

CSE 591: Theoretical Aspects of CPS

Exact System Relationships
Reference Textbook Ch 4.2 & 4.3

Instructor: Georgios E. Fainekos

School of Computing, Informatics and
Decision System Engineering

Arizona State University

✉ fainekos at asu edu

🌐 <http://www.public.asu.edu/~gfaineko>

Announcements

- Do not forget to take a look at HWO
 - If you feel comfortable that you know all the concepts, skip it
 - Otherwise, try to do it
- Project proposal deadline is approaching (17 Feb)
 - You must submit up to 2 page proposal
 - A small intro to the problem
 - Why it is interesting/challenging
 - Why it is related to CPS
 - What you are going to do and when
 - What you are going to deliver
 - Some project ideas from other courses:
<http://courses.ece.illinois.edu/ece598/sm/2008Fall/schedule.shtml>

In the previous class

- Review of notation and definitions:
 - Alphabet: A non-empty finite set
 - Usually denoted by Σ (or Z in the textbook), eg $Z = \{0,1\}$, $Z = \{a,b,c\}$
 - Symbol: a member of the alphabet
 - Eg. 0 or 1 from $Z = \{0,1\}$
 - (finite or infinite) string: A (finite or infinite) sequence of symbols
 - Empty string: ϵ
 - Eg. If $Z = \{0,1\}$, then
 - Finite strings: 10, 0101, 1010111
 - Infinite strings: 1111..., 101010...
 - Concatenation: If α, β are strings, then the concatenation of α and β is written as $\alpha\beta$.
 - Eg. If $\alpha=11$ and $\beta=00$, then $\alpha\beta=1100$
 - Language: A set of strings built over an alphabet

In the previous class

- Review of notation and definitions:
 - Star operator: $L^* = \{x_1x_2\dots x_k \mid k \geq 0 \text{ and each } x_i \in L\}$
 - Eg. $L = \{a,b,aa,aaa,\dots\}$, $L^* = \{aa,ab,ba,aaa,aab,aba,\dots\}$
 - Omega operator: $L^\omega = \{x_1x_2x_3\dots \mid \text{each } x_i \in L\}$
 - Eg. $L = \{a\}$, $L^\omega = \{aaa\dots\}$
 - If $L \subseteq Z^\omega$, then the set of all finite prefixes is
 - $\text{Fin } L = \{u \in Z^* \mid \exists v \in Z^\omega uv \in L\}$
 - If $L \subseteq Z^*$, then the limit of L is
 - $\text{Lim } L = \{u \in Z^\omega \mid \forall k \geq 0. u(0,k) \in L\}$
 - where
 - $u(m,n) = u_m u_{m+1} \dots u_n$
 - $u(m,\omega) = u_m u_{m+1} \dots$
 - $u(0,0) = \varepsilon$
 - Note: usually in the literature $\text{Lim } L$ represents the set of infinite words that have infinitely many prefixes in the set L

In the previous class

- Behavioral relationships

- Given S, S' :

- how are $B(S)$ and $B(S')$ related?
- how are $\text{Reach}(S)$ and $\text{Reach}(S')$ related?

