

**ON THE STRUCTURE OF POSITIVE  
RADIAL SOLUTIONS FOR QUASILINEAR EQUATIONS  
IN ANNULAR DOMAINS**

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**Abstract.** We study the existence, multiplicity and nonexistence of positive radial solutions to boundary value problems for the quasilinear equation  $\operatorname{div}(A(|\nabla u|)\nabla u) + \lambda h(|x|)f(u) = 0$  in annular domains under general assumptions on the function  $A(u)$ . Various possible behaviors of the quotient  $\frac{f(u)}{A(u)u}$  at zero and infinity are considered. We shall use fixed point theorems for operators on a Banach space.

1. INTRODUCTION

In this paper we consider the existence, multiplicity and nonexistence of positive radial solutions for the quasilinear equation

$$\operatorname{div}(A(|\nabla u|)\nabla u) + \lambda k(|x|)f(u) = 0, \text{ in } R_1 < |x| < R_2, x \in \mathbb{R}^n, n \geq 2 \quad (1.1)$$

with one of the following three sets of boundary conditions,

$$u = 0 \text{ on } |x| = R_1 \text{ and } |x| = R_2, \quad (1.2a)$$

$$\partial u / \partial r = 0 \text{ on } |x| = R_1 \text{ and } u = 0 \text{ on } |x| = R_2, \quad (1.2b)$$

$$u = 0 \text{ on } |x| = R_1 \text{ and } \partial u / \partial r = 0 \text{ on } |x| = R_2, \quad (1.2c)$$

where  $r = |x|$  and  $\partial/\partial r$  denotes differentiation in the radial direction, and  $0 < R_1 < R_2 < \infty$ .

Ni and Serrin [14, 15] established some existence and non-existence theorems for radial ground state solutions of quasilinear equations of the form (1.1) in  $\mathbb{R}^n$ . The function  $A$  originates from a variety of practical applications, for instance, the degenerate  $m$ -Laplace operator, namely  $A(|p|) =$

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$|p|^{m-2}$ ,  $m > 1$ . When  $A \equiv 1$  we recall that (1.1) reduces to the classical semilinear elliptic equation

$$\Delta u + \lambda k(|x|)f(u) = 0, \text{ in } R_1 < |x| < R_2, x \in \mathbb{R}^n, n \geq 2. \quad (1.3)$$

(1.3)-(1.2) has been studied by Bandle, Coffman and Marcus [1], Bandle and Peletier [2], Coffman and Kwong [3], Lin [12], Ni and Nussbaum [13] and many others [5, 7, 9, 11, 16, 18, 19]. In particular, when  $f$  is non-negative, Bandle, Coffman and Marcus [1], Coffman and Marcus [5] and Lin [12] have established the existence of positive radial solutions of (1.3)-(1.2) under the assumption that  $f$  is superlinear, i.e.,  $\lim_{u \rightarrow 0} \frac{f(u)}{u} = 0$  and  $\lim_{u \rightarrow \infty} \frac{f(u)}{u} = \infty$ , which improves various earlier existence results by many authors under some additional assumptions on  $f$ .

On the other hand, the present author [16] has established the existence of positive radial solutions of (1.3)-(1.2) under the assumption that  $f$  is sublinear, i.e.,  $\lim_{u \rightarrow 0} \frac{f(u)}{u} = \infty$  and  $\lim_{u \rightarrow \infty} \frac{f(u)}{u} = 0$ . In fact, we shall show that the existence, multiplicity and nonexistence of positive radial solutions of (1.3)-(1.2) are characterized by the asymptotic behaviors of the quotient  $\frac{f(u)}{u}$  at zero and infinity.

The main purpose of this paper is to examine the quasilinear problem (1.1)-(1.2) under general assumptions on the function  $A$ . In this paper we introduce a new and general assumption (see H1) on the function  $A$ , which covers the two important cases  $A \equiv 1$  and  $A(|p|) = |p|^{m-2}$ ,  $m > 1$ , i.e., the degenerate  $m$ -Laplace operator.

Under such assumption, we are able to show that the structure of the positive radial solution set of (1.1)-(1.2) is exactly the same as that of the two special cases  $A \equiv 1$  and  $A(|p|) = |p|^{m-2}$ ,  $m > 1$ , in the sense that Theorems 1.1 and 1.2 hold for the general problem (1.1)-(1.2) and the two special cases. We consider not only existence, but also multiplicity and nonexistence. Our results (Theorems 1.1 and 1.2) generalize and extend the work of many authors [1, 2, 3, 5, 7, 11, 12, 13, 16, 18, 19]. Furthermore, most of our results are new even for the case  $A(|p|) = |p|^{m-2}$ ,  $m > 1$ .

Finally, our arguments in this paper are closely related to those of [16], in which the present author uses the fixed point index for compact maps, which is based on Leray-Schauder degree theory, to study (1.1)-(1.2) for  $A \equiv 1$ .

Let  $\varphi(t) := A(|t|)t$ . We make the assumptions:

- (H1)  $\varphi$  is an odd, increasing homeomorphism from  $\mathbb{R}$  onto  $\mathbb{R}$  and there exist two increasing homeomorphisms  $\psi_1$  and  $\psi_2$  from  $(0, \infty)$  onto

$(0, \infty)$  such that

$$\psi_1(\sigma)\varphi(t) \leq \varphi(\sigma t) \leq \psi_2(\sigma)\varphi(t), \text{ for all } \sigma \text{ and } t > 0.$$

(H2)  $k : [R_1, R_2] \rightarrow [0, \infty)$  is continuous and  $k(t) \not\equiv 0$  on any subinterval of  $[R_1, R_2]$ .

(H3)  $f : [0, \infty) \rightarrow [0, \infty)$  is continuous.

(H4)  $f(u) > 0$  for  $u > 0$ .

In order to state our results we introduce the notation

$$f_0 := \lim_{u \rightarrow 0} \frac{f(u)}{\varphi(u)} \quad \text{and} \quad f_\infty := \lim_{u \rightarrow \infty} \frac{f(u)}{\varphi(u)}.$$

Our main results are:

**Theorem 1.1.** *Assume (H1)-(H3) hold.*

- (a) *If  $f_0 = 0$  and  $f_\infty = \infty$ , then for all  $\lambda > 0$  (1.1)-(1.2) has a positive radial solution.*
- (b) *If  $f_0 = \infty$  and  $f_\infty = 0$ , then for all  $\lambda > 0$  (1.1)-(1.2) has a positive radial solution.*

**Theorem 1.2.** *Assume (H1)-(H4) hold.*

- (a) *If  $f_0 = 0$  or  $f_\infty = 0$ , then there exists a  $\lambda_0 > 0$  such that for all  $\lambda > \lambda_0$  (1.1)-(1.2) has a positive radial solution.*
- (b) *If  $f_0 = \infty$  or  $f_\infty = \infty$ , then there exists a  $\lambda_0 > 0$  such that for all  $0 < \lambda < \lambda_0$  (1.1)-(1.2) has a positive radial solution.*
- (c) *If  $f_0 = f_\infty = 0$ , then there exists a  $\lambda_0 > 0$  such that for all  $\lambda > \lambda_0$  (1.1)-(1.2) has two positive radial solutions.*
- (d) *If  $f_0 = f_\infty = \infty$ , then there exists a  $\lambda_0 > 0$  such that for all  $0 < \lambda < \lambda_0$  (1.1)-(1.2) has two positive radial solutions.*
- (e) *If  $f_0 < \infty$  and  $f_\infty < \infty$ , then there exists a  $\lambda_0 > 0$  such that for all  $0 < \lambda < \lambda_0$  (1.1)-(1.2) has no positive radial solution.*
- (f) *If  $f_0 > 0$  and  $f_\infty > 0$ , then there exists a  $\lambda_0 > 0$  such that for all  $\lambda > \lambda_0$  (1.1)-(1.2) has no positive radial solution.*

We should mention that, on an annulus, there are non-radially symmetric positive solutions of (1.1)-(1.2) even when  $f(u) = u^p$ , which was first observed by Brezis and Nirenberg [4].

