

9. AUTOCORRELATION

[1] Definition of Autocorrelation (AUTO)

1) Model: $y_t = x_{t\bullet}'\beta + \varepsilon_t$.

- We say that AUTO exists if $\text{cov}(\varepsilon_t, \varepsilon_s) \neq 0$, $t \neq s$.

2) Assumptions:

- All of SIC except SIC.3 (the random sample assumption).
- Or, all of WIC except WIC.2 [$E(\varepsilon_t | \varepsilon_1, \dots, \varepsilon_{t-1}, x_{1\bullet}, \dots, x_{t\bullet}) = 0$].

Replace WIC.2 by $E(\varepsilon_t | x_{1\bullet}, \dots, x_{T\bullet}) = 0$ (strictly exogenous regressors).

Comments:

For OLS, the assumption of weakly exogenous regressors is enough.
However, for GLS, we need the assumption of strictly exogenous regressors (that is, $E(\varepsilon_t | x_{T\bullet}, x_{T-1,\bullet}, \dots, x_{1\bullet}) = 0$ for all t).

3) Example:

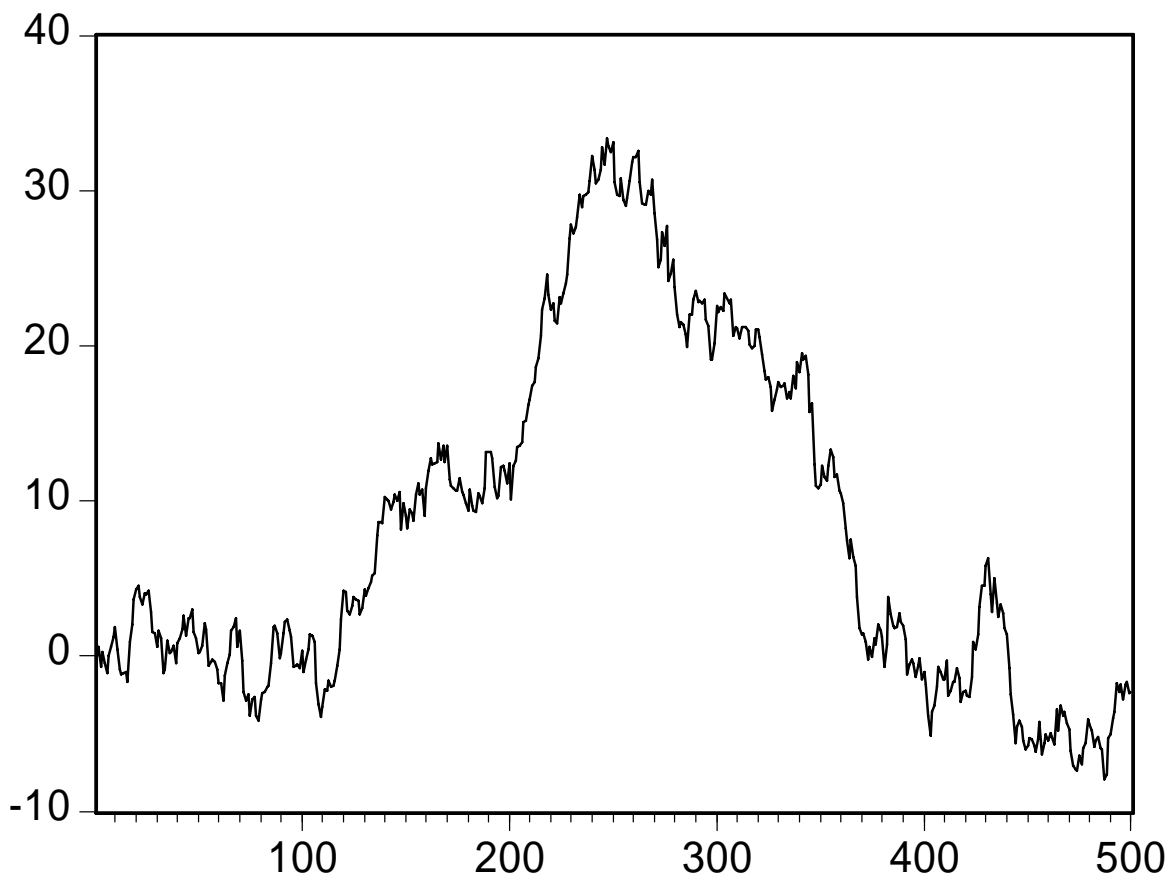
- AR(1): $\varepsilon_t = \rho\varepsilon_{t-1} + v_t$, v_t iid $N(0, \sigma_v^2)$.

$$\rightarrow \text{cov}(\varepsilon_t, \varepsilon_{t-1}) = E(\varepsilon_t \varepsilon_{t-1}) = E[(\rho\varepsilon_{t-1} + v_t)\varepsilon_{t-1}] = \rho E(\varepsilon_{t-1}^2) \neq 0.$$

- MA(1): $\varepsilon_t = v_t + \psi v_{t-1}$, v_t iid $N(0, \sigma_v^2)$.

$$\rightarrow \text{cov}(\varepsilon_t, \varepsilon_{t-1}) = E(\varepsilon_t \varepsilon_{t-1}) = E[(v_t + \psi v_{t-1})(v_{t-1} + \psi v_{t-2})]$$

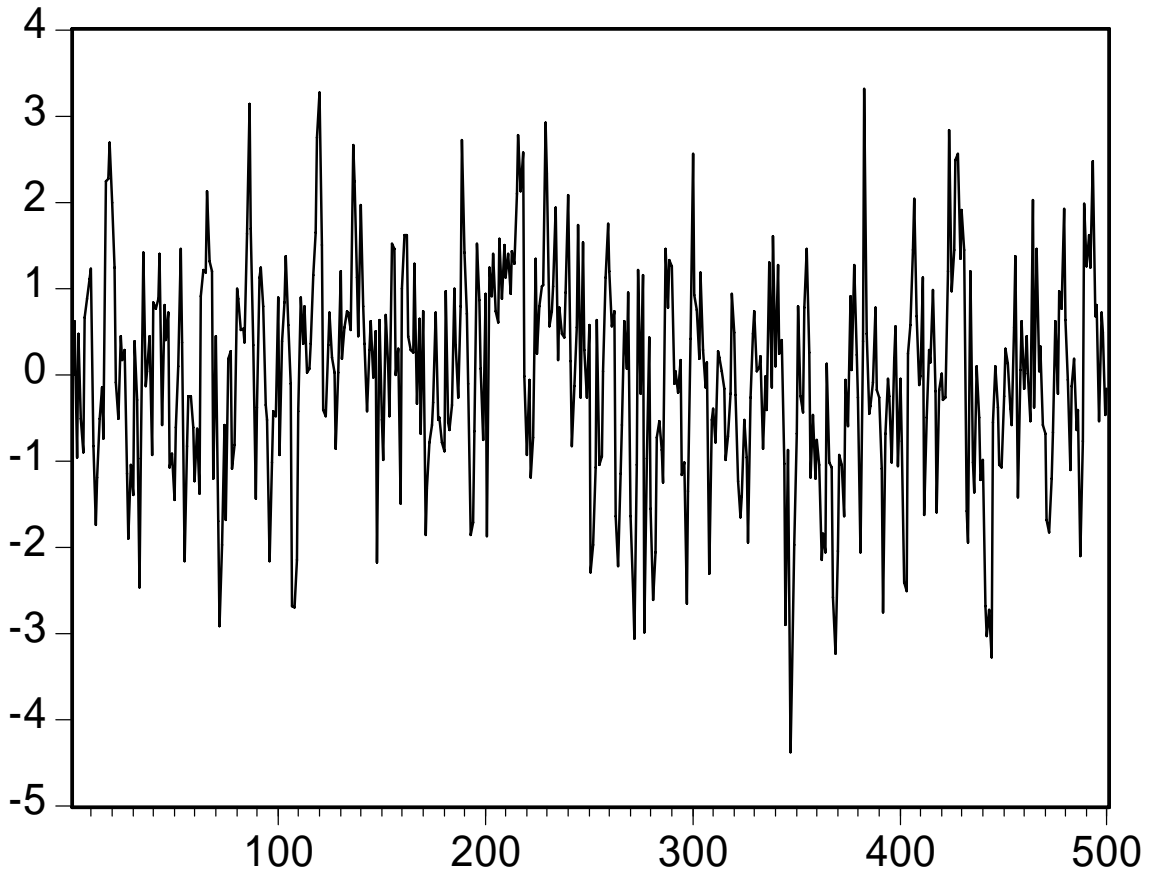
$$= \psi E(v_{t-1}^2) = \psi \sigma_v^2 \neq 0.$$



