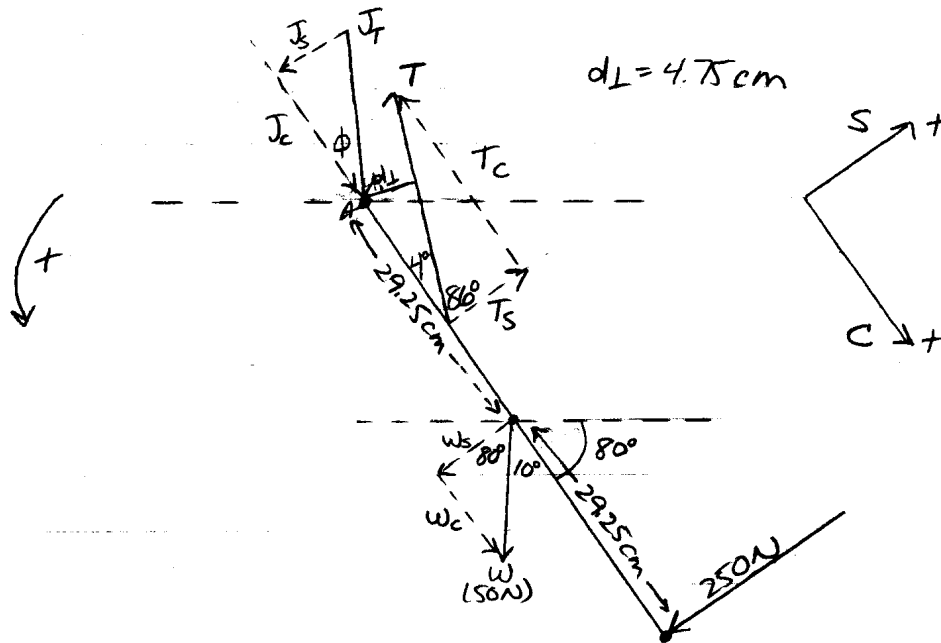


KIN 512 Problem Set #1

a) Draw a complete Free Body Diagram (FBD)



b) Calculate T (patellar ligament force)

$$\oplus \sum M_A = 0$$

$$\Rightarrow T d_L - (W \cos(80^\circ))(29.25 \text{ cm}) - (250 \text{ N})(58.5 \text{ cm}) = 0$$

$$\Rightarrow T = \frac{(50)(\cos(80^\circ))(29.25 \text{ cm}) + (250 \text{ N})(58.5 \text{ cm})}{4.75 \text{ cm}}$$

$$\Rightarrow T = 3132.412728 \text{ N} \quad \Rightarrow \boxed{T = 3130 \text{ N}}$$

c) Calculate compressive and shear components of the joint force J_T .

$$\downarrow \sum F_c = 0$$

$$\Rightarrow J_c + W_c - T_c = 0$$

$$\Rightarrow J_c = T \sin 86^\circ - W \sin 80^\circ$$

$$\Rightarrow J_c = (3132.412728 \text{ N})(\sin 86^\circ) - (50 \text{ N})(\sin 80^\circ)$$

$$\Rightarrow J_c = 3075.4194 \text{ N} \quad \Rightarrow \boxed{J_c = 3080 \text{ N}}$$

$$\begin{aligned} \uparrow \sum F_s &= 0 \\ -J_s - w_s - 250N + T_s &= 0 \\ \Rightarrow J_s &= T_s - w_s - 250N \\ \Rightarrow J_s &= T \cos(86) - w \cos(80) - 250N \\ \Rightarrow J_s &= (3132.412728N) \cos(86) - (50N) \cos(80) - 250N \\ \Rightarrow J_s &= -40.17634267N \Rightarrow \boxed{J_s = -40.2N} \end{aligned}$$

d) Calculate the magnitude of J_T and its direction.

$$\begin{aligned} |J_T| &= \sqrt{J_s^2 + J_c^2} \\ \Rightarrow |J_T| &= \sqrt{(-40.17634267)^2 + (3075.4194)^2} \\ \Rightarrow |J_T| &= 3075.681814N \Rightarrow \boxed{|J_T| = 3080N} \end{aligned}$$