## 2. PRELIMINARIES

A radial solution of (1.1)-(1.2) can be considered as a solution of the equation

$$(r^{n-1}\varphi(u'(r)))' + \lambda r^{n-1}k(r)f(u(r)) = 0, \text{ in } R_1 < r < R_2, \quad (2.1)$$

with one of the following three sets of boundary conditions,

$$u(R_1) = u(R_2) = 0, \quad (2.2a)$$

$$u'(R_1) = u(R_2) = 0, \quad (2.2b)$$

$$u(R_1) = u'(R_2) = 0. \quad (2.2c)$$

We shall treat classical solutions of (2.1)-(2.2), namely functions  $u$  of class  $C^1$  on  $[R_1, R_2]$  with  $\varphi(u') \in C^1(R_1, R_2)$ , which satisfies (2.1)-(2.2) for  $r \in (R_1, R_2)$ . A solution  $u$  is positive if  $u(r) > 0$  for all  $r \in (R_1, R_2)$ .

Applying change of variables,  $r = (R_2 - R_1)t + R_1$ , we can transform (2.1)-(2.2) into the form

$$(q(t)\varphi(p(t)u'))' + \lambda h(t)f(u) = 0, \quad 0 < t < 1 \quad (2.3)$$

with one of the following three sets of boundary conditions,

$$u(0) = u(1) = 0, \quad (2.4a)$$

$$u'(0) = u(1) = 0, \quad (2.4b)$$

$$u(0) = u'(1) = 0, \quad (2.4c)$$

where

$$q(t) := ((R_2 - R_1)t + R_1)^{n-1}, \quad p(t) := \frac{1}{R_2 - R_1}$$

and

$$h(t) := (R_2 - R_1)((R_2 - R_1)t + R_1)^{n-1}k((R_2 - R_1)t + R_1).$$

It is easy to see that (H1)-(H2) imply

$$(P) \left\{ \begin{array}{l} p(t) \text{ and } q(t) \in C[0, 1] \text{ with } p > 0 \text{ and } q > 0 \text{ for } t \in [0, 1] \\ \text{and } q(t) \text{ is nondecreasing on } [0, 1]. \\ \varphi \text{ is an odd, increasing homeomorphism from } \mathbb{R} \text{ onto } \mathbb{R} \text{ and} \\ \text{there exist two increasing homeomorphisms } \psi_1 \text{ and } \psi_2 \text{ from} \\ (0, \infty) \text{ onto } (0, \infty) \text{ such that} \\ \psi_1(\sigma)\varphi(t) \leq \varphi(\sigma t) \leq \psi_2(\sigma)\varphi(t), \text{ for all } \sigma \text{ and } t > 0. \\ h : [0, 1] \rightarrow [0, \infty) \text{ is continuous and does not vanish identically} \\ \text{on any subinterval of } [0, 1]. \end{array} \right.$$

For (2.3)-(2.4) we shall prove Theorems 2.1 and 2.2, which immediately imply that Theorems 1.1 and 1.2 are true. In addition, Part (g) of Theorem 2.2 also holds for (1.1)-(1.2).

Although the functions  $p$ ,  $q$ ,  $\varphi$  and  $h$  are of the special forms defined above, we remark that Theorems 2.1 and 2.2, including Lemmas 2.4-2.11, hold even for general functions  $p$ ,  $q$ ,  $\varphi$  and  $h$  if they satisfy the property (P).

In the following proof we only use the property (P) of  $p, q, \varphi$  and  $h$  and do not rely on any special form that  $p, q, \varphi$  and  $h$  may have. Define

$$\rho := \left[ \int_0^1 \frac{1}{p(s)} ds \right]^{-1} \min \left\{ \int_0^{\frac{1}{4}} \frac{1}{p(t)} dt, \int_{\frac{3}{4}}^1 \frac{1}{p(t)} dt \right\} > 0,$$

and

$$\begin{aligned} \gamma(t) := & \frac{\rho}{2} \left[ \int_{\frac{1}{4}}^t \frac{1}{p(s)} \psi_2^{-1} \left( \frac{1}{q(1)} \int_s^t h(\tau) d\tau \right) ds \right. \\ & \left. + \int_t^{\frac{3}{4}} \frac{1}{p(s)} \psi_2^{-1} \left( \frac{1}{q(1)} \int_t^s h(\tau) d\tau \right) ds \right], \end{aligned}$$

where  $t \in [\frac{1}{4}, \frac{3}{4}]$ . It follows from (H1)-(H2) that  $\Gamma := \min_{\frac{1}{4} \leq t \leq \frac{3}{4}} \gamma(t) > 0$ .

**Theorem 2.1.** *Assume (H1)-(H3) hold.*

- (a) *If  $f_0 = 0$  and  $f_\infty = \infty$ , then for all  $\lambda > 0$  (2.3)-(2.4) has a positive solution.*
- (b) *If  $f_0 = \infty$  and  $f_\infty = 0$ , then for all  $\lambda > 0$  (2.3)-(2.4) has a positive solution.*

**Theorem 2.2.** *Assume (H1)-(H4) hold.*

- (a) *If  $f_0 = 0$  or  $f_\infty = 0$ , then there exists a  $\lambda_0 > 0$  such that for all  $\lambda > \lambda_0$  (2.3)-(2.4) has a positive solution.*
- (b) *If  $f_0 = \infty$  or  $f_\infty = \infty$ , then there exists a  $\lambda_0 > 0$  such that for all  $0 < \lambda < \lambda_0$  (2.3)-(2.4) has a positive solution.*
- (c) *If  $f_0 = f_\infty = 0$ , then there exists a  $\lambda_0 > 0$  such that for all  $\lambda > \lambda_0$  (2.3)-(2.4) has two positive solutions.*
- (d) *If  $f_0 = f_\infty = \infty$ , then there exists a  $\lambda_0 > 0$  such that for all  $0 < \lambda < \lambda_0$  (2.3)-(2.4) has two positive solutions.*
- (e) *If  $f_0 < \infty$  and  $f_\infty < \infty$ , then there exists a  $\lambda_0 > 0$  such that for all  $0 < \lambda < \lambda_0$  (2.3)-(2.4) has no positive solution.*
- (f) *If  $f_0 > 0$  and  $f_\infty > 0$ , then there exists a  $\lambda_0 > 0$  such that for all  $\lambda > \lambda_0$  (2.3)-(2.4) has no positive solution.*
- (g) *If  $0 < f_0 < \infty, 0 < f_\infty < \infty$  and either*

$$\psi_2 \left( \frac{1}{\Gamma \psi_2^{-1}(f_0)} \right) < \lambda < \psi_1 \left( \frac{1}{\int_0^1 \frac{1}{p(s)} ds \psi_1^{-1} \left( \frac{1}{q(0)} \int_0^1 h(\tau) d\tau \right) \psi_1^{-1}(f_\infty)} \right)$$

or

$$\psi_2 \left( \frac{1}{\Gamma \psi_2^{-1}(f_\infty)} \right) < \lambda < \psi_1 \left( \frac{1}{\int_0^1 \frac{1}{p(s)} ds \psi_1^{-1} \left( \frac{1}{q(0)} \int_0^1 h(\tau) d\tau \right) \psi_1^{-1}(f_0)} \right),$$

then (2.3)-(2.4) has a positive solution.