— E1

$$\varepsilon_t = \varepsilon_{t-1} + v_t, \sigma_v^2 = 1.$$

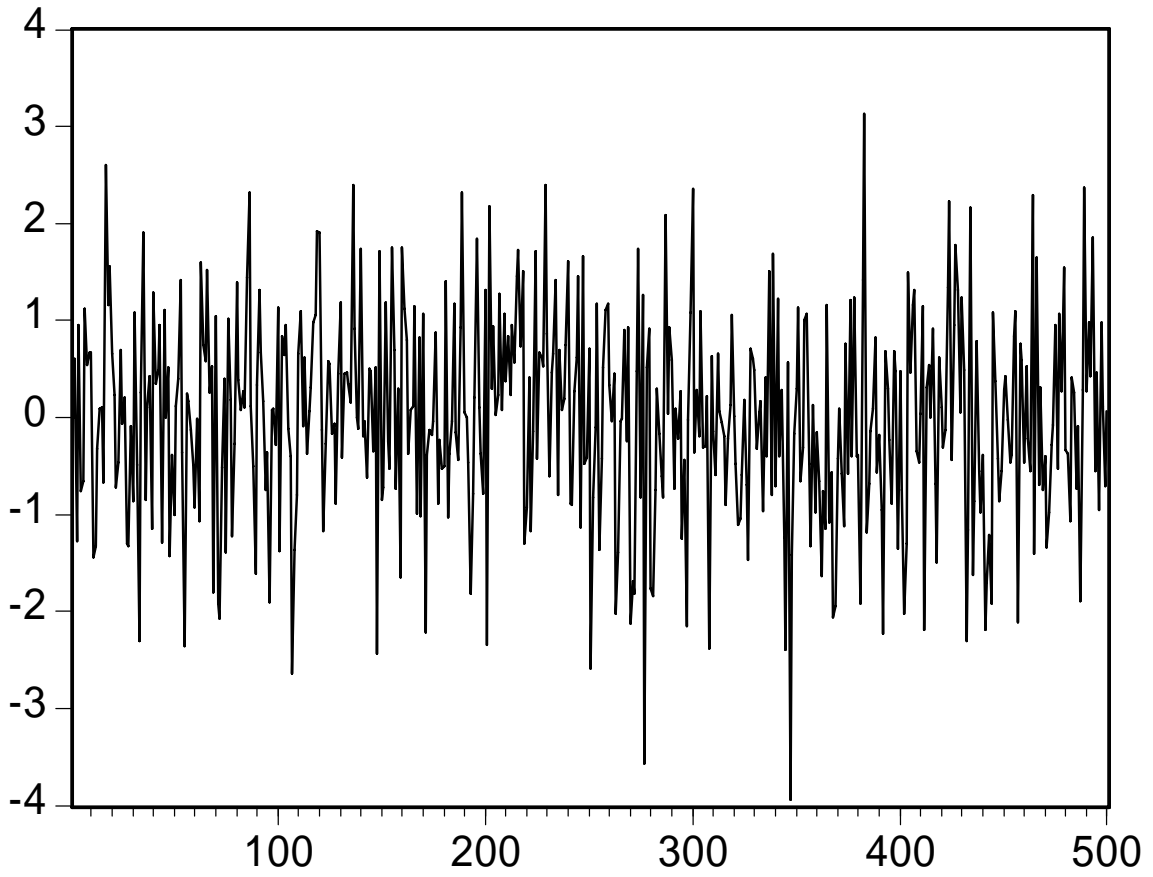
AUTO-2



— E2

$$\varepsilon_t = 0.5\varepsilon_{t-1} + v_t.$$

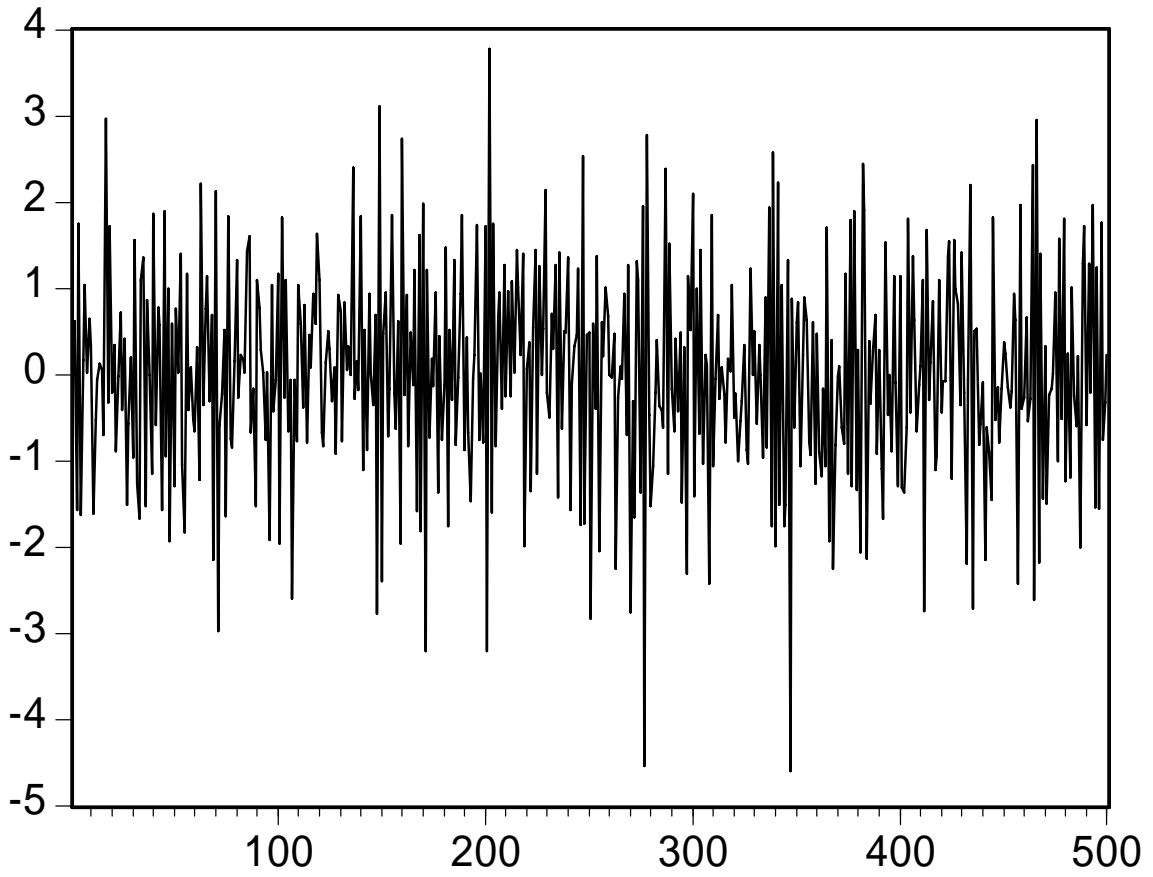
AUTO-3



— E3

$$\varepsilon_t = v_t$$

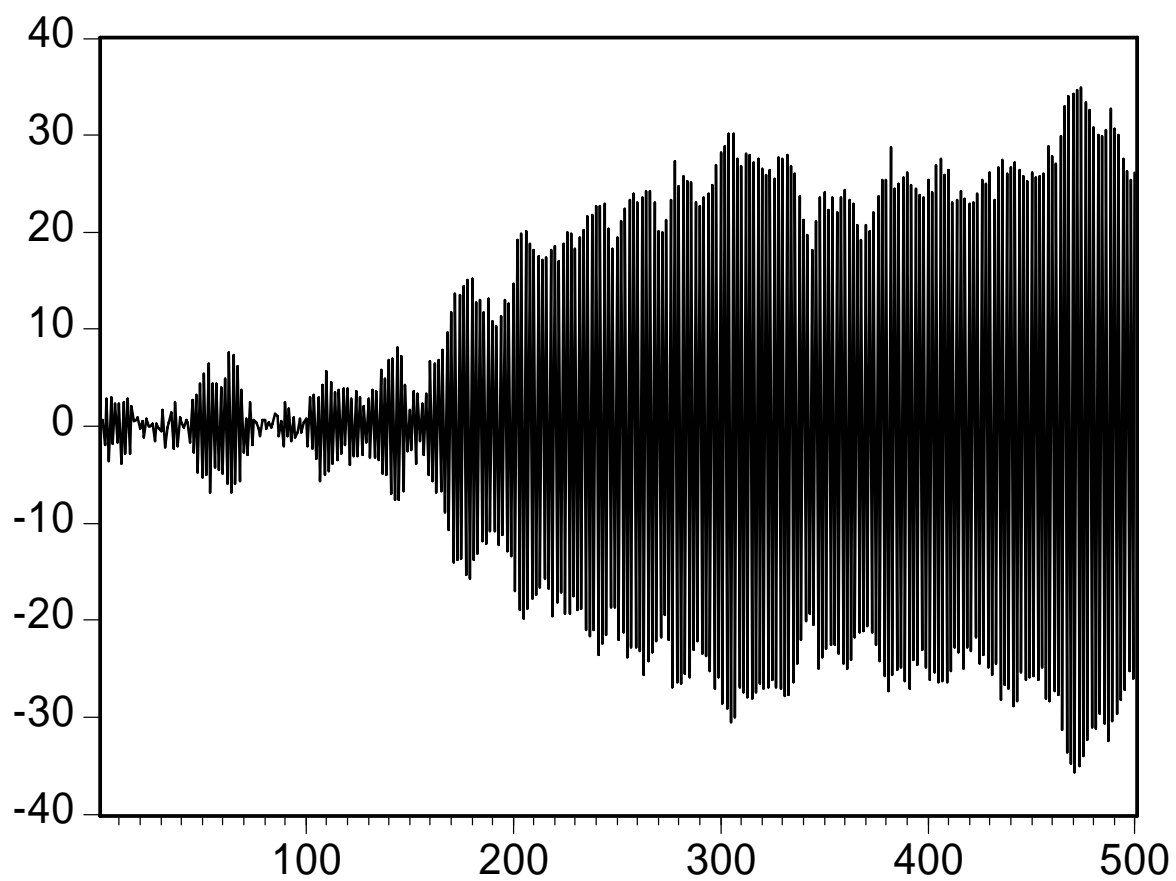
AUTO-4



— E4

$$\varepsilon_t = -0.5\varepsilon_{t-1} + v_t$$

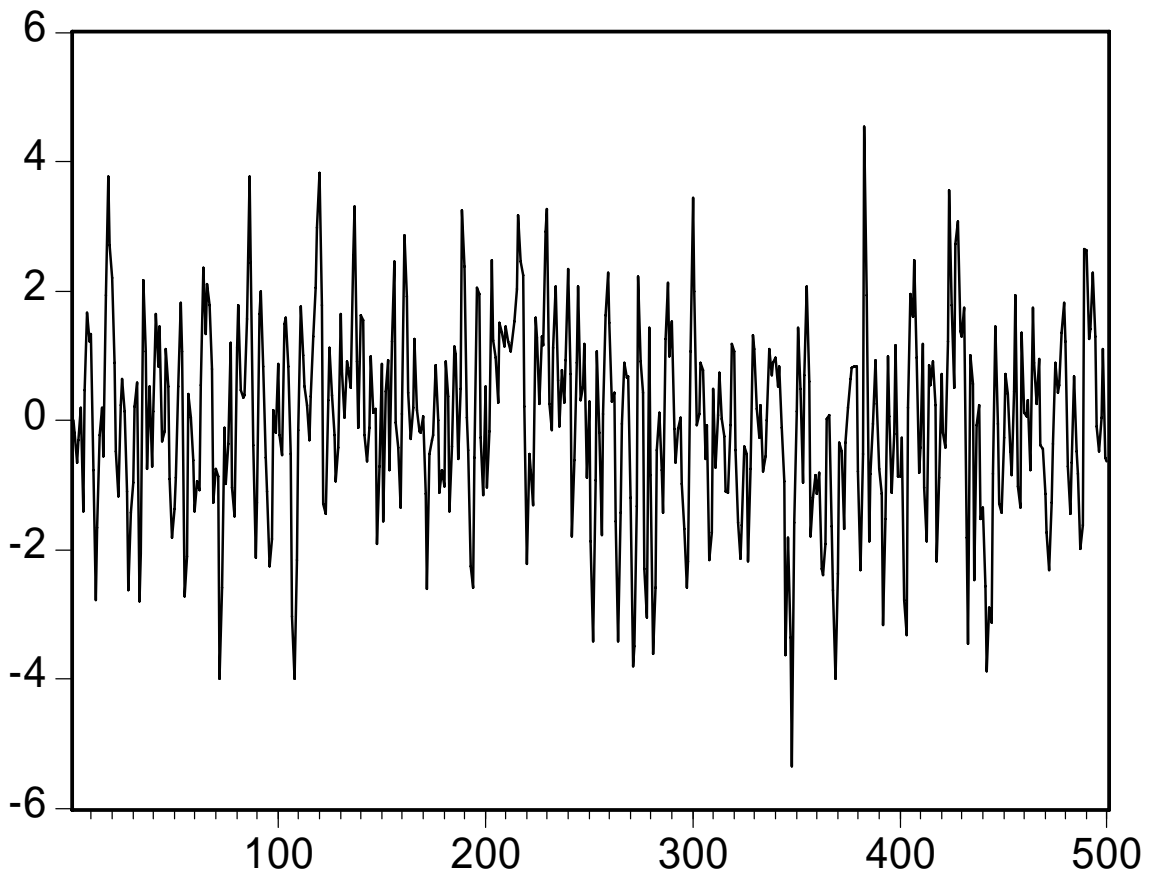
AUTO-5



— E5

$$\varepsilon_t = -\varepsilon_t + v_t$$

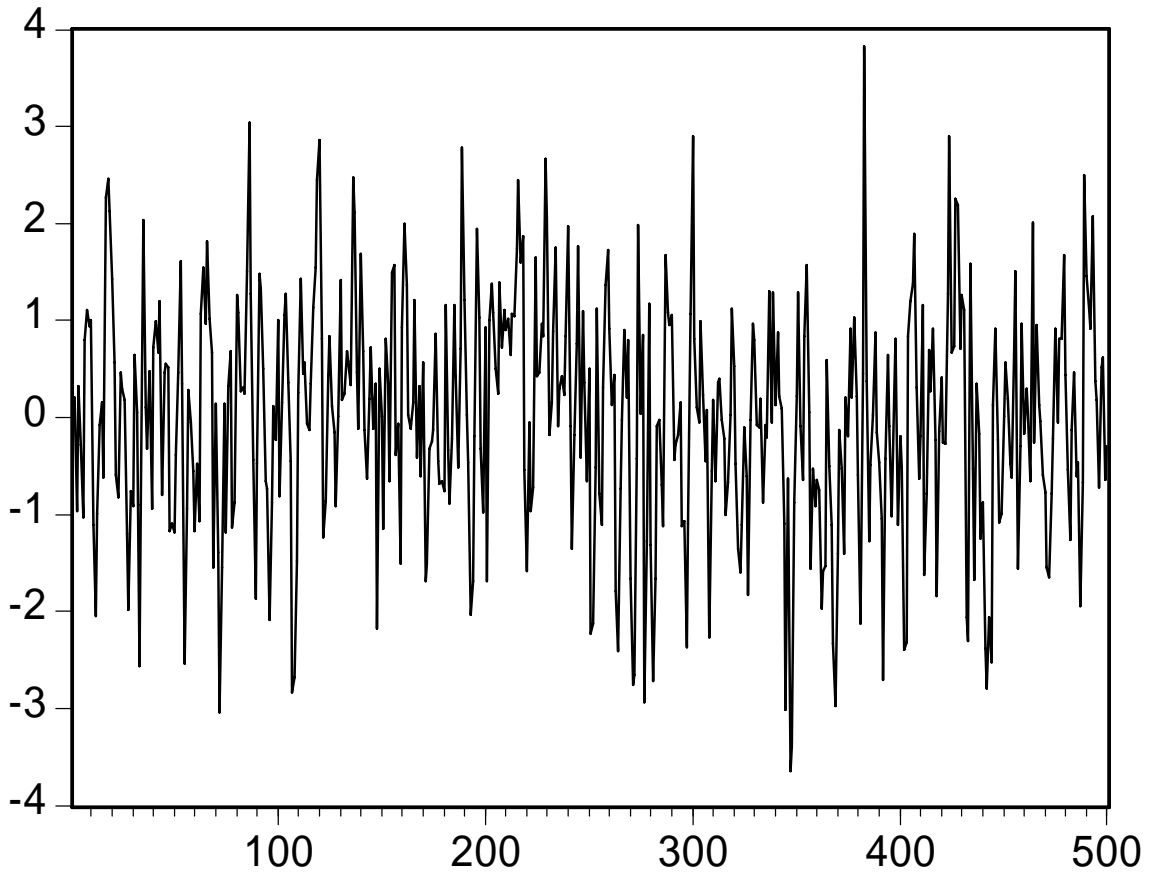
AUTO-6



— E6

$$\varepsilon_t = v_t + v_{t-1}$$

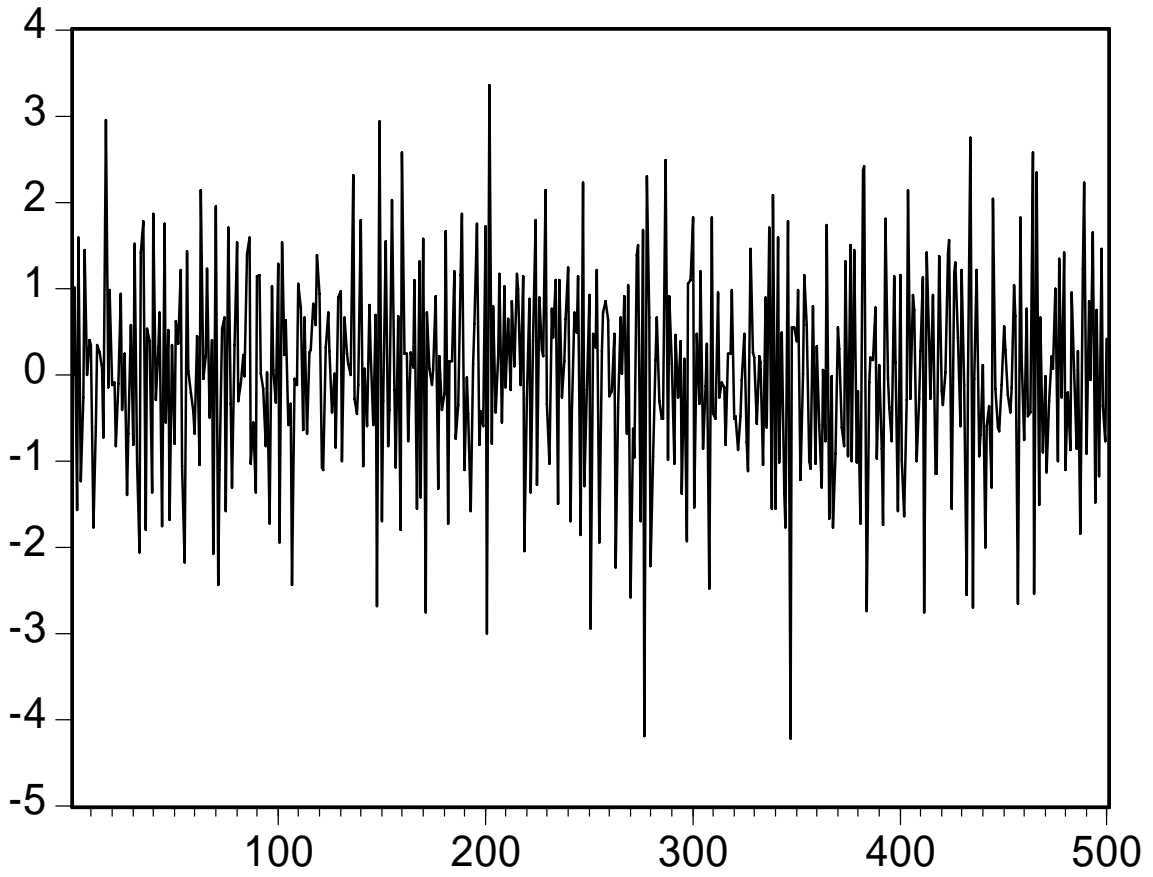
AUTO-7



— E7

$$\varepsilon_t = v_t + 0.5v_{t-1}$$

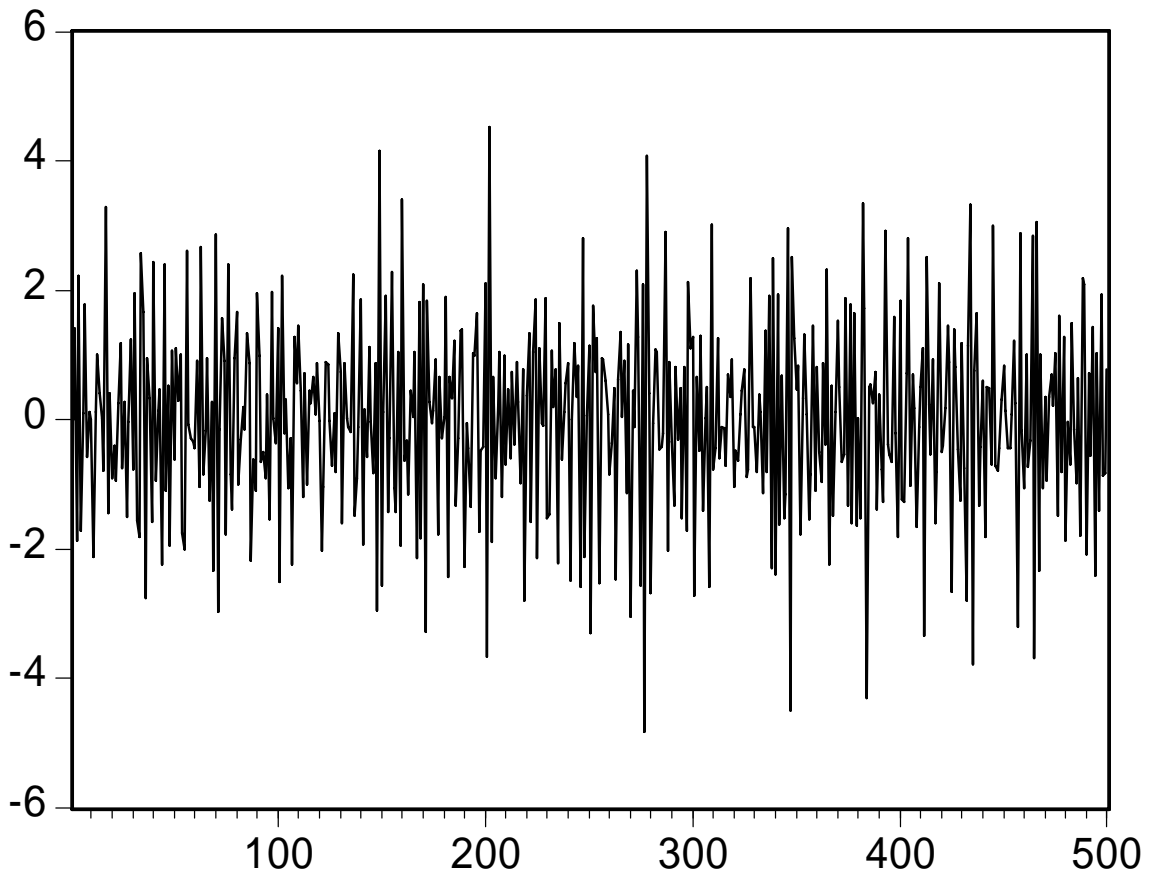
AUTO-8



— E8

$$\varepsilon_t = v_t - 0.5v_{t-1}.$$

AUTO-9



— E9

$$\varepsilon_t = v_t - v_{t-1}.$$

AUTO-10

4) Typical in time-series data:

- i) Presence of unobservable variables.
- ii) Seasonally adjusted data.

Empirical Example: Expectations-Augmented Phillips curve:

- Data: (Table F5.1 – from Greene)
 - From 1950I to 2000II.
 - For data descriptions, see p. 948.
 - INFL: Annualized inflation rate (%).
 - UNEMP: Unemployment rate (%).

- Expectation-Augmented Phillips curve:

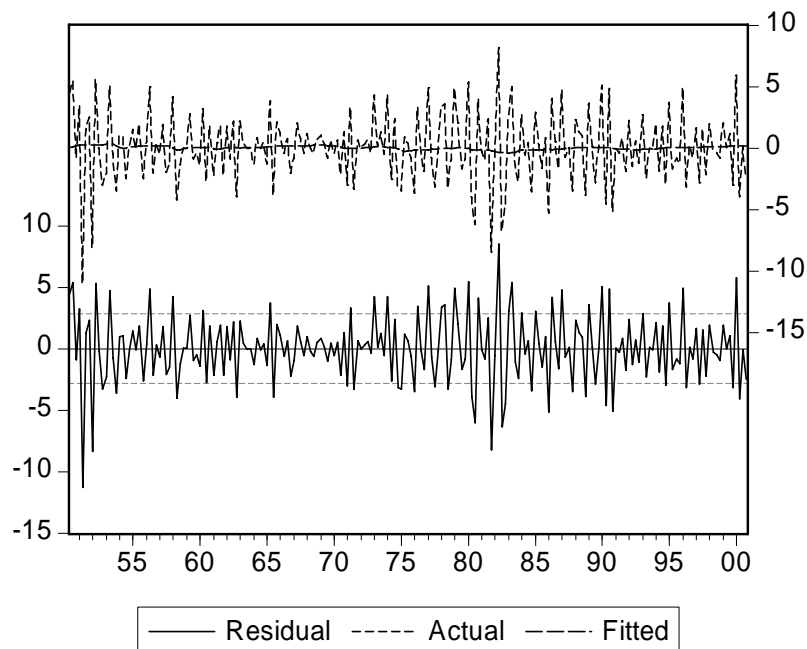