- Similarity relationships

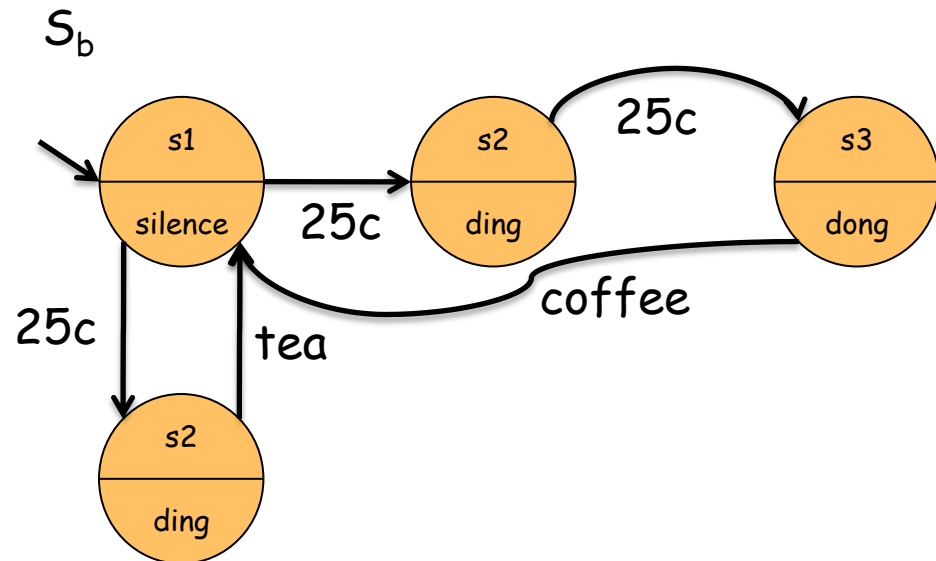
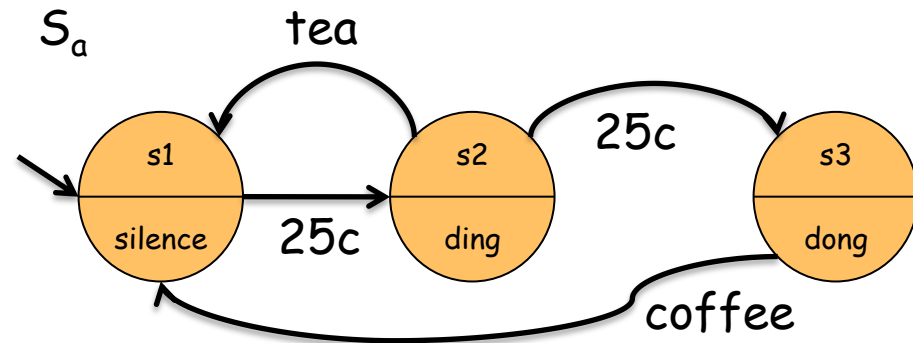
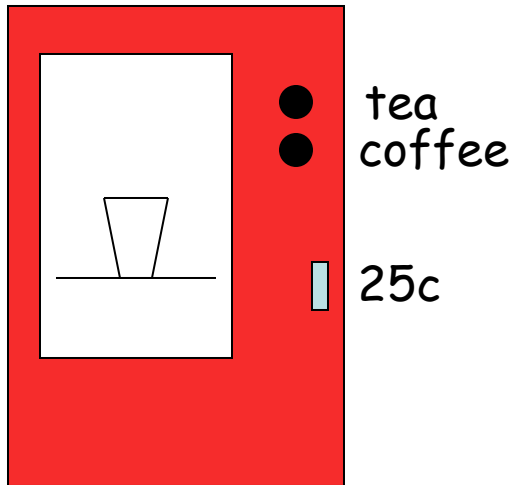
- Let S_a, S_b with $Y_a = Y_b$. A relation $R \subseteq X_a \times X_b$ is a **simulation relation** from S_a to S_b if

- $\forall x_{a0} \in X_{a0} . \exists x_{b0} \in X_{b0} . (x_{a0}, x_{b0}) \in R$
- $\forall (x_a, x_b) \in R . H_a(x_a) = H_b(x_b)$
- $\forall (x_a, x_b) \in R .$

$$x_a \xrightarrow[a]{u_a} x'_a \text{ implies } x_b \xrightarrow[b]{u_b} x'_b \text{ satisfying } (x'_a, x'_b) \in R$$