The following well-known result of the fixed point index is crucial in our arguments.

**Lemma 2.3.** ([6, 8, 10]). *Let  $E$  be a Banach space and  $K$  a cone in  $E$ . For  $r > 0$ , define  $K_r := \{u \in K : \|x\| < r\}$ . Assume that  $T : \bar{K}_r \rightarrow K$  is completely continuous such that  $Tx \neq x$  for  $x \in \partial K_r := \{u \in K : \|x\| = r\}$ .*

- (i) *If  $\|Tx\| \geq \|x\|$  for  $x \in \partial K_r$ , then  $i(T, K_r, K) = 0$ .*
- (ii) *If  $\|Tx\| \leq \|x\|$  for  $x \in \partial K_r$ , then  $i(T, K_r, K) = 1$ .*

In order to apply Lemma 2.3 to (2.3)-(2.4), let  $X$  be the Banach space  $C[0, 1]$  with  $\|u\| = \sup_{t \in [0, 1]} |u(t)|$ . Define  $K$  be a cone in  $X$  by

$$K := \{u \in X : u(t) \geq 0, \quad \min_{\frac{1}{4} \leq t \leq \frac{3}{4}} u(t) \geq \rho \|u\|\}.$$

Also, define, for  $r$  a positive number,  $\Omega_r$  by  $\Omega_r := \{u \in K : \|u\| < r\}$ . Note that  $\partial \Omega_r = \{u \in K : \|u\| = r\}$ .

Let the map  $T_\lambda : K \rightarrow X$  be defined by

$$T_\lambda u(t) := \begin{cases} \int_0^t \frac{1}{p(s)} \varphi^{-1}\left(\frac{1}{q(s)} \lambda \int_s^\sigma h(\tau) f(u(\tau)) d\tau\right) ds, & 0 \leq t \leq \sigma, \\ \int_t^1 \frac{1}{p(s)} \varphi^{-1}\left(\frac{1}{q(s)} \lambda \int_\sigma^s h(\tau) f(u(\tau)) d\tau\right) ds, & \sigma \leq t \leq 1, \end{cases}$$

where  $\sigma = 0$  for (2.3)-(2.4b) and  $\sigma = 1$  for (2.3)-(2.4c). For (2.3)-(2.4a)  $\sigma \in (0, 1)$  is a solution of the equation

$$Z_1(t) = Z_2(t), \tag{2.5}$$

where

$$Z_1(t) = \int_0^t \frac{1}{p(s)} \varphi^{-1}\left(\frac{1}{q(s)} \lambda \int_s^t h(\tau) f(u(\tau)) d\tau\right) ds, \quad 0 \leq t \leq 1,$$

and

$$Z_2(t) = \int_t^1 \frac{1}{p(s)} \varphi^{-1}\left(\frac{1}{q(s)} \lambda \int_t^s h(\tau) f(u(\tau)) d\tau\right) ds, \quad 0 \leq t \leq 1.$$

Note that (2.5) has at least one solution in  $(0, 1)$ . In fact, if  $h(\tau)f(u(\tau)) \equiv 0$  on  $[0, 1]$ , we may choose any  $\sigma \in (0, 1)$ . If there is a  $\tau \in (0, 1)$  such that  $h(\tau)f(u(\tau)) > 0$ , then  $Z_1(0) - Z_2(0) < 0$  and  $Z_1(1) - Z_2(1) > 0$ . Since  $Z_1(t) - Z_2(t)$  is nondecreasing continuous function defined on  $[0, 1]$ , (2.5) has at least one solution in  $(0, 1)$ . Moreover, if  $\sigma_1$  and  $\sigma_2 \in (0, 1)$  are solutions of (2.5), it is not difficult to show that  $h(\tau)f(u(\tau)) \equiv 0$  on  $[\sigma_1, \sigma_2]$ . Therefore,  $T_\lambda u(t)$  is independent of the choice of  $\sigma \in [\sigma_1, \sigma_2]$  and then the operator is well defined.

**Lemma 2.4.** *Assume (H1)-(H2) hold. Let  $u$  and  $v \in X$  with  $u(t) \geq 0$  and  $v(t) \leq 0$  for  $t \in [0, 1]$ . If  $(q(t)\varphi(p(t)u'))' = v$ , then*

$$u(t) \geq \left[ \int_0^1 \frac{1}{p(s)} ds \right]^{-1} \min \left\{ \int_0^t \frac{1}{p(s)} ds, \int_t^1 \frac{1}{p(s)} ds \right\} \|u\|, \quad t \in [0, 1].$$

*In particular,*

$$\min_{\frac{1}{4} \leq t \leq \frac{3}{4}} u(t) \geq \rho \|u\|.$$

**Proof.** Since  $q(t)\varphi(p(t)u'(t))$  is nonincreasing, it follows, from  $\varphi^{-1}$  is increasing and  $q(t)$  is nondecreasing, that  $p(t)u'(t)$  is nonincreasing. Hence, for  $0 \leq t_0 < t < t_1 \leq 1$ ,

$$u(t) - u(t_0) = \int_{t_0}^t \frac{1}{p(s)} p(s) u'(s) ds \geq \int_{t_0}^t \frac{1}{p(s)} ds p(t) u'(t)$$

and

$$u(t_1) - u(t) = \int_t^{t_1} \frac{1}{p(s)} p(s) u'(s) ds \leq \int_t^{t_1} \frac{1}{p(s)} ds p(t) u'(t),$$

from which, we have

$$u(t) \geq \left[ \int_{t_0}^{t_1} \frac{1}{p(s)} ds \right]^{-1} \left[ \int_t^{t_1} \frac{1}{p(s)} ds u(t_0) + \int_{t_0}^t \frac{1}{p(s)} ds u(t_1) \right].$$

Considering the above inequality on  $[0, \sigma]$  and  $[\sigma, 1]$ , we have

$$u(t) \geq \left[ \int_0^1 \frac{1}{p(s)} ds \right]^{-1} \int_0^t \frac{1}{p(s)} ds \|u\| \quad \text{for } t \in [0, \sigma],$$

and

$$u(t) \geq \left[ \int_0^1 \frac{1}{p(s)} ds \right]^{-1} \int_t^1 \frac{1}{p(s)} ds \|u\| \quad \text{for } t \in [\sigma, 1],$$

where  $\sigma \in [0, 1]$  such that  $u(\sigma) = \|u\|$ . Hence,

$$u(t) \geq \left[ \int_0^1 \frac{1}{p(s)} ds \right]^{-1} \min \left\{ \int_0^t \frac{1}{p(s)} ds, \int_t^1 \frac{1}{p(s)} ds \right\} \|u\|, \quad t \in [0, 1]. \quad \square$$

We remark that, according to Lemma 2.4, any non-negative solution of (2.3)-(2.4) is positive unless it is identical to zero.