$$INFL_t - INFL_{t-1} = \beta_1 + \beta_2 UNEMP_t + \varepsilon_t,$$

where $\beta_1 = -\beta_2 u^*$ and u^* is the natural unemployment rate.

Dependent Variable: INFL-INFL(-1)
 Method: Least Squares
 Date: 04/22/03 Time: 17:03
 Sample(adjusted): 1950:2 2000:4
 Included observations: 203 after adjusting endpoints

Variable	Coefficient	Std. Error	t-Statistic	Prob.
C	0.517770	0.743156	0.696717	0.4868
UNEMP	-0.090768	0.126270	-0.718842	0.4731

R-squared	0.002564	Mean dependent var	0.003028
Adjusted R-squared	-0.002398	S.D. dependent var	2.829120
S.E. of regression	2.832510	Akaike info criterion	4.930007
Sum squared resid	1612.646	Schwarz criterion	4.962649
Log likelihood	-498.3957	F-statistic	0.516733
Durbin-Watson stat	2.792357	Prob(F-statistic)	0.473073



AUTO-12

[2] Stationarity Assumption on ε_t

(1) Stationarity and Ergodicity

- Let $\{s_t\}$ be a process of interest.
- Notation:
 - $E(s_t) \equiv \mu_t$; $\text{var}(s_t) \equiv \gamma_{0t}$; $\text{cov}(s_t, s_{t-j}) \equiv \gamma_{jt}$ [Autocovariance]
- Definition of Covariance (weak) Stationarity:
 - $\{s_t\}$ is called covariance-stationary (CS) iff
 $\mu_t = \mu$ (finite) for all t and $\gamma_{jt} = \gamma_j$ (finite) for all t .
[e.g., $\text{cov}(s_5, s_3) = \text{cov}(s_4, s_2) = \gamma_2$]