The direction of J_T is given by ϕ (see FBD)

$$\begin{aligned} \tan \phi &= \frac{J_s}{J_c} \Rightarrow \phi = \tan^{-1}\left(\frac{J_s}{J_c}\right) \\ \Rightarrow \phi &= \tan^{-1}\left(\frac{-40.17634267}{3075.4194}\right) \\ \Rightarrow \phi &= -0.748452043^\circ \Rightarrow \boxed{\phi = -0.75^\circ} \end{aligned}$$

ie J_T is at an angle of -0.75° relative to the long axis of the Tibia).

e) Since $J_s = -40.2N$, it means that J_s is directed anteriorly, therefore J_s is sustained by the PCL to counteract net posteriorly directed force. (the PCL provides anteriorly directed force to prevent the Tibia from translating posteriorly).

Note: If you got a negative value for J_s it means that you drew the direction of J_T wrong on your FBD. Rather than showing J_T pointing slightly posteriorly, it actually points slightly anteriorly (as indicated in this solution above). The negative angle ϕ also reflects the same thing. It is OK to keep these negative values; or you could redraw J_T in your FBD and solve for positive values for J_s and ϕ . Either way, the interpretation is the same.

f) Calculate Q (quadriceps muscle force), knowing T and an appropriate T/Q ratio.

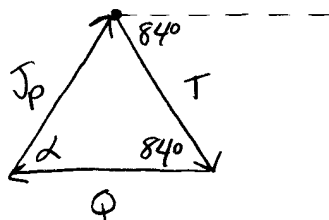
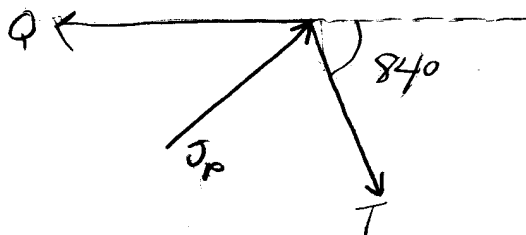
Here we have 80° of knee flexion, so from the literature (from Miller et al (1997) Clinical Biomechanics, 12, 1-7, on Page K22 of the class notes) at 80° of flexion an appropriate T/Q ratio is ~ 0.7 (which is approximately in the mid range of all data shown).

We found $T = 3132.412728 \text{ N}$ from part b)

$$\therefore \frac{T}{Q} = 0.7 \Rightarrow Q = \frac{T}{0.7} = \frac{3132.412728 \text{ N}}{0.7}$$

$$\Rightarrow Q = 4474.875326 \text{ N} \Rightarrow \boxed{Q = 4470 \text{ N}}$$

g) Complete a Free Body Diagram of the Patella. Compute the Patellofemoral Joint Force (J_p).



Using the law of Cosines to get J_p :

$$\Rightarrow J_p^2 = T^2 + Q^2 - 2TQ \cos(84^\circ)$$

$$\Rightarrow J_p^2 = (3132.412728)^2 + (4474.875326)^2 - 2(T)(Q) \cos(84^\circ)$$

$$\Rightarrow J_p^2 = 2.690613504 \times 10^7$$

$$\Rightarrow J_p = 5187.112399 \text{ N} \Rightarrow \boxed{J_p = 5190 \text{ N}}$$

h) Calculate the direction (α) of J_p .

Using the Law of Sines we get:

$$\frac{\sin \alpha}{T} = \frac{\sin 84}{J_p}$$

$$\Rightarrow \sin \alpha = \frac{T \sin 84}{J_p} \Rightarrow \alpha = \sin^{-1} \left(\frac{T \sin 84}{J_p} \right)$$

$$\Rightarrow \alpha = \sin^{-1} \left(\frac{(3132.412728) \sin 84}{(5187.112399)} \right) = \sin^{-1} (0.600575581)$$

$$\Rightarrow \alpha = 36.91113173^\circ \Rightarrow \boxed{\alpha = 36.9^\circ}$$

$\therefore J_p$ is at an angle of 36.9° with respect to ϕ .