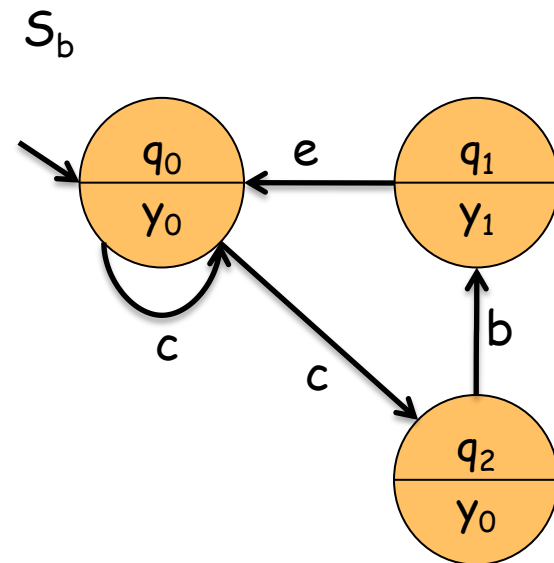
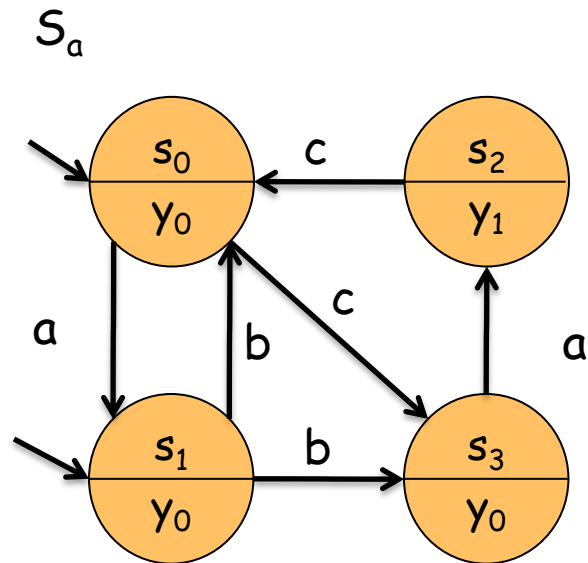
- Given S_a, S_b with $Y_a = Y_b$, we say that S_a is simulated by S_b or that S_b simulates S_a , **written** $S_a \leq_S S_b$, if there exists a simulation relation from S_a to S_b .

Vending Machine Example



Example 4.15

Bisimulation $R = \{(s_0, q_0), (s_1, q_0), (s_2, q_1), (s_3, q_2)\}$



Bisimulation

- Def. Given S_a, S_b with $Y_a=Y_b$ we say that S_a is **bisimilar** to S_b , denoted $S_a \cong_S S_b$, if there exists a relation R satisfying:
 1. R is a simulation relation from S_a to S_b
 2. R^{-1} is a simulation relation from S_b to S_a
- Let S_a, S_b with $Y_a=Y_b$. A relation $R \subseteq X_a \times X_b$ is a **bisimulation relation** between S_a and S_b if
 1. $\forall x_{a0} \in X_{a0} . \exists x_{b0} \in X_{b0} . (x_{a0}, x_{b0}) \in R$
 2. $\forall x_{b0} \in X_{b0} . \exists x_{a0} \in X_{a0} . (x_{a0}, x_{b0}) \in R$
 3. $\forall (x_a, x_b) \in R . H_a(x_a) = H_b(x_b)$
 4. $\forall (x_a, x_b) \in R .$

$$x_a \xrightarrow{a} x'_a \text{ implies } x_b \xrightarrow{b} x'_b \text{ satisfying } (x'_a, x'_b) \in R$$

$$x_b \xrightarrow{b} x'_b \text{ implies } x_a \xrightarrow{a} x'_a \text{ satisfying } (x'_a, x'_b) \in R$$

