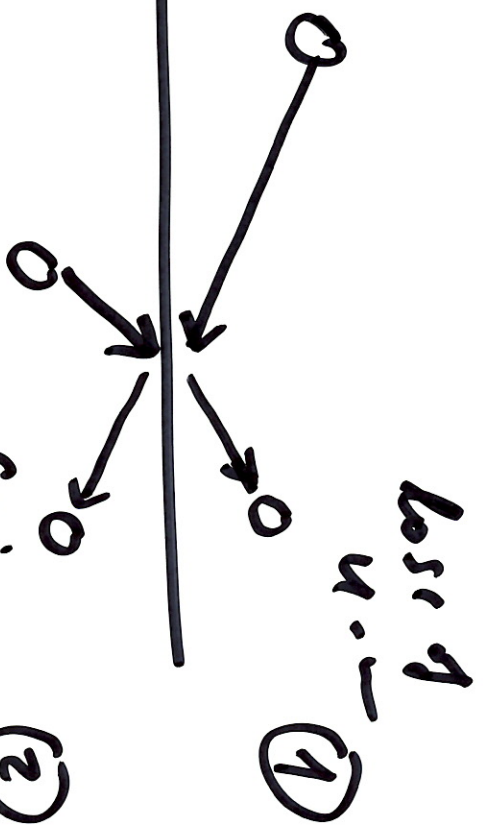




(Newtonian fluid)

$$\phi \propto -\frac{\partial v}{\partial z}$$

$$\phi = -\mu \frac{\partial v}{\partial z}$$



Loss 1

①

②

gain of momentum

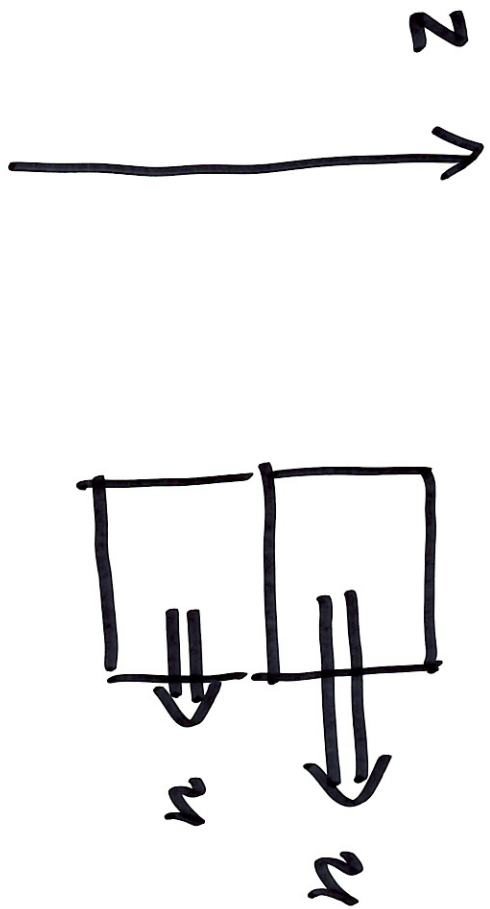
(dynamic)

viscosity

Fluent

Material





net flux in direction of u_z

$$\frac{\partial u}{\partial t} = -\frac{1}{\rho} \frac{\partial \phi}{\partial z}$$

ϕ : momentum flux
 $[\phi > 0 \text{ in if } \Rightarrow]$
 $[\phi > 0 \text{ is in } +z \text{ dir.}]$

Momentum = ϕ . (tired).

$$\frac{\partial u}{\partial t} = \frac{1}{\rho} \frac{\partial^2 u}{\partial z^2}$$

← x-dir
← z-dir

Amount of momentum passing through x-section per unit time area

Repeat it 8 more times

Navier - Stokes eq (viscous)

9 terms

$$\frac{\partial u}{\partial t} = \underbrace{-u \frac{\partial u}{\partial x} - v \frac{\partial u}{\partial y} - w \frac{\partial u}{\partial z}}_{\text{Inertial}} - \underbrace{\frac{1}{\rho} \frac{\partial p}{\partial x}}_{\text{P.A.F.}} + \underbrace{\frac{\mu}{\rho} \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)}_{\text{viscous}}$$

$$\frac{\partial v}{\partial t} = \text{''} + \frac{\mu}{\rho} \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right)$$

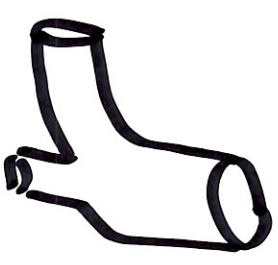
$$\frac{\partial w}{\partial t} = \text{''} + \frac{\mu}{\rho} \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right)$$

(-g)

General

$$\frac{\partial \vec{v}}{\partial t} = -\vec{v} \cdot \nabla \vec{v} - \frac{1}{\rho} \nabla p + \frac{\mu}{\rho} \nabla^2 \vec{v}$$

(I)
(PGF)
(Visc)



Steady

$$0 = \text{(I)} + \text{(PGF)} + \text{(Visc)}$$

"Turbulent"

Reynolds * $\approx \frac{|\text{(I)}|}{|\text{(Visc)}|}$

primary balance

High Re: $|\text{(I)}| \gg |\text{(Visc)}|$

Low Re: $|\text{(I)}| \sim |\text{(PGF)}|$

"Laminar"

Low Re: $|\text{(I)}| \ll |\text{(Visc)}|$

$\text{(PGF)} \sim \text{(Visc)}$

$$0 \approx \underbrace{-\vec{v} \cdot \nabla \vec{v}} - \frac{1}{\rho} \nabla p + \underbrace{\frac{\mu}{\rho} \nabla^2 \vec{v}}$$

$$Re \sim \frac{|\vec{v} \cdot \nabla \vec{v}|}{\nu \nabla^2 \vec{v}} \sim \frac{UL}{\nu} \quad \frac{\mu}{\rho} \equiv \nu$$

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