**Lemma 2.5.** *Assume (H1)-(H3) hold. Then  $T_\lambda(K) \subset K$  and the map  $T_\lambda : K \rightarrow K$  is completely continuous.*

**Proof.** Lemma 2.4 implies that  $T_\lambda(K) \subset K$ . It is not difficult to verify that  $T_\lambda$  is compact and continuous.  $\square$

Now it is not difficult to show that (2.3)-(2.4) is equivalent to the fixed point equation

$$T_\lambda u = u \quad \text{in } K.$$

**Lemma 2.6.** *Assume (H1) holds. Then for all  $\sigma, t \in (0, \infty)$*

$$\psi_2^{-1}(\sigma)t \leq \varphi^{-1}(\sigma\varphi(t)) \leq \psi_1^{-1}(\sigma)t.$$

**Proof.** Since  $\sigma = \psi_1(\psi_1^{-1}(\sigma)) = \psi_2(\psi_2^{-1}(\sigma))$  and  $\varphi(\varphi^{-1}(\sigma\varphi(t))) = \sigma\varphi(t)$ , it follows that

$$\psi_2(\psi_2^{-1}(\sigma))\varphi(t) = \varphi(\varphi^{-1}(\sigma\varphi(t))) = \psi_1(\psi_1^{-1}(\sigma))\varphi(t).$$

On the other hand, we have by (H1)

$$\psi_1(\psi_1^{-1}(\sigma))\varphi(t) \leq \varphi(\psi_1^{-1}(\sigma)t) \quad \text{and} \quad \psi_2(\psi_2^{-1}(\sigma))\varphi(t) \geq \varphi(\psi_2^{-1}(\sigma)t).$$

Hence,

$$\varphi(\psi_2^{-1}(\sigma)t) \leq \varphi(\varphi^{-1}(\sigma\varphi(t))) \leq \varphi(\psi_1^{-1}(\sigma)t).$$

Since  $\varphi^{-1}$  is increasing, we obtain

$$\psi_2^{-1}(\sigma)t \leq \varphi^{-1}(\sigma\varphi(t)) \leq \psi_1^{-1}(\sigma)t. \quad \square$$

**Lemma 2.7.** *Assume (H1)-(H3) hold and let  $\eta > 0$ . If  $u \in K$  and  $f(u(t)) \geq \varphi(u(t)\eta)$  for  $t \in [\frac{1}{4}, \frac{3}{4}]$ , then*

$$\|T_\lambda u\| \geq \psi_2^{-1}(\lambda)\Gamma\eta\|u\|.$$

**Proof.** Note that from the definition of  $T_\lambda u$  that  $T_\lambda u(\sigma)$  is the maximum value of  $T_\lambda u$  on  $[0,1]$ . If  $\sigma \in [\frac{1}{4}, \frac{3}{4}]$ , it follows from Lemma 2.4 and Lemma 2.6 that

$$\begin{aligned} \|T_\lambda u\| &\geq \frac{1}{2} \left[ \int_{\frac{1}{4}}^{\sigma} \frac{1}{p(s)} \varphi^{-1} \left( \frac{1}{q(1)} \lambda \int_s^{\sigma} h(\tau) f(u(\tau)) d\tau \right) ds \right. \\ &\quad \left. + \int_{\sigma}^{\frac{3}{4}} \frac{1}{p(s)} \varphi^{-1} \left( \frac{1}{q(1)} \lambda \int_{\sigma}^s h(\tau) f(u(\tau)) d\tau \right) ds \right] \\ &\geq \frac{1}{2} \left[ \int_{\frac{1}{4}}^{\sigma} \frac{1}{p(s)} \varphi^{-1} \left( \frac{1}{q(1)} \int_s^{\sigma} h(\tau) \psi_2(\psi_2^{-1}(\lambda)) \varphi(u(\tau)\eta) d\tau \right) ds \right. \\ &\quad \left. + \int_{\sigma}^{\frac{3}{4}} \frac{1}{p(s)} \varphi^{-1} \left( \frac{1}{q(1)} \int_{\sigma}^s h(\tau) \psi_2(\psi_2^{-1}(\lambda)) \varphi(u(\tau)\eta) d\tau \right) ds \right] \\ &\geq \frac{1}{2} \left[ \int_{\frac{1}{4}}^{\sigma} \frac{1}{p(s)} \varphi^{-1} \left( \frac{1}{q(1)} \int_s^{\sigma} h(\tau) \varphi(\psi_2^{-1}(\lambda)\rho\eta\|u\|) d\tau \right) ds \right. \end{aligned}$$



$$\begin{aligned}
& + \int_{\sigma}^{\frac{3}{4}} \frac{1}{p(s)} \varphi^{-1} \left( \frac{1}{q(1)} \int_{\sigma}^s h(\tau) \varphi(\psi_2^{-1}(\lambda) \rho \eta \|u\|) d\tau \right) ds \Big] \\
& \geq \frac{1}{2} \left[ \int_{\frac{1}{4}}^{\sigma} \frac{1}{p(s)} \psi_2^{-1} \left( \frac{1}{q(1)} \int_s^{\sigma} h(\tau) d\tau \right) \psi_2^{-1}(\lambda) \rho \eta \|u\| ds \right. \\
& \quad \left. + \int_{\sigma}^{\frac{3}{4}} \frac{1}{p(s)} \psi_2^{-1} \left( \frac{1}{q(1)} \int_{\sigma}^s h(\tau) d\tau \right) \psi_2^{-1}(\lambda) \rho \eta \|u\| ds \right] \\
& = \frac{\psi_2^{-1}(\lambda) \eta \rho \|u\|}{2} \left[ \int_{\frac{1}{4}}^{\sigma} \frac{1}{p(s)} \psi_2^{-1} \left( \frac{1}{q(1)} \int_s^{\sigma} h(\tau) d\tau \right) ds \right. \\
& \quad \left. + \int_{\sigma}^{\frac{3}{4}} \frac{1}{p(s)} \psi_2^{-1} \left( \frac{1}{q(1)} \int_{\sigma}^s h(\tau) d\tau \right) ds \right] \geq \psi_2^{-1}(\lambda) \Gamma \eta \|u\|.
\end{aligned}$$

For  $\sigma > \frac{3}{4}$ , it is easy to see

$$\|T_{\lambda} u\| \geq \int_{\frac{1}{4}}^{\frac{3}{4}} \frac{1}{p(s)} \varphi^{-1} \left( \frac{1}{q(1)} \lambda \int_s^{\frac{3}{4}} h(\tau) f(u(\tau)) d\tau \right) ds.$$

On the other hand, we have

$$\|T_{\lambda} u\| \geq \int_{\frac{1}{4}}^{\frac{3}{4}} \frac{1}{p(s)} \varphi^{-1} \left( \frac{1}{q(1)} \lambda \int_{\frac{1}{4}}^s h(\tau) f(u(\tau)) d\tau \right) ds \text{ for } \sigma < \frac{1}{4}.$$

Therefore, similar arguments show that

$$\|T_{\lambda} u\| \geq \psi_2^{-1}(\lambda) \Gamma \eta \|u\| \text{ if } \sigma > \frac{3}{4} \text{ or } \sigma < \frac{1}{4}. \quad \square$$

Define a new function

$$f^*(u) := \max_{0 \leq t \leq u} \{f(t)\}.$$

Note that  $f_0^* = \lim_{u \rightarrow 0} \frac{f^*(u)}{\varphi(u)}$  and  $f_{\infty}^* = \lim_{u \rightarrow \infty} \frac{f^*(u)}{\varphi(u)}$ .