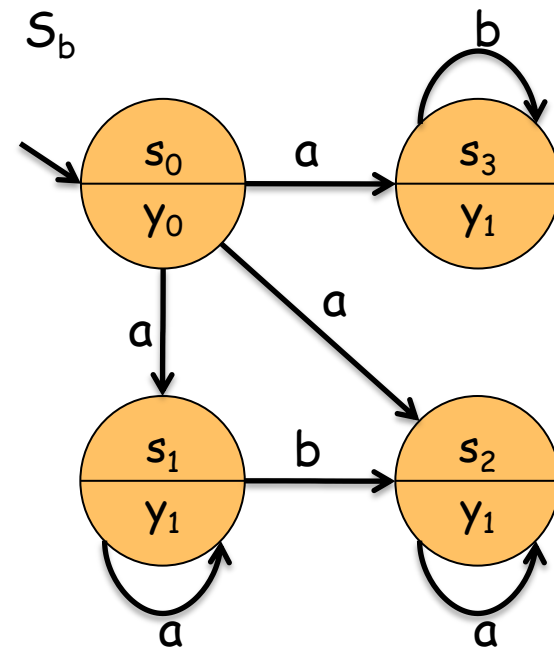
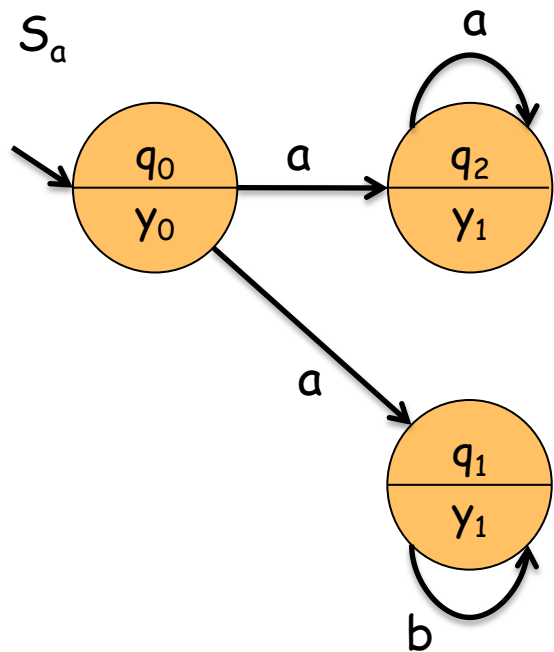
Alternating Similarity Relationships

- Def. Let S_a, S_b with $Y_a = Y_b$. A relation $R \subseteq X_a \times X_b$ is an **alternating simulation relation** from S_a to S_b if
 1. $\forall x_{a0} \in X_{a0} . \exists x_{b0} \in X_{b0} . (x_{a0}, x_{b0}) \in R$
 2. $\forall (x_a, x_b) \in R . H_a(x_a) = H_b(x_b)$
 3. $\forall (x_a, x_b) \in R .$
 $\forall u_a \in U_a(x_a) . \exists u_b \in U_b(x_b) .$
 $\forall x'_b \in \text{Post}_{u_b}(x_b) . \exists x'_a \in \text{Post}_{u_a}(x_a) . (x'_a, x'_b) \in R$
- Given S_a, S_b with $Y_a = Y_b$, we say that S_a is alternatingly simulated by S_b or that S_b alternatingly simulates S_a , **written $S_a \leq_{AS} S_b$** , if there exists an alternating simulation relation from S_a to S_b .

Example 4.21

Simulation $R = \{(q_0, s_0), (q_1, s_1), (q_2, s_2)\}$

Alternating Simulation $R' = \{(q_0, s_0), (q_1, s_1), (q_1, s_2), (q_1, s_3)\}$



Alternating Similarity Relationships

- Def. Let R be an alternating simulation relation between S_a and S_b . The **extended alternating simulation relation** $R^e \subseteq X_a \times X_b \times U_a \times U_b$ associated with R is defined by all $(x_a, x_b, u_a, u_b) \in X_a \times X_b \times U_a \times U_b$ such that
 1. $(x_a, x_b) \in R$
 2. $u_a \in U_a(x_a)$
 3. $u_b \in U_b(x_b)$ and $\forall x_b' \in \text{Post}_{u_b}(x_b) . \exists x_a' \in \text{Post}_{u_a}(x_a) . (x_a', x_b') \in R$
- Def. Given S_a, S_b with $Y_a = Y_b$ we say that S_a is **alternatingly bisimilar** to S_b , denoted $S_a \cong_{AS} S_b$, if there exists a relation R satisfying:
 1. R is an alternating simulation relation from S_a to S_b
 2. R^{-1} is an alternating simulation relation from S_b to S_a