- Rough Definition of Ergodicity: $\gamma_{jt} \rightarrow 0$ as $j \rightarrow \infty$.
- Ergodicity is needed for CLT and LLN.

(2) Stationarity Assumption on ε_t in $y_t = x_t \beta + \varepsilon_t$:

- $E(\varepsilon_t) = 0$, for all t .
- $\text{var}(\varepsilon_t) = \sigma_\varepsilon^2$, for all t .
- $\text{cov}(\varepsilon_t, \varepsilon_{t-j}) = \gamma_{tj} = \gamma_j$, for all t .
- $\gamma_j \rightarrow 0$ as $j \rightarrow \infty$.

[3] Properties of OLS

(1) Autocorrelation:

$$\rho_j = \gamma_j / \gamma_0 = \gamma_j / \text{var}(\varepsilon_t).$$

(2) Autocorrelation Matrix under the stationarity assumption:

$$\bullet R = \begin{pmatrix} 1 & \rho_1 & \rho_2 & \rho_3 & \dots & \rho_{T-1} \\ \rho_1 & 1 & \rho_1 & \rho_2 & \dots & \rho_{T-2} \\ \rho_2 & \rho_1 & 1 & \rho_1 & \dots & \rho_{T-3} \\ \rho_3 & \rho_2 & \rho_1 & 1 & \dots & \rho_{T-4} \\ \vdots & \vdots & \vdots & \vdots & & \vdots \\ \rho_{T-1} & \rho_{T-2} & \rho_{T-3} & \rho_{T-4} & \dots & 1 \end{pmatrix}.$$

- Let $\sigma^2 = \text{var}(\varepsilon_t) \equiv \gamma_0$.
- $\text{Cov}(\varepsilon) = \sigma^2 \Omega = \sigma^2 R$.

Theorem:

The OLS estimator $\hat{\beta}$ is unbiased (and consistent). But it is inefficient.