**Lemma 2.8.** *Assume (H1)-(H3) hold. Then  $f_0^* = f_0$  and  $f_{\infty}^* = f_{\infty}$ .*

**Proof.** It is easy to see that  $f_0^* = f_0$ . For the second part, we consider two cases, (a)  $f(u)$  is bounded and (b)  $f(u)$  is unbounded. For the case (a), it follows, from  $\lim_{u \rightarrow \infty} \varphi(u) = \infty$ , that  $f_{\infty}^* = 0 = f_{\infty}$ . For the case (b), for any  $\delta > 0$ , let  $M := \max_{0 \leq t \leq \delta} \{f(t)\}$  and  $N_{\delta} := \min\{u : u \geq \delta, f(u) \geq M\} \geq \delta$ , then

$$\max_{0 \leq t \leq N_{\delta}} \{f(t)\} = f(N_{\delta}).$$

Thus, for any  $\delta > 0$ , there exists a  $N_\delta \geq \delta$  such that

$$f^*(u) = \max\left\{\max_{0 \leq t \leq N_\delta} \{f(t)\}, \max_{N_\delta \leq t \leq u} \{f(t)\}\right\} = \max_{N_\delta \leq t \leq u} \{f(t)\} \text{ for } u > N_\delta.$$

Hence, it follows, from the definitions of  $f_\infty$  and  $f_\infty^*$ , that  $f_\infty^* = f_\infty$ .  $\square$

**Lemma 2.9.** *Assume (H1)-(H3) hold and let  $r > 0$ . If there exists an  $\varepsilon > 0$  such that  $f^*(r) \leq \psi_1(\varepsilon)\varphi(r)$ , then*

$$\|T_\lambda u\| \leq \psi_1^{-1}(\lambda) \int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) d\tau\right) \varepsilon \|u\| \text{ for } u \in \partial\Omega_r.$$

**Proof.** From the definition of  $T_\lambda$ , Lemma 2.4 and Lemma 2.6, for  $u \in \partial\Omega_r$ , we have

$$\begin{aligned} \|T_\lambda u\| &\leq \int_0^1 \frac{1}{p(s)} \varphi^{-1}\left(\frac{1}{q(0)} \lambda \int_0^1 h(\tau) f(u(\tau)) d\tau\right) ds \\ &\leq \int_0^1 \frac{1}{p(s)} \varphi^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) \lambda f^*(r) d\tau\right) ds \\ &\leq \int_0^1 \frac{1}{p(s)} ds \varphi^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) \psi_1(\psi_1^{-1}(\lambda)) \psi_1(\varepsilon) \varphi(r) d\tau\right) \\ &\leq \int_0^1 \frac{1}{p(s)} ds \varphi^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) d\tau \varphi(\psi_1^{-1}(\lambda) \varepsilon r)\right) \\ &\leq \int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) d\tau\right) \psi_1^{-1}(\lambda) \varepsilon \|u\|. \quad \square \end{aligned}$$

The following two lemmas are weak forms of Lemmas 2.7 and 2.9.

**Lemma 2.10.** *Assume (H1)-(H4) hold. If  $u \in \partial\Omega_r$ ,  $r > 0$ , then*

$$\|T_\lambda u\| \geq \frac{\varphi^{-1}(\lambda \hat{m}_r) \Gamma}{\rho},$$

where  $\hat{m}_r := \min_{\rho r \leq t \leq r} \{f(t)\} > 0$ .

**Proof.** Since  $\lambda f(u(t)) \geq \lambda \hat{m}_r = \varphi(\varphi^{-1}(\lambda \hat{m}_r))$  for  $t \in [\frac{1}{4}, \frac{3}{4}]$ , it is easy to see that this lemma can be shown in a similar manner as in Lemma 2.7.  $\square$

**Lemma 2.11.** *Assume (H1)-(H4) hold. If  $u \in \partial\Omega_r$ ,  $r > 0$ , then*

$$\|T_\lambda u\| \leq \varphi^{-1}(\lambda \hat{M}_r) \int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) d\tau\right),$$

where  $\hat{M}_r := \max_{0 \leq t \leq r} \{f(t)\} > 0$ .

**Proof.** Since  $\lambda f(u(t)) \leq \lambda \hat{M}_r = \varphi(\varphi^{-1}(\lambda \hat{M}_r))$  for  $t \in [0, 1]$ , it is easy to see that this lemma can be shown in a similar manner as in Lemma 2.9.  $\square$

### 3. PROOF OF THEOREM 2.1

**Proof.** Part (a). It follows from Lemma 2.8 that  $f_0^* = 0$ . Therefore, we can choose  $r_1 > 0$  so that  $f^*(r_1) \leq \psi_1(\varepsilon)\varphi(r_1)$ , where the constant  $\varepsilon > 0$  satisfies

$$\varepsilon \psi_1^{-1}(\lambda) \int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \int_0^1 h(s) ds\right) < 1.$$

We have by Lemma 2.9 that

$$\|T_\lambda u\| \leq \psi_1^{-1}(\lambda) \int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) d\tau\right) \varepsilon \|u\| < \|u\| \quad \text{for } u \in \partial\Omega_{r_1}.$$

Now, since  $f_\infty = \infty$ , there is an  $\hat{H} > 0$  such that  $f(u) \geq \psi_2(\eta)\varphi(u)$  for  $u \geq \hat{H}$ , where  $\eta > 0$  is chosen so that

$$\psi_2^{-1}(\lambda)\Gamma\eta > 1.$$

Let  $r_2 = \max\{2r_1, \frac{\hat{H}}{\rho}\}$ . If  $u \in \partial\Omega_{r_2}$ , then

$$\min_{\frac{1}{4} \leq t \leq \frac{3}{4}} u(t) \geq \rho \|u\| = \rho r_2 \geq \hat{H},$$

which implies that

$$f(u(t)) \geq \psi_2(\eta)\varphi(u(t)) \geq \varphi(u(t)\eta) \quad \text{for } t \in \left[\frac{1}{4}, \frac{3}{4}\right].$$

It follows from Lemma 2.7 that

$$\|T_\lambda u\| \geq \psi_2^{-1}(\lambda)\Gamma\eta \|u\| > \|u\| \quad \text{for } u \in \partial\Omega_{r_2}.$$

By Lemma 2.3,  $i(T_\lambda, \Omega_{r_1}, K) = 1$  and  $i(T_\lambda, \Omega_{r_2}, K) = 0$ . It follows from the additivity of the fixed point index that  $i(T_\lambda, \Omega_{r_2} \setminus \bar{\Omega}_{r_1}, K) = -1$ . Thus,  $i(T_\lambda, \Omega_{r_2} \setminus \bar{\Omega}_{r_1}, K) \neq 0$ , which implies  $T_\lambda$  has a fixed point  $u \in \Omega_{r_2} \setminus \bar{\Omega}_{r_1}$  according to the existence property of the fixed point index. The fixed point  $u \in \Omega_{r_2} \setminus \bar{\Omega}_{r_1}$  is the desired positive solution of (2.3)-(2.4).