Theorem:

$$\text{Cov}(\hat{\beta}) = (X'X)^{-1} X' \sigma^2 \Omega X (X'X)^{-1}.$$

Implications:

- The t and F-tests based on $s^2(X'X)^{-1}$ are all irrelevant.
- Need to estimate $\Delta = X'(\sigma^2\Omega)X$.
 - If $\hat{\Delta}$ is available, a consistent estimate of $Cov(\hat{\beta})$ is $(XX)^{-1}\hat{\Delta}(XX)^{-1}$.
- Using this estimate, we can compute t and Wald statistics.

(3) Nonparametric Estimation of $X'(\sigma^2\Omega)X$.

- Definitions:
 - Let $e_t =$ OLS residuals; and $g_t = e_t x_t$.

- Define: $S_0 = \frac{1}{T} \sum_t g_t g_t'$;

$$S_j = \frac{1}{T} \sum_{t=j+1}^T g_t g_{t-j}';$$

$$\hat{\Delta} = T \left(S_0 + \sum_{i=1}^q k \left(\frac{i}{q+1} \right) (S_j + S_j') \right),$$

where q is called bandwidth and $k(\bullet)$ is a kernel function.

- Can also control for heteroskedasticity.

- Choice of q ?
 - If we believe that $\rho_j = 0$ for $j > \tau$ [it happens if ε_t follows $MA(\tau)$], choose $q = \tau$ or more.
 - If don't know? Choose q such that $q \rightarrow \infty$ and $q/T \rightarrow 0$, as $T \rightarrow \infty$.
- Newey-West Method (1987, ECON)
 - Use Bartlett's kernel, $k(z) = 1 - z$.
 - Choose $q = T^{1/5}$ or $q = T^{2/9}$ (same for other methods) so that $q/T^{1/4} \rightarrow 0$.
- Gallant Method (1987, Nonlinear Statistic Models)
 - Use Pazen kernel,

$$k(z) = 1 - 6z^2 + 6z^3 \text{ for } 0 \leq z \leq 1/2;$$

$$= 2(1-z)^3, 1/2 \leq z \leq 1 \text{ and } = 0, \text{ otherwise.}$$
- Andrews (1991, ECON)
 - Quadratic kernel:

$$k(z) = \frac{3}{(6\pi z/5)^2} \left[\frac{\sin(6\pi z/5)}{6\pi z/5} - \cos(6\pi z/5) \right].$$
 - $\hat{\Delta} = \frac{T^2}{T-p} \left[S_0 + \sum_{i=1}^{T-1} k\left(\frac{i}{q+1}\right) (S_i + S'_i) \right].$

[4] Detection of First-Order AUTO

[Testing $H_0: \rho_1 = 0$ against $H_a: \rho_1 \neq 0$ assuming $\rho_2 = \dots = 0$]

(1) Notation:

- Sample Autocovariance: $r_j = \frac{1}{T-j} \sum_{t=j+1}^T e_t e_{t-j}$.
- Sample Autocorrelation: $a_j = \frac{r_j}{r_0}$ ($-1 \leq a_j \leq 1$).

Note: Under the CS and Ergodicity assumptions,

$$r_j \rightarrow_p \gamma_j \text{ as } T \rightarrow \infty;$$

$$a_j \rightarrow_p \rho_j \text{ as } T \rightarrow \infty.$$

(2) Durbin-Watson Test (Assuming regressors are strictly exogenous)

- D-W test statistic: $DW = \frac{\sum_{t=2}^T (e_t - e_{t-1})^2}{\sum_{t=1}^T e_t^2}$.

• Intuition:

- $DW = 2(1-a_1) - \frac{e_1^2 + e_T^2}{\sum_{t=1}^T e_t^2} \approx 2(1-a_1)$.

→ If H_0 is correct, $DW \approx 2$.

→ For formal test with DW, see book.

(3) LM-type Test (Regressors need not be strictly exogenous)

STEP 1: Regress e_t on x_t and e_{t-1} , and get R^2 .

STEP 2: t-test for H_0 : the coefficient on $e_{t-1} = 0$. Or

$$T \times R^2 \rightarrow_p \chi^2(1).$$

(4) Note on these tests.

- Suppose $\rho_j \neq 0, j = 2, 3, \dots$. Then, these tests may fail to detect autocorrelation.
- Accepting $H_0: \rho_1 = 0$ does not mean that $\rho_j = 0, j = 2, 3, \dots$.

[5] Detection of Higher-Order AUTO

$$[H_0: \rho_1 = \rho_2 = \dots = \rho_m = 0]$$

(1) LM-type test.

STEP 1: Regress e_t on $x_{t\bullet}$ and e_{t-1}, \dots, e_{t-m} .

STEP 2: $LM = TR^2 \rightarrow_d \chi^2(m)$.

(2) Box-Pierce Test.

- $BP = T \sum_{j=1}^m a_j^2 \rightarrow_d \chi^2(m)$.

(3) Ljung-Box Test

- $LB = T(T+2) \sum_{j=1}^m \frac{a_j^2}{T-j} \rightarrow_d \chi^2(m)$.

[EMPIRICAL EXAMPLE]

Data: ustc96.wf1 (Quarterly data)

- FEDFRQ = Fed Fund Rate (%)
- GDP
- INF = annualized quarterly inflation rate (%)
- M1Q = M1
- M2Q = M2
- TBILLQ = treasury bill rate (%)
- GGDP = $400 \cdot \ln(\text{GDP}/\text{GDP}(-1))$:
Annualized growth rate of GDP (%)
- GM1 = $400 \cdot \text{LOG}(\text{M1Q}/\text{M1Q}(-1))$:
Annualized growth rate of M1 (%)

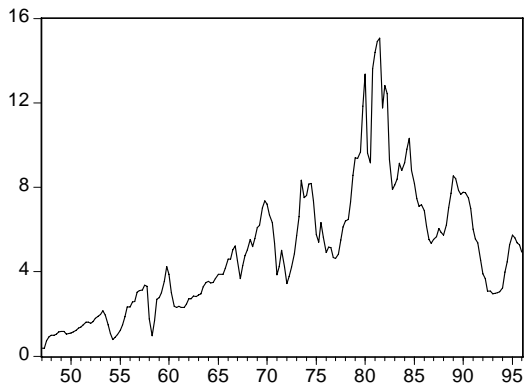
Research project:

How Fed reacts to the economy?

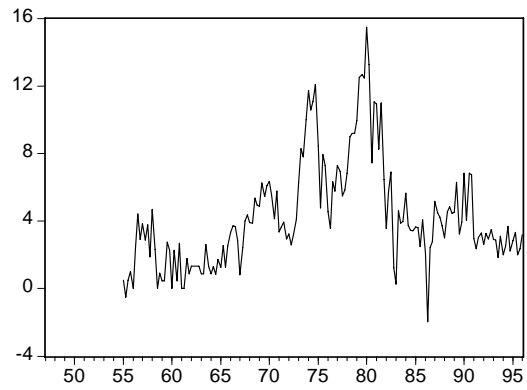
Model to estimate:

$$(\text{fedfrq} - \text{tbillq}) = \beta_1 + \beta_2 \text{ggdp}_{t-4} + \beta_3 \text{inf}_{t-1} + \varepsilon_t.$$

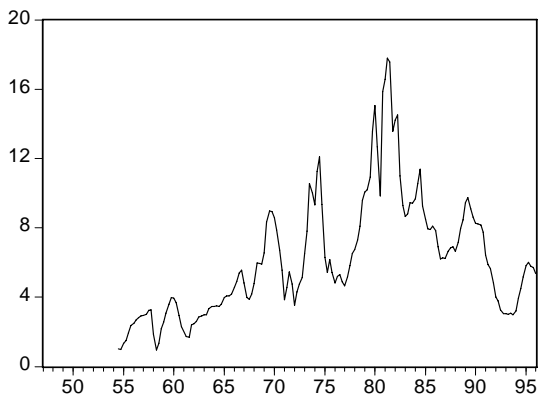
- Why $(\text{fedfrq}_t - \text{tbillq}_t)$ instead of fedfrq_t ?
The variable “fedfrq” appears to be nonstationary.
But $(\text{fedfrq} - \text{tbillq})$ is stationary.
- Why not ggdp_{t-1} , ggdp_{t-2} , ... and inf_{t-2} , inf_{t-3} ... ?
They appear to be insignificant.



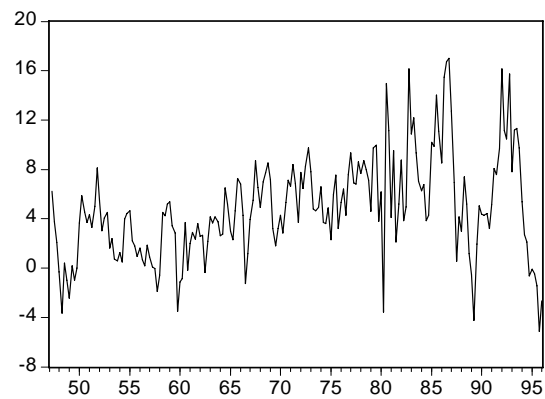
— TBILLQ



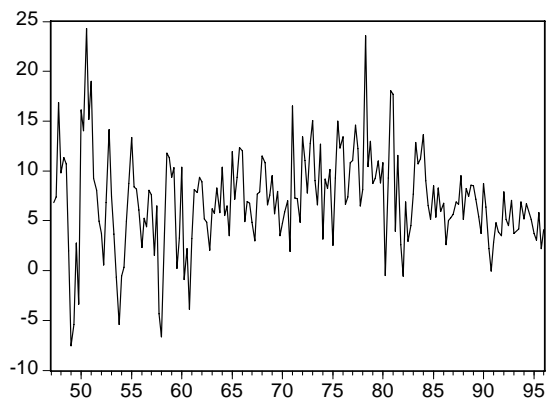
— INF



— FEDFRQ



— GM1



— GGDP

OLS Results:

Dependent Variable: DEVFEDTBILL

Method: Least Squares

Sample(adjusted): 1955:2 1996:1

Included observations: 164 after adjusting endpoints

Variable	Coefficient	Std. Error	t-Statistic	Prob.
C	-0.166704	0.097205	-1.714962	0.0883
INF(-1)	0.161085	0.015494	10.39627	0.0000
GGDP(-4)	0.004583	0.011710	0.391376	0.6960
R-squared	0.443511	Mean dependent var	0.553354	
Adjusted R-squared	0.436598	S.D. dependent var	0.775250	
S.E. of regression	0.581904	Akaike info criterion	1.773099	
Sum squared resid	54.51650	Schwarz criterion	1.829804	
Log likelihood	-142.3942	F-statistic	64.15699	
Durbin-Watson stat	0.836136	Prob(F-statistic)	0.000000	

- $DW = 0.836 \rightarrow$ Implies AUTO.

view/residual tests/serial correlation LM test

lags to include: 4

Breusch-Godfrey Serial Correlation LM Test:

F-statistic	22.08502	Probability	0.000000
Obs*R-squared	59.05181	Probability	0.000000

Test Equation:

Dependent Variable: RESID

Method: Least Squares

Date: 04/16/02 Time: 15:42

Presample missing value lagged residuals set to zero.

Variable	Coefficient	Std. Error	t-Statistic	Prob.
C	0.089264	0.080027	1.115428	0.2664
INF(-1)	-0.013771	0.012714	-1.083200	0.2804
GGDP(-4)	-0.004093	0.009658	-0.423734	0.6723
RESID(-1)	0.547954	0.080008	6.848755	0.0000
RESID(-2)	-0.001062	0.089982	-0.011801	0.9906
RESID(-3)	0.104931	0.089976	1.166214	0.2453
RESID(-4)	0.029028	0.080553	0.360359	0.7191

R-squared	0.360072	Mean dependent var	-4.56E-16
Adjusted R-squared	0.335616	S.D. dependent var	0.578323
S.E. of regression	0.471389	Akaike info criterion	1.375480
Sum squared resid	34.88664	Schwarz criterion	1.507792
Log likelihood	-105.7894	F-statistic	14.72335
Durbin-Watson stat	1.945094	Prob(F-statistic)	0.000000

AUTO-23

OLS with NEWKEY-WEST

option/heteroskedasticity/Newey-West

Dependent Variable: DEVFEDTBILL

Method: Least Squares

Sample(adjusted): 1955:2 1996:1

Included observations: 164 after adjusting endpoints

Newey-West HAC Standard Errors & Covariance (lag truncation=4)

Variable	Coefficient	Std. Error	t-Statistic	Prob.
C	-0.166704	0.104925	-1.588788	0.1141
INF(-1)	0.161085	0.026485	6.082115	0.0000
GGDP(-4)	0.004583	0.009885	0.463627	0.6435
R-squared	0.443511	Mean dependent var	0.553354	
Adjusted R-squared	0.436598	S.D. dependent var	0.775250	
S.E. of regression	0.581904	Akaike info criterion	1.773099	
Sum squared resid	54.51650	Schwarz criterion	1.829804	
Log likelihood	-142.3942	F-statistic	64.15699	
Durbin-Watson stat	0.836136	Prob(F-statistic)	0.000000	

[6] AR(1)

(1) Assumptions:

- $\varepsilon_t = \rho\varepsilon_{t-1} + v_t$, v_t iid $N(0, \sigma_v^2)$, $|\rho| < 1$.
- $\{\varepsilon_t\}$ starts at the infinite past ($-\infty$)

(2) Derivation of Ω and V .

- $$\begin{aligned}\varepsilon_t &= \rho(\rho\varepsilon_{t-2} + v_{t-1}) + v_t = \rho^2\varepsilon_{t-2} + v_t + \rho v_{t-1} \\ &= \rho^2(\rho\varepsilon_{t-3} + v_{t-2}) + v_t + \rho v_{t-1} = \rho^3\varepsilon_{t-3} + v_t + \rho v_{t-1} + \rho^2 v_{t-2} \\ &= \rho^\infty \varepsilon_{t-\infty} + \sum_{j=0}^{\infty} \rho^j v_{t-j} = \sum_{j=0}^{\infty} \rho^j v_{t-j}.\end{aligned}$$
- $$\gamma_0 = \text{var}(\varepsilon_t) = \text{var}\left(\sum_{j=0}^{\infty} \rho^j v_{t-j}\right) = \sum_{j=0}^{\infty} \rho^{2j} \text{var}(v_{t-j}) = \frac{\sigma_v^2}{1 - \rho^2}.$$
- $$\gamma_1 = E(\varepsilon_t \varepsilon_{t-1}) = E[(\rho\varepsilon_{t-1} + v_t)\varepsilon_{t-1}] = \rho E(\varepsilon_{t-1}^2) = \rho \text{var}(\varepsilon_{t-1}) = \frac{\rho \sigma_v^2}{1 - \rho^2}.$$
- $$\gamma_2 = E(\varepsilon_t \varepsilon_{t-2}) = E[(\rho^2\varepsilon_{t-2} + \rho v_{t-1} + v_t)\varepsilon_{t-2}] = \rho^2 E(\varepsilon_{t-2}^2) = \frac{\rho^2 \sigma_v^2}{1 - \rho^2}.$$
- $$\vdots$$
- In general, $\gamma_j = \rho^j \text{var}(\varepsilon_t)$: $\rho_j = \frac{\gamma_j}{\gamma_0} = \rho^j.$

- $\text{Cov}(\varepsilon) = \sigma^2 \Omega = \sigma_v^2 \frac{1}{1-\rho^2} \begin{pmatrix} 1 & \rho & \rho^2 & \rho^3 & \dots & \rho^{T-1} \\ \rho & 1 & \rho & \rho^2 & \dots & \rho^{T-2} \\ \rho^2 & \rho & 1 & \rho & \dots & \rho^{T-3} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \rho^{T-1} & \rho^{T-2} & \rho^{T-3} & \rho^{T-4} & \dots & 1 \end{pmatrix}.$

- Set $\Omega^* = \frac{1}{1-\rho^2} \begin{pmatrix} 1 & \rho & \rho^2 & \rho^3 & \dots & \rho^{T-1} \\ \rho & 1 & \rho & \rho^2 & \dots & \rho^{T-2} \\ \rho^2 & \rho & 1 & \rho & \dots & \rho^{T-3} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \rho^{T-1} & \rho^{T-2} & \rho^{T-3} & \rho^{T-4} & \dots & 1 \end{pmatrix}.$

- $(\Omega^*)^{-1} = \begin{pmatrix} 1 & -\rho & 0 & 0 & \dots & 0 & 0 \\ -\rho & 1+\rho^2 & -\rho & 0 & \dots & 0 & 0 \\ 0 & -\rho & 1+\rho^2 & -\rho & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 1+\rho^2 & -\rho \\ 0 & 0 & 0 & 0 & \dots & -\rho & 1 \end{pmatrix}.$

- $V = \begin{pmatrix} \sqrt{1-\rho^2} & 0 & 0 & 0 & \dots & 0 & 0 \\ -\rho & 1 & 0 & 0 & \dots & 0 & 0 \\ 0 & -\rho & 1 & 0 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 1 & 0 \\ 0 & 0 & 0 & 0 & \dots & -\rho & 1 \end{pmatrix} \rightarrow V'V = (\Omega^*)^{-1}.$

(3) GLS when ρ is known.

1) Prais-Winston GLS:

$$\mathbf{Vy} = \begin{pmatrix} \sqrt{1-\rho^2} y_1 \\ y_2 - \rho y_1 \\ y_3 - \rho y_2 \\ \vdots \\ y_T - \rho y_{T-1} \end{pmatrix}; \mathbf{VX} = \begin{pmatrix} \sqrt{1-\rho^2} x_{11} & \dots \\ x_{21} - \rho x_{11} & \dots \\ x_{31} - \rho x_{21} & \dots \\ \vdots \\ x_{T1} - \rho x_{T-1,1} & \dots \end{pmatrix}.$$

→ OLS on $\mathbf{Vy} = \mathbf{VX}\beta + \mathbf{V}\varepsilon$.

2) Cochrane-Orcutt GLS

$$\mathbf{y}^* = \begin{pmatrix} y_2 - \rho y_1 \\ y_3 - \rho y_2 \\ \vdots \\ y_T - \rho y_{T-1} \end{pmatrix}; \mathbf{X}^* = \begin{pmatrix} x_{21} - \rho x_{11} & \dots \\ x_{31} - \rho x_{21} & \dots \\ \vdots \\ x_{T1} - \rho x_{T-1,1} & \dots \end{pmatrix}.$$

- Asymptotically, P-W GLS = C-O GLS.
- When T is small, CO GLS is not desirable.

(4) FGLS when ρ is unknown

1) Consistent estimator of ρ

- Cochrane-Orcutt: $\hat{\rho} = \frac{\sum_{t=2}^T e_t e_{t-1}}{\sum_{t=1}^T e_t^2}$.
- Theil: $\hat{\rho} = \frac{(\sum_{t=2}^T e_t e_{t-1}) / (T - 1)}{(\sum_{t=1}^T e_t^2) / (T - k)}$ or $\hat{\rho} = 1 - \frac{DW}{2}$.

2) Two-Step FGLS of β

- Do GLS with $\hat{\rho}$.
- Asymptotically identical to MLE of β if regressors are strictly exogenous.
- Two-Step FGLS and GLS (or MLE) can have different distributions if regressors are only weakly exogenous.

3) Iterative FGLS of β .