Part (b). If  $f_0 = \infty$ , there is a  $r_1 > 0$  such that  $f(u) \geq \psi_2(\eta)\varphi(u)$  for  $0 \leq u \leq r_1$ , where  $\eta > 0$  is chosen so that  $\psi_2^{-1}(\lambda)\Gamma\eta > 1$ . If  $u \in \partial\Omega_{r_1}$ , then

$$f(u(t)) \geq \psi_2(\eta)\varphi(u(t)) \geq \varphi(u(t)\eta) \quad \text{for } t \in [0, 1].$$

Lemma 2.7 implies that

$$\|T_\lambda u\| \geq \psi_2^{-1}(\lambda)\Gamma\eta \|u\| > \|u\| \quad \text{for } u \in \partial\Omega_{r_1}.$$

We now determine  $\Omega_{r_2}$ . Since  $f_\infty^* = f_\infty = 0$ , there is a  $r_2 > 2r_1$  such that  $f^*(r_2) \leq \psi_1(\varepsilon)\varphi(r_2)$ , where the constant  $\varepsilon > 0$  satisfies

$$\varepsilon\psi_1^{-1}(\lambda) \int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \int_0^1 h(s) ds\right) < 1.$$

Thus, we have by Lemma 2.9

$$\|T_\lambda u\| \leq \psi_1^{-1}(\lambda) \int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) d\tau\right) \varepsilon \|u\| < \|u\| \quad \text{for } u \in \partial\Omega_{r_2}.$$

By Lemma 2.3,  $i(T_\lambda, \Omega_{r_1}, K) = 0$  and  $i(T_\lambda, \Omega_{r_2}, K) = 1$ . It follows from the additivity of the fixed point index that  $i(T_\lambda, \Omega_{r_2} \setminus \bar{\Omega}_{r_1}, K) = 1$ . Thus,  $T_\lambda$  has a fixed point in  $\Omega_{r_2} \setminus \bar{\Omega}_{r_1}$ , which is the desired positive solution of (2.3)-(2.4).

#### 4. PROOF OF THEOREM 2.2

**Proof.** Part (a). Choose a number  $r_1 > 0$ . By Lemma 2.10, we infer that there exists a  $\lambda_0 > 0$  such that

$$\|T_\lambda u\| > \|u\|, \quad \text{for } u \in \partial\Omega_{r_1}, \lambda > \lambda_0.$$

If  $f_0^* = f_0 = 0$ , we can choose  $0 < r_2 < r_1$  so that  $f^*(r_2) \leq \psi_1(\varepsilon)\varphi(r_2)$ , where the constant  $\varepsilon > 0$  satisfies

$$\varepsilon\psi_1^{-1}(\lambda) \int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \int_0^1 h(s) ds\right) < 1.$$

Thus, we have by Lemma 2.9 that

$$\|T_\lambda u\| \leq \psi_1^{-1}(\lambda) \int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) d\tau\right) \varepsilon \|u\| < \|u\| \quad \text{for } u \in \partial\Omega_{r_2}.$$

If  $f_\infty^* = f_\infty = 0$ , there is an  $r_3 > 2r_1$  such that  $f^*(r_3) \leq \psi_1(\varepsilon)\varphi(r_3)$ , where the constant  $\varepsilon > 0$  satisfies

$$\varepsilon\psi_1^{-1}(\lambda) \int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \int_0^1 h(s) ds\right) < 1.$$

Thus, we have

$$\|T_\lambda u\| \leq \psi_1^{-1}(\lambda) \int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) d\tau\right) \varepsilon \|u\| < \|u\| \quad \text{for } u \in \partial\Omega_{r_3}.$$

It follows from Lemma 2.3 that

$$i(T_\lambda, \Omega_{r_1}, K) = 0, \quad i(T_\lambda, \Omega_{r_2}, K) = 1 \quad \text{and} \quad i(T_\lambda, \Omega_{r_3}, K) = 1.$$

Thus,  $i(T_\lambda, \Omega_{r_1} \setminus \bar{\Omega}_{r_2}, K) = -1$  and  $i(T_\lambda, \Omega_{r_3} \setminus \bar{\Omega}_{r_1}, K) = 1$ . Hence,  $T_\lambda$  has a fixed point in  $\Omega_{r_1} \setminus \bar{\Omega}_{r_2}$  or  $\Omega_{r_3} \setminus \bar{\Omega}_{r_1}$  according to  $f_0 = 0$  or  $f_\infty = 0$ , respectively. Consequently, (2.3)-(2.4) has a positive solution for  $\lambda > \lambda_0$ .

Part (b). Choose a number  $r_1 > 0$ . By Lemma 2.11 we infer that there exists a  $\lambda_0 > 0$  such that

$$\|T_\lambda u\| < \|u\|, \text{ for } u \in \partial\Omega_{r_1}, 0 < \lambda < \lambda_0.$$

If  $f_0 = \infty$ , there is a  $0 < r_2 < r_1$  such that  $f(u) \geq \psi_2(\eta)\varphi(u)$  for  $0 \leq u \leq r_2$ , where  $\eta > 0$  is chosen so that

$$\psi_2^{-1}(\lambda)\Gamma\eta > 1.$$

Then

$$f(u(t)) \geq \psi_2(\eta)\varphi(u(t)) \geq \varphi(u(t)\eta) \text{ for } u \in \partial\Omega_{r_2}, t \in [0, 1].$$

Lemma 2.7 implies that

$$\|T_\lambda u\| \geq \psi_2^{-1}(\lambda)\Gamma\eta\|u\| > \|u\| \text{ for } u \in \partial\Omega_{r_2}.$$

If  $f_\infty = \infty$ , there is an  $\hat{H} > 0$  such that  $f(u) \geq \psi_2(\eta)\varphi(u)$  for  $u \geq \hat{H}$ , where  $\eta > 0$  is chosen so that

$$\psi_2^{-1}(\lambda)\Gamma\eta > 1.$$

Let  $r_3 = \max\{2r_1, \frac{\hat{H}}{\rho}\}$ . If  $u \in \partial\Omega_{r_3}$ , then

$$\min_{\frac{1}{4} \leq t \leq \frac{3}{4}} u(t) \geq \rho\|u\| \geq \hat{H},$$

and hence,

$$f(u(t)) \geq \psi_2(\eta)\varphi(u(t)) \geq \varphi(u(t)\eta) \text{ for } t \in [\frac{1}{4}, \frac{3}{4}].$$