STEP 1: Get Two-Step FGLS.

STEP 2: Using T-S FGLS, compute residuals.

STEP 3: Using these residuals, estimate ρ again.

STEP 4: Using this estimate ρ , compute FGLS.

STEP 5: Keep doing this until the estimates of β do not change.

Comments:

- Asymptotically identical to MLE of β and two-step GLS if regressors are strictly exogenous.
- Iterative FGLS and GLS (or MLE) can have different distributions if regressors are only weakly exogenous.

(5) Nonlinear Least Square Approach (Estimate β and ρ jointly)

- Durbin Equation: $y_t = \rho y_{t-1} + x_{t\bullet}'\beta + x_{t-1,\bullet}'(-\rho\beta) + v_t$.

$$(y_t = x_{t\bullet}'\beta + \varepsilon_t) - (\rho y_{t-1} = x_{t-1,\bullet}'(\rho\beta) + \rho\varepsilon_{t-1})$$

→ $y_t = \rho y_{t-1} + x_{t\bullet}'\beta + x_{t-1,\bullet}'(-\rho\beta) + v_t$. [Durbin Equation]

→ Regress y_t on y_{t-1} , $x_{t\bullet}$ and $x_{t-1,\bullet}$.

→ The estimated coefficient on y_{t-1} is a consistent estimate of ρ .

- Estimate this equation by NLLS
- Both estimates of β and ρ are asymptotically identical to MLE if the v_t are normal.
- Okay with weakly exogenous $x_{t\bullet}$.

(6) MLE (Estimate β , ρ and σ_v^2 jointly): See Greene.

- $y \sim N(X\beta, \sigma^2\Omega)$:

$$\rightarrow f(y) = \frac{1}{(2\pi)^{T/2} |\sigma^2\Omega|^{T/2}} \exp\left(-\frac{1}{2\sigma^2} (y - X\beta)' \Omega^{-1} (y - X\beta)\right),$$

where $\sigma^2 = \frac{\sigma_v^2}{1 - \rho^2}$.

- $$l_T(\theta) = \ln f(y) = - (T/2)\ln(2\pi) - (T/2)\ln(\sigma_v^2) + (1/2)\ln(1-\rho^2)$$

$$- [1/(2\sigma_v^2)](Vy-VX\beta)'(Vy-VX\beta)$$

$$= - (T/2)\ln(2\pi) - (T/2)\ln(\sigma_v^2) + (1/2)\ln(1-\rho^2)$$

$$- [(1-\rho^2)/(2\sigma_v^2)](y_1-x_1\cdot'\beta)^2$$

$$- [1/(2\sigma_v^2)]\sum_{t=2}^T (y_t - \rho y_{t-1} - x_{t\cdot}'\beta + x_{t-1\cdot}'(\rho\beta))^2,$$

where $\theta = (\beta', \rho, \sigma_v^2)'$.

- If T is large: $(1/2)\ln(1-\rho^2) - [(1-\rho^2)/(2\sigma_v^2)](y_1-x_1\cdot'\beta)^2$ is negligible.

- Full MLE \approx partial MLE (called MLE conditional on y_1) on

$$- (T/2)\ln(2\pi) - (T/2)\ln(\sigma_v^2)$$

$$- [1/(2\sigma_v^2)] \sum_{t=2}^T (y_t - \rho y_{t-1} - x_{t\cdot}'\beta + x_{t-1\cdot}'(\rho\beta))^2.$$

→ Conditional MLE = NLLS.

→ In EViews, y c x1 x2 x3 ar(1).

[EMPIRICAL EXAMPLE]

Data: ustc96.wf1

- FEDFRQ = Fed Fund Rate (%)
- GDP
- INF = annualized quarterly inflation rate (%)
- M1Q = M1
- M2Q = M2
- TBILLQ = treasury bill rate (%)
- GGDP = $400 \cdot \ln(\text{GDP}/\text{GDP}(-1))$:
Annualized growth rate of GDP (%)
- GM1 = $400 \cdot \text{LOG}(\text{M1Q}/\text{M1Q}(-1))$:
Annualized growth rate of M1 (%)

Model to estimate:

$$(\text{fedfrq}-\text{tbillq}) = \beta_1 + \beta_2 \text{ggdp}_{t-4} + \beta_3 \text{inf}_{t-1} + \varepsilon_t.$$

From OLS (p. AUTO_24), $\hat{\rho} = 1 - \text{DW}/2 = 1 - 0.836/2 = 0.582$.

Cochrane-Orcutt GLS:

$$\text{codevfedtbill} = \text{devfedtbill} - 0.582 * \text{devfedtbill}(-1);$$

$$\text{coinf} = \text{inf}(-1) - 0.582 * \text{inf}(-2);$$

$$\text{coggdpr} = \text{ggdpr}(-4) - 0.582 * \text{ggdpr}(-5).$$

Dependent Variable: CODEVFEDTBILL

Method: Least Squares

Sample(adjusted): 1955:3 1996:1

Included observations: 163 after adjusting endpoints

Variable	Coefficient	Std. Error	t-Statistic	Prob.
C	0.120528	0.046543	2.589568	0.0105
COINF	0.062266	0.019788	3.146685	0.0020
COGGDP	-0.013761	0.008305	-1.657006	0.0995
R-squared	0.071071	Mean dependent var	0.172108	
Adjusted R-squared	0.059460	S.D. dependent var	0.452537	
S.E. of regression	0.438877	Akaike info criterion	1.209040	
Sum squared resid	30.81813	Schwarz criterion	1.265980	
Log likelihood	-95.53674	F-statistic	6.120716	
Durbin-Watson stat	1.889811	Prob(F-statistic)	0.002745	

Residual Tests:

Breusch-Godfrey Serial Correlation LM Test:

F-statistic	1.455219	Probability	0.218506
Obs*R-squared	5.863290	Probability	0.209593

Test Equation:

Dependent Variable: RESID

Method: Least Squares

Presample missing value lagged residuals set to zero.

Variable	Coefficient	Std. Error	t-Statistic	Prob.
C	0.015854	0.048248	0.328589	0.7429
COINF	-0.012542	0.021580	-0.581194	0.5619
COGGDP	0.000382	0.008388	0.045568	0.9637
RESID(-1)	0.060842	0.085325	0.713054	0.4769
RESID(-2)	0.067904	0.080385	0.844726	0.3996
RESID(-3)	0.024977	0.079489	0.314223	0.7538
RESID(-4)	0.160788	0.079539	2.021496	0.0449

R-squared	0.035971	Mean dependent var	1.20E-17
Adjusted R-squared	-0.001107	S.D. dependent var	0.436160
Log likelihood	-92.55107	F-statistic	0.970146
Durbin-Watson stat	1.980720	Prob(F-statistic)	0.447394

NLLS Estimation: Joint estimation of ρ and β

Dependent Variable: DEVFEDTBILL

Method: Least Squares

Sample(adjusted): 1955:3 1996:1

Included observations: 163 after adjusting endpoints

Convergence achieved after 10 iterations

Variable	Coefficient	Std. Error	t-Statistic	Prob.
C	0.529433	0.204273	2.591796	0.0104
INF(-1)	0.036529	0.021294	1.715487	0.0882
GGDP(-4)	-0.016524	0.007907	-2.089836	0.0382
AR(1)	0.801587	0.049480	16.20038	0.0000
R-squared	0.690945	Mean dependent var	0.556646	
Adjusted R-squared	0.685114	S.D. dependent var	0.776488	
S.E. of regression	0.435724	Akaike info criterion	1.200618	
Sum squared resid	30.18701	Schwarz criterion	1.276538	
Log likelihood	-93.85038	F-statistic	118.4908	
Durbin-Watson stat	2.037432	Prob(F-statistic)	0.000000	
Inverted AR Roots	.80			

[7] AR(p)

(1) Assumptions:

- $\varepsilon_t = \rho_1 \varepsilon_{t-1} + \rho_2 \varepsilon_{t-2} + \dots + \rho_p \varepsilon_{t-p} + v_t$, v_t iid $N(0, \sigma_v^2)$.

The solutions of $1 - \rho_1 z - \dots - \rho_p z^p = 0$ are all outside of $(-1, 1)$.

→ Guarantees CS and ergodicity.

- $\{\varepsilon_t\}$ starts at the infinite past $(-\infty)$

(2) Estimation

- θ 's can be consistently estimated by regressing e_t on e_{t-1}, \dots, e_{t-p} .

→ The estimated coefficient on e_{t-j} is a consistent estimate of ρ_j .

- Use Cochrane-Ocutt type FGLS:

$$\rightarrow y_t^* = y_t - \hat{\rho}_1 y_{t-1} - \hat{\rho}_2 y_{t-2} - \dots - \hat{\rho}_p y_{t-p};$$

$$x_{t,\bullet}^* = x_{t,\bullet} - \hat{\rho}_1 x_{t-1,\bullet} - \hat{\rho}_2 x_{t-2,\bullet} - \dots - \hat{\rho}_p x_{t-p,\bullet}.$$

- Use NLLS:

$$(y_t = x_{t,\bullet}'\beta + \varepsilon_t) - (\rho_1 y_{t-1} = x_{t-1,\bullet}'(\rho_1\beta) + \rho_1\varepsilon_{t-1})$$

$$- \dots - (\rho_p y_{t-p} = x_{t-p,\bullet}'(\rho_p\beta) + \rho_p\varepsilon_{t-p})$$

$$\rightarrow y_t - \rho_1 y_{t-1} - \dots - \rho_p y_{t-p} = x_{t,\bullet}'\beta + x_{t-1,\bullet}'(-\rho_1\beta) + \dots + x_{t-p,\bullet}'(-\rho_p\beta).$$

$$\rightarrow y_t = \rho_1 y_{t-1} + \dots + \rho_p y_{t-p} + x_{t,\bullet}'\beta + x_{t-1,\bullet}'(-\rho_1\beta) + \dots + x_{t-p,\bullet}'(-\rho_p\beta).$$

→ Do NLLS on this equation = MLE conditional on y_1, \dots, y_p .

≈ Full MLE if T is large.

→ In EViews, y c x1 x2 x3 ar(1) ar(2) ... ar(p).

[8] MOVING AVERAGE: MA(q)

(1) Assumption

1) $\varepsilon_t = v_t + \psi_1 v_{t-1} + \dots + \psi_q v_{t-q}$, v_t iid $N(0, \sigma_v^2)$.

2) The ψ_j are finite: Guarantees CS.

(2) Estimation

1) FGLS is possible for MA(1), but is messy. (See Fomby, et al)

2) Use conditional MLE (See Hamilton, Ch. 5.)

→ This is a kind of NLLS.

→ In EViews, y c x1 x2 x3 ma(1) ma(2) ... ma(q)

[EMPIRICAL EXAMPLE]

Data: ustc96.wf1

- FEDFRQ = Fed Fund Rate (%)
- GDP
- INF = annualized quarterly inflation rate (%)
- M1Q = M1
- M2Q = M2
- TBILLQ = treasury bill rate (%)
- GGDP = $400 \cdot \ln(\text{GDP}/\text{GDP}(-1))$:
Annualized growth rate of GDP (%).
- GM1 = $400 \cdot \text{LOG}(\text{M1Q}/\text{M1Q}(-1))$:
Annualized growth rate of M1 (%)
- DEVFEDTBILL = fedfrq – tbillq.

Model to estimate:

$$(\text{fedfrq}-\text{tbillq}) = \text{ggdp}_t = \beta_1 + \beta_2 \text{ggdp}_{t-4} + \beta_3 \text{inf}_{t-1} + \varepsilon_t.$$

NLLS with the MA(1) error assumption

Dependent Variable: DEVFEDTBILL
Method: Least Squares
Date: 04/16/02 Time: 16:32
Sample(adjusted): 1955:2 1996:1
Included observations: 164 after adjusting endpoints
Convergence achieved after 21 iterations
Backcast: 1955:1

Variable	Coefficient	Std. Error	t-Statistic	Prob.
C	0.003068	0.109018	0.028145	0.9776
INF(-1)	0.135388	0.017354	7.801677	0.0000
GGDP(-4)	-0.003800	0.009799	-0.387766	0.6987
MA(1)	0.500564	0.070720	7.078139	0.0000
R-squared	0.598690	Mean dependent var	0.553354	
Adjusted R-squared	0.591165	S.D. dependent var	0.775250	
S.E. of regression	0.495697	Akaike info criterion	1.458382	
Sum squared resid	39.31442	Schwarz criterion	1.533989	
Log likelihood	-115.5874	F-statistic	79.56466	
Durbin-Watson stat	1.646195	Prob(F-statistic)	0.000000	
Inverted MA Roots	-.50			

view/residual tests/serial correlation LM test

lags to include: 4

Breusch-Godfrey Serial Correlation LM Test:

F-statistic	8.456939	Probability	0.000003
Obs*R-squared	29.22516	Probability	0.000007

Test Equation:

Dependent Variable: RESID

Method: Least Squares

Presample missing value lagged residuals set to zero.

Variable	Coefficient	Std. Error	t-Statistic	Prob.
C	0.080678	0.101892	0.791802	0.4297
INF(-1)	-0.024547	0.016595	-1.479138	0.1411
GGDP(-4)	0.003187	0.009113	0.349778	0.7270
MA(1)	-0.966492	0.937799	-1.030596	0.3043
RESID(-1)	1.092440	0.950547	1.149275	0.2522
RESID(-2)	-0.172172	0.478126	-0.360097	0.7193
RESID(-3)	0.307428	0.264810	1.160938	0.2474
RESID(-4)	-0.002848	0.144443	-0.019715	0.9843
R-squared	0.178202	Mean dependent var		0.000221
Adjusted R-squared	0.141327	S.D. dependent var		0.491114
S.E. of regression	0.455089	Akaike info criterion		1.310902
Sum squared resid	32.30849	Schwarz criterion		1.462115
Log likelihood	-99.49395	F-statistic		4.832531
Durbin-Watson stat	1.946651	Prob(F-statistic)		0.000060

[9] ARMA(p,q)

(1) Assumption

- 1) $\varepsilon_t = \rho_1 \varepsilon_{t-1} + \dots + \rho_p \varepsilon_{t-p} + v_t + \psi_1 v_{t-1} + \dots + \psi_q v_{t-q}$, v_t iid $N(0, \sigma_v^2)$.
- 2) The ψ_j are finite and all solutions of $1 - \rho_1 z - \rho_2 z^2 - \dots - \rho_p z^p = 0$ are all outside of $(-1, 1)$: Guarantees CS and ergodicity.

(2) Estimation

- Use conditional MLE (See Hamilton, Ch. 5.)
 - This is a kind of NLLS.
 - In EViews, `y c x1 x2 x3 ar(1) ... ar(p) ma(1) ... ma(q)`.

Dependent Variable: DEVFEDTBILL
 Method: Least Squares
 Sample(adjusted): 1955:3 1996:1
 Included observations: 163 after adjusting endpoints
 Convergence achieved after 11 iterations
 Backcast: 1955:2

Variable	Coefficient	Std. Error	t-Statistic	Prob.
C	0.523522	0.208742	2.507982	0.0132
INF(-1)	0.037847	0.021901	1.728134	0.0859
GGDP(-4)	-0.016419	0.008010	-2.049704	0.0420
AR(1)	0.810490	0.058291	13.90420	0.0000
MA(1)	-0.029295	0.101800	-0.287767	0.7739
R-squared	0.691116	Mean dependent var	0.556646	
Adjusted R-squared	0.683296	S.D. dependent var	0.776488	
S.E. of regression	0.436980	Akaike info criterion	1.212337	
Sum squared resid	30.17036	Schwarz criterion	1.307237	
Log likelihood	-93.80543	F-statistic	88.37967	
Durbin-Watson stat	2.000338	Prob(F-statistic)	0.000000	
Inverted AR Roots	.81			
Inverted MA Roots	.03			

[10] Forecasting

(1) AR(1) Model:

$$y_t = x_t \cdot \beta + \varepsilon_t; \varepsilon_t = \rho \varepsilon_{t-1} + v_t.$$

$$\begin{aligned} \hat{E}(y_{T+1} | \Omega_T) &= \hat{x}_{T+1, \cdot} \cdot \hat{\beta} + \hat{E}(\varepsilon_{T+1} | \Omega_T) = \hat{x}_{T+1, \cdot} \cdot \hat{\beta} + \widehat{\rho \varepsilon_T} \\ &= \hat{x}_{T+1, \cdot} \cdot \hat{\beta} + \hat{\rho}(y_T - x_T \cdot \hat{\beta}). \end{aligned}$$

$$\begin{aligned} \hat{E}(y_{T+2} | \Omega_T) &= \hat{x}_{T+2, \cdot} \cdot \hat{\beta} + \hat{E}(\varepsilon_{T+2} | \Omega_T) = \hat{x}_{T+2, \cdot} \cdot \hat{\beta} + \widehat{\rho \varepsilon_{T+1}} \\ &= \hat{x}_{T+2, \cdot} \cdot \hat{\beta} + \widehat{\rho^2 \varepsilon_T} = \hat{x}_T \cdot \hat{\beta} + \hat{\rho}^2 (y_T - x_T \cdot \hat{\beta}). \end{aligned}$$

$$\hat{E}(y_{T+n} | \Omega_T) = \hat{x}_{T+n, \cdot} \cdot \hat{\beta} + \hat{\rho}^n (y_T - x_T \cdot \hat{\beta}).$$

(2) MA(1) Model:

$$y_t = x_t \cdot \beta + \varepsilon_t; \varepsilon_t = \psi v_{t-1} + v_t.$$

- Estimating v_T :

Set $\hat{v}_0 = 0$.

$$\hat{v}_1 = \hat{\varepsilon}_1 - \hat{\psi} \hat{v}_0 = (y_1 - x_1 \cdot \hat{\beta}).$$

$$\hat{v}_2 = \hat{\varepsilon}_2 - \hat{\psi} \hat{v}_1 = (y_2 - x_2 \cdot \hat{\beta}) + \hat{\psi} v_0.$$

:

$$\hat{v}_T = (y_T - x_T \cdot \hat{\beta}) - \hat{\psi} \hat{v}_{T-1}.$$

- Forecasting:

$$\begin{aligned}\hat{E}(y_{T+1} | \Omega_T) &= \hat{x}_{T+1,\bullet}' \hat{\beta} + \hat{E}(\varepsilon_{T+1} | \Omega_T) = \hat{x}_{T+1,\bullet}' \hat{\beta} + \overbrace{v_{T+1} + \psi v_T} \\ &= \hat{x}_{T+1,\bullet}' \hat{\beta} + \hat{\psi} \hat{v}_T.\end{aligned}$$

$$\begin{aligned}\hat{E}(y_{T+2} | \Omega_T) &= \hat{x}_{T+2,\bullet}' \hat{\beta} + \hat{E}(\varepsilon_{T+2} | \Omega_T) = \hat{x}_{T+2,\bullet}' \hat{\beta} + \overbrace{v_{T+2} + \psi v_{T+1}} \\ &= \hat{x}_{T+2,\bullet}' \hat{\beta}.\end{aligned}$$

:

$$\hat{E}(y_{T+n} | \Omega_T) = \hat{x}_{T+n,\bullet}' \hat{\beta}.$$