It follows from Lemma 2.7 that

$$\|T_\lambda u\| \geq \psi_2^{-1}(\lambda)\Gamma\eta\|u\| > \|u\| \text{ for } u \in \partial\Omega_{r_3}.$$

It follows from Lemma 2.3 that

$$i(T_\lambda, \Omega_{r_1}, K) = 1, \quad i(T_\lambda, \Omega_{r_2}, K) = 0 \quad \text{and} \quad i(T_\lambda, \Omega_{r_3}, K) = 0,$$

and hence,  $i(T_\lambda, \Omega_{r_1} \setminus \bar{\Omega}_{r_2}, K) = 1$  and  $i(T_\lambda, \Omega_{r_3} \setminus \bar{\Omega}_{r_1}, K) = -1$ . Thus,  $T_\lambda$  has a fixed point in  $\Omega_{r_1} \setminus \bar{\Omega}_{r_2}$  or  $\Omega_{r_3} \setminus \bar{\Omega}_{r_1}$  according to  $f_0 = \infty$  or  $f_\infty = \infty$ , respectively. Consequently, (2.3)-(2.4) has a positive solution for  $0 < \lambda < \lambda_0$ .

Part (c). Choose two numbers  $0 < r_3 < r_4$ . By Lemma 2.10 we infer that there exists a  $\lambda_0 > 0$  such that

$$\|T_\lambda u\| > \|u\|, \text{ for } u \in \partial\Omega_{r_i}, \lambda > \lambda_0, (i = 3, 4).$$

Since  $f_0 = 0$  and  $f_\infty = 0$ , it follows from the proof of Theorem 2.2 (a) that we can choose  $r_1 < r_3/2$  and  $r_2 > 2r_4$  such that

$$\|T_\lambda u\| < \|u\| \text{ for } u \in \partial\Omega_{r_i}, (i = 1, 2).$$

It follows from Lemma 2.3 that

$$\begin{aligned} i(T_\lambda, \Omega_{r_1}, K) &= 1, & i(T_\lambda, \Omega_{r_2}, K) &= 1, \\ i(T_\lambda, \Omega_{r_3}, K) &= 0, & i(T_\lambda, \Omega_{r_4}, K) &= 0 \end{aligned}$$

and hence,  $i(T_\lambda, \Omega_{r_3} \setminus \bar{\Omega}_{r_1}, K) = -1$  and  $i(T_\lambda, \Omega_{r_2} \setminus \bar{\Omega}_{r_4}, K) = 1$ . Thus,  $T_\lambda$  has two fixed points  $u_1(t)$  and  $u_2(t)$  such that  $u_1(t) \in \Omega_{r_3} \setminus \bar{\Omega}_{r_1}$  and  $u_2(t) \in \Omega_{r_2} \setminus \bar{\Omega}_{r_4}$ , which are the desired distinct positive solutions of (2.3)-(2.4) for  $\lambda > \lambda_0$  satisfying

$$r_1 < \|u_1\| < r_3 < r_4 < \|u_2\| < r_2.$$

Part (d). Choose two numbers  $0 < r_3 < r_4$ . By Lemma 2.11 we infer that there exists a  $\lambda_0 > 0$  such that

$$\|T_\lambda u\| < \|u\|, \quad \text{for } u \in \partial\Omega_{r_i}, 0 < \lambda < \lambda_0, (i = 3, 4).$$

Since  $f_0 = \infty$  and  $f_\infty = \infty$ , it follows from the proof of Theorem 2.2 (b) that we can choose  $r_1 < r_3/2$  and  $r_2 > 2r_4$  such that

$$\|T_\lambda u\| > \|u\| \quad \text{for } u \in \partial\Omega_{r_i}, \quad (i = 1, 2).$$

It follows from Lemma 2.3 that

$$\begin{aligned} i(T_\lambda, \Omega_{r_1}, K) &= 0, & i(T_\lambda, \Omega_{r_2}, K) &= 0, \\ i(T_\lambda, \Omega_{r_3}, K) &= 1, & i(T_\lambda, \Omega_{r_4}, K) &= 1 \end{aligned}$$

and hence,  $i(T_\lambda, \Omega_{r_3} \setminus \bar{\Omega}_{r_1}, K) = 1$  and  $i(T_\lambda, \Omega_{r_2} \setminus \bar{\Omega}_{r_4}, K) = -1$ . Thus,  $T_\lambda$  has two fixed points  $u_1(t)$  and  $u_2(t)$  such that  $u_1(t) \in \Omega_{r_3} \setminus \bar{\Omega}_{r_1}$  and  $u_2(t) \in \Omega_{r_2} \setminus \bar{\Omega}_{r_4}$ , which are the desired distinct positive solutions of (2.3)-(2.4) for  $0 < \lambda < \lambda_0$  satisfying

$$r_1 < \|u_1\| < r_3 < r_4 < \|u_2\| < r_2.$$

Part (e) Since  $f_0 < \infty$  and  $f_\infty < \infty$ , there exist positive numbers  $\varepsilon_1, \varepsilon_2, r_1$  and  $r_2$  such that  $r_1 < r_2$  and

$$\begin{aligned} f(u) &\leq \varepsilon_1 \varphi(u) \quad \text{for } u \in [0, r_1], \\ f(u) &\leq \varepsilon_2 \varphi(u) \quad \text{for } u \in [r_2, \infty). \end{aligned}$$

Let  $\varepsilon_3 := \max\{\varepsilon_1, \varepsilon_2, \max_{r_1 \leq u \leq r_2} \{\frac{f(u)}{\varphi(u)}\}\} > 0$ . Thus, we have

$$f(u) \leq \varepsilon_3 \varphi(u) \quad \text{for } u \in [0, \infty).$$

Assume  $v(t)$  is a positive solution of (2.3)-(2.4). We will show that this leads to a contradiction for  $0 < \lambda < \lambda_0 := \psi_1\left(\frac{1}{\int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\varepsilon_3 \frac{1}{q(0)} \int_0^1 h(\tau) d\tau\right)}\right)$ . Since  $T_\lambda v(t) = v(t)$  for  $t \in [0, 1]$ ,

$$\begin{aligned} \|v\| &= \|T_\lambda v\| \leq \int_0^1 \frac{1}{p(s)} \varphi^{-1}\left(\frac{1}{q(0)} \lambda \int_0^1 h(\tau) f(v(\tau)) d\tau\right) ds \\ &\leq \int_0^1 \frac{1}{p(s)} ds \varphi^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) \varepsilon_3 d\tau \psi_1(\psi_1^{-1}(\lambda)) \varphi(\|v\|)\right) \\ &\leq \int_0^1 \frac{1}{p(s)} ds \varphi^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) \varepsilon_3 d\tau \varphi(\psi_1^{-1}(\lambda) \|v\|)\right) \\ &\leq \int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \varepsilon_3 \int_0^1 h(\tau) d\tau\right) \psi_1^{-1}(\lambda) \|v\| < \|v\|, \end{aligned}$$

which is a contradiction.

Part (f). Since  $f_0 > 0$  and  $f_\infty > 0$ , it follows that there exist positive numbers  $\eta_1, \eta_2, r_1$  and  $r_2$  such that  $r_1 < r_2$  and

$$f(u) \geq \eta_1 \varphi(u) \text{ for } u \in [0, r_1],$$

$$f(u) \geq \eta_2 \varphi(u) \text{ for } u \in [r_2, \infty).$$

Let  $\eta_3 := \min\{\eta_1, \eta_2, \min_{r_1 \leq u \leq r_2} \left\{\frac{f(u)}{\varphi(u)}\right\}\} > 0$ . Thus, we have

$$f(u) \geq \eta_3 \varphi(u) \text{ for } u \in [0, \infty).$$

Since  $\eta_3 \varphi(u) = \psi_2(\psi_2^{-1}(\eta_3)) \varphi(u)$ , (H1) implies that

$$f(u) \geq \eta_3 \varphi(u) \geq \varphi(\psi_2^{-1}(\eta_3) u) \text{ for } u \in [0, \infty).$$

Assume  $v(t)$  is a positive solution of (2.3)-(2.4). We will show that this leads to a contradiction for  $\lambda > \lambda_0 := \psi_2\left(\frac{1}{\Gamma \psi_2^{-1}(\eta_3)}\right)$ . Since  $T_\lambda v(t) = v(t)$  for  $t \in [0, 1]$ , it follows from Lemma 2.7 that

$$\|v\| = \|T_\lambda v\| \geq \psi_2^{-1}(\lambda) \Gamma \psi_2^{-1}(\eta_3) \|v\| > \|v\|,$$

which is a contradiction.

Part (g). If

$$\psi_2\left(\frac{1}{\Gamma \psi_2^{-1}(f_0)}\right) < \lambda < \psi_1\left(\frac{1}{\int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) d\tau\right) \psi_1^{-1}(f_\infty)}\right),$$

there exists an  $0 < \varepsilon < f_0$  such that

$$\psi_2\left(\frac{1}{\Gamma \psi_2^{-1}(f_0 - \varepsilon)}\right) < \lambda < \psi_1\left(\frac{1}{\int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) d\tau\right) \psi_1^{-1}(f_\infty + \varepsilon)}\right).$$

Beginning with  $f_0$ , there is a  $r_1 > 0$  such that  $f(u) \geq (f_0 - \varepsilon)\varphi(u)$  for  $0 \leq u \leq r_1$ . Note that  $(f_0 - \varepsilon)\varphi(u) = \psi_2(\psi_2^{-1}(f_0 - \varepsilon))\varphi(u)$ . If  $u \in \partial\Omega_{r_1}$ , then

$$f(u(t)) \geq \psi_2(\psi_2^{-1}(f_0 - \varepsilon))\varphi(u(t)) \geq \varphi(u(t)\psi_2^{-1}(f_0 - \varepsilon)) \quad \text{for } t \in [0, 1].$$

Lemma 2.7 implies that

$$\|T_\lambda u\| \geq \psi_2^{-1}(\lambda)\Gamma\psi_2^{-1}(f_0 - \varepsilon)\|u\| > \|u\| \quad \text{for } u \in \partial\Omega_{r_1}.$$

It remains to consider  $f_\infty$ . It follows from Lemma 2.8 that  $\lim_{u \rightarrow \infty} \frac{f^*(u)}{\varphi(u)} = f_\infty$ . Therefore, there is a  $r_2 > 2r_1$  such that

$$f^*(r_2) \leq (f_\infty + \varepsilon)\varphi(r_2) = \psi_1(\psi_1^{-1}(f_\infty + \varepsilon))\varphi(r_2).$$

Lemma 2.9 implies that, for  $u \in \partial\Omega_{r_2}$ , we have

$$\|T_\lambda u\| \leq \psi_1^{-1}(\lambda) \int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) d\tau\right) \psi_1^{-1}(f_\infty + \varepsilon)\|u\| < \|u\|.$$

It follows from Lemma 2.3 that

$$i(T_\lambda, \Omega_{r_1}, K) = 0 \quad \text{and} \quad i(T_\lambda, \Omega_{r_2}, K) = 1.$$

Hence,  $i(T_\lambda, \Omega_{r_2} \setminus \bar{\Omega}_{r_1}, K) = 1$ . Thus,  $T_\lambda$  has a fixed point in  $\Omega_{r_2} \setminus \bar{\Omega}_{r_1}$ , which is the desired positive solution of (2.3)-(2.4).

If

$$\psi_2\left(\frac{1}{\Gamma\psi_2^{-1}(f_\infty)}\right) < \lambda < \psi_1\left(\frac{1}{\int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) d\tau\right) \psi_1^{-1}(f_0)}\right),$$

there exists an  $0 < \varepsilon < f_\infty$  such that

$$\psi_2\left(\frac{1}{\Gamma\psi_2^{-1}(f_\infty - \varepsilon)}\right) < \lambda < \psi_1\left(\frac{1}{\int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) d\tau\right) \psi_1^{-1}(f_0 + \varepsilon)}\right).$$

Since  $f_0^* = f_0$ , there exists a  $r_3 > 0$  such that  $f^*(r_3) \leq (f_0 + \varepsilon)\varphi(r_3)$ . Lemma 2.9 implies that

$$\|T_\lambda u\| \leq \psi_1^{-1}(\lambda) \int_0^1 \frac{1}{p(s)} ds \psi_1^{-1}\left(\frac{1}{q(0)} \int_0^1 h(\tau) d\tau\right) \psi_1^{-1}(f_0 + \varepsilon)\|u\| < \|u\|$$

for  $u \in \partial\Omega_{r_3}$ . Next, considering  $f_\infty$ , there is an  $\hat{H} > 0$  such that  $f(u) \geq (f_\infty - \varepsilon)\varphi(u)$  for  $u \geq \hat{H}$ . Let  $r_4 = \max\{2r_3, \frac{\hat{H}}{\rho}\}$ . If  $u \in \partial\Omega_{r_4}$ , then

$$\min_{\frac{1}{4} \leq t \leq \frac{3}{4}} u(t) \geq \rho\|u\| \geq \hat{H}$$



and hence,

$$f(u(t)) \geq (f_\infty - \varepsilon)\varphi(u(t)) \geq \varphi(u(t))\psi_2^{-1}(f_\infty - \varepsilon) \quad \text{for } t \in \left[\frac{1}{4}, \frac{3}{4}\right].$$

Lemma 2.7 implies that

$$\|T_\lambda u\| \geq \psi_2^{-1}(\lambda)\Gamma\psi_2^{-1}(f_\infty - \varepsilon)\|u\| > \|u\| \quad \text{for } u \in \partial\Omega_{r_4}.$$

Again it follows from Lemma 2.3 that

$$i(T_\lambda, \Omega_{r_3}, K) = 1 \quad \text{and} \quad i(T_\lambda, \Omega_{r_4}, K) = 0.$$

Hence,  $i(T_\lambda, \Omega_{r_4} \setminus \bar{\Omega}_{r_3}, K) = -1$ . Thus,  $T_\lambda$  has a fixed point in  $\Omega_{r_4} \setminus \bar{\Omega}_{r_3}$ , which is the desired positive solution of (2.3)-(2.4).  $\